

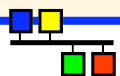


Recent progress at KEK and Plans for SuperKEKB

**Kazuro Furukawa
for Control Groups at KEK**

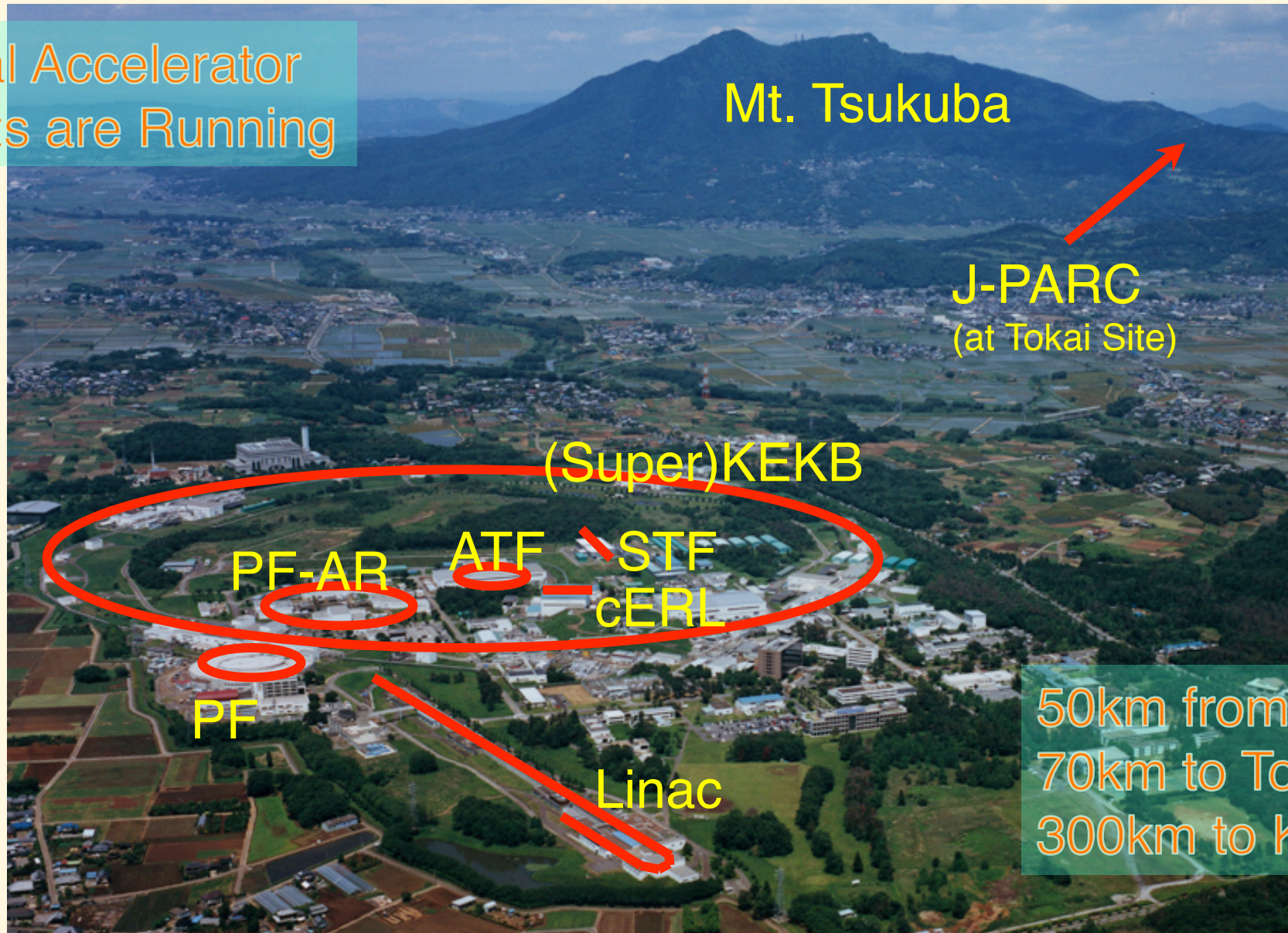
< kazuro.Furukawa @ kek.jp >

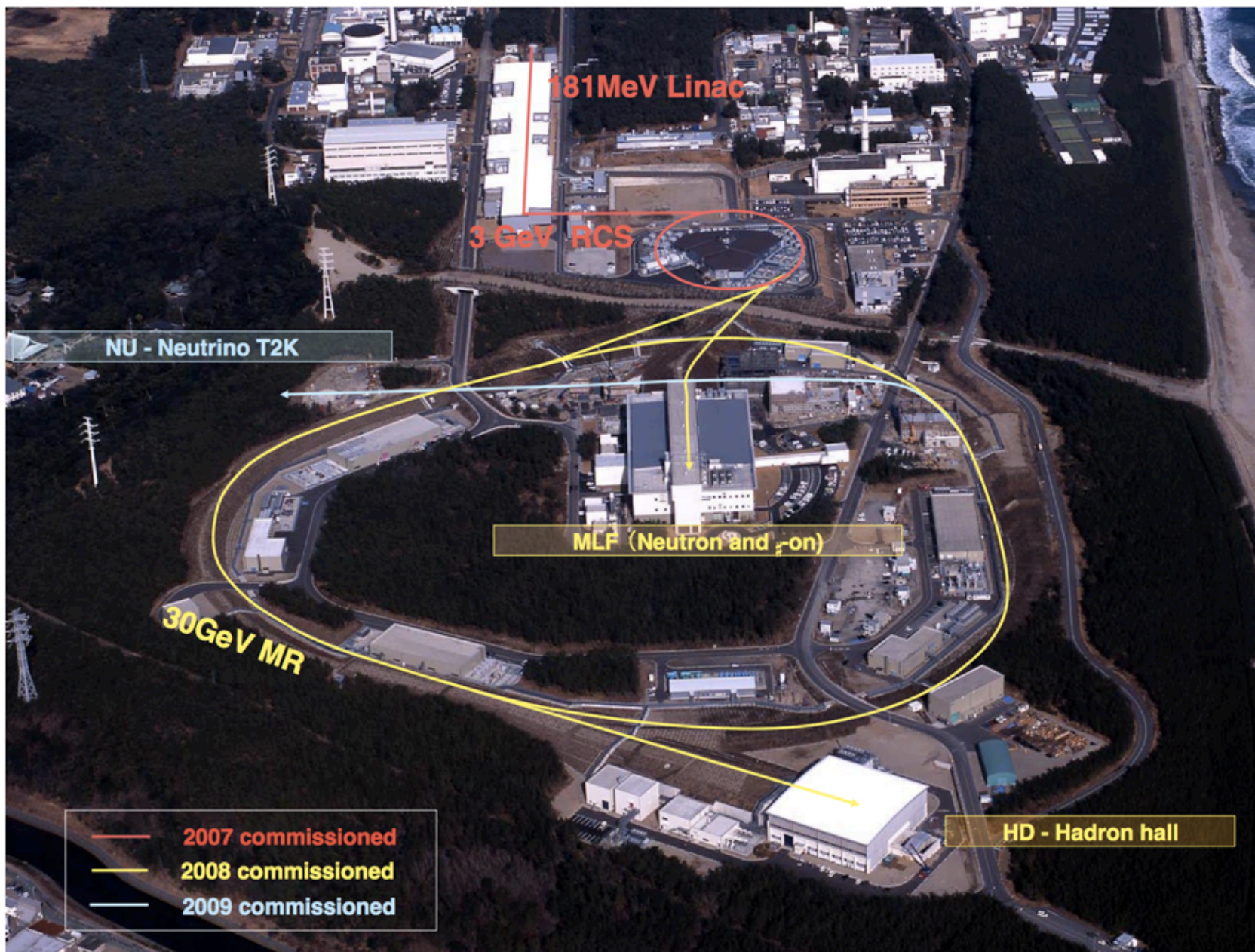
October 11, 2010.



Accelerators at KEK

Several Accelerator
Projects are Running

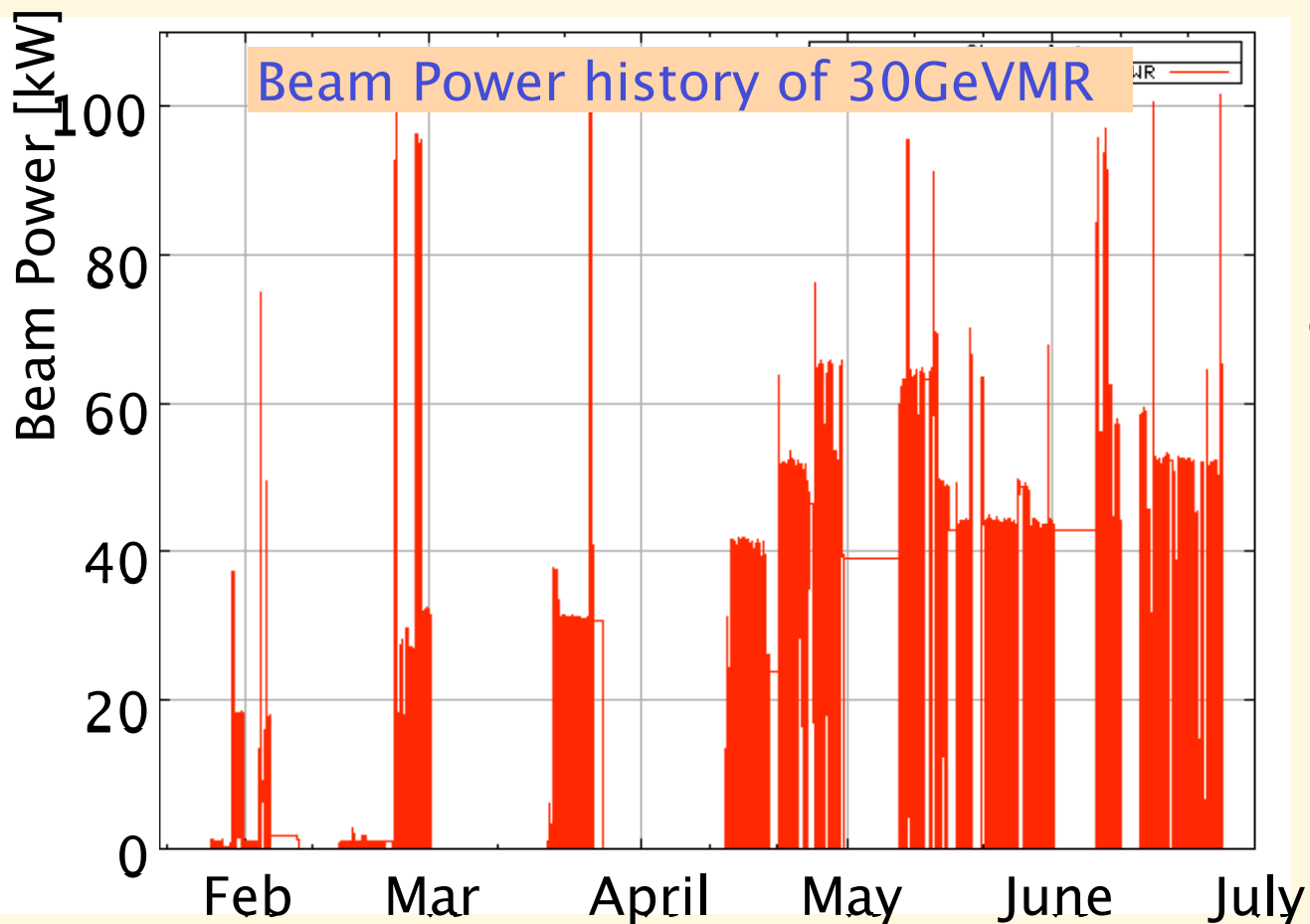


**J-PARC****Japan Proton Accelerator Research Complex**Yamamoto/
Kamikubota

Bird's eye photo
in January of 2008

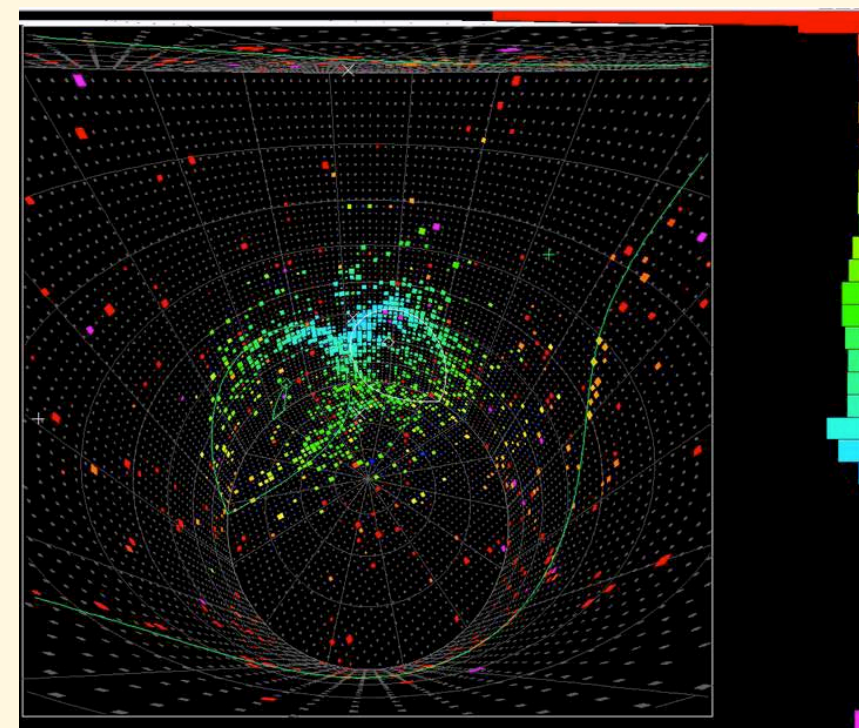
2010 Operational Highlights

Yamamoto/
Kamikubota



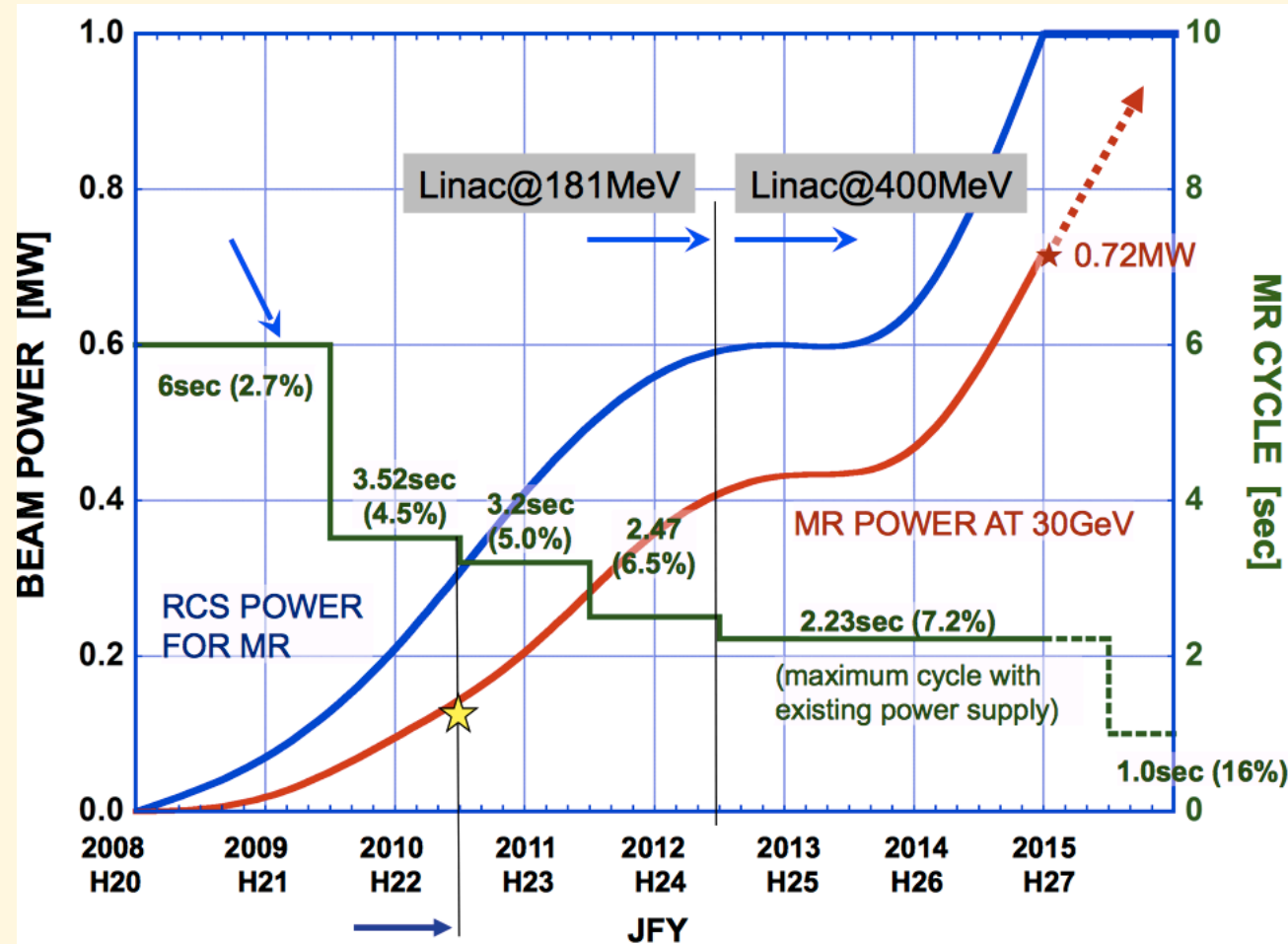
Feb. 24, 2010
First Neutrino Event from J-PARC
observed at Super Kamiokande

Delivers beam at 50KW to Nu. Exp.



Plan for Future

Yamamoto/
Kamikubota

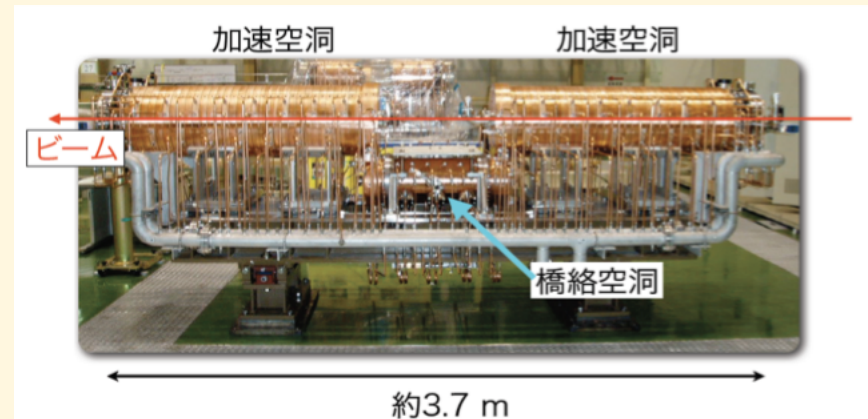


Current status

ACS: Acceleration Structure
for 400MeV Linac Upgrade

Plan for MR Beam Power for
Nu Exp.

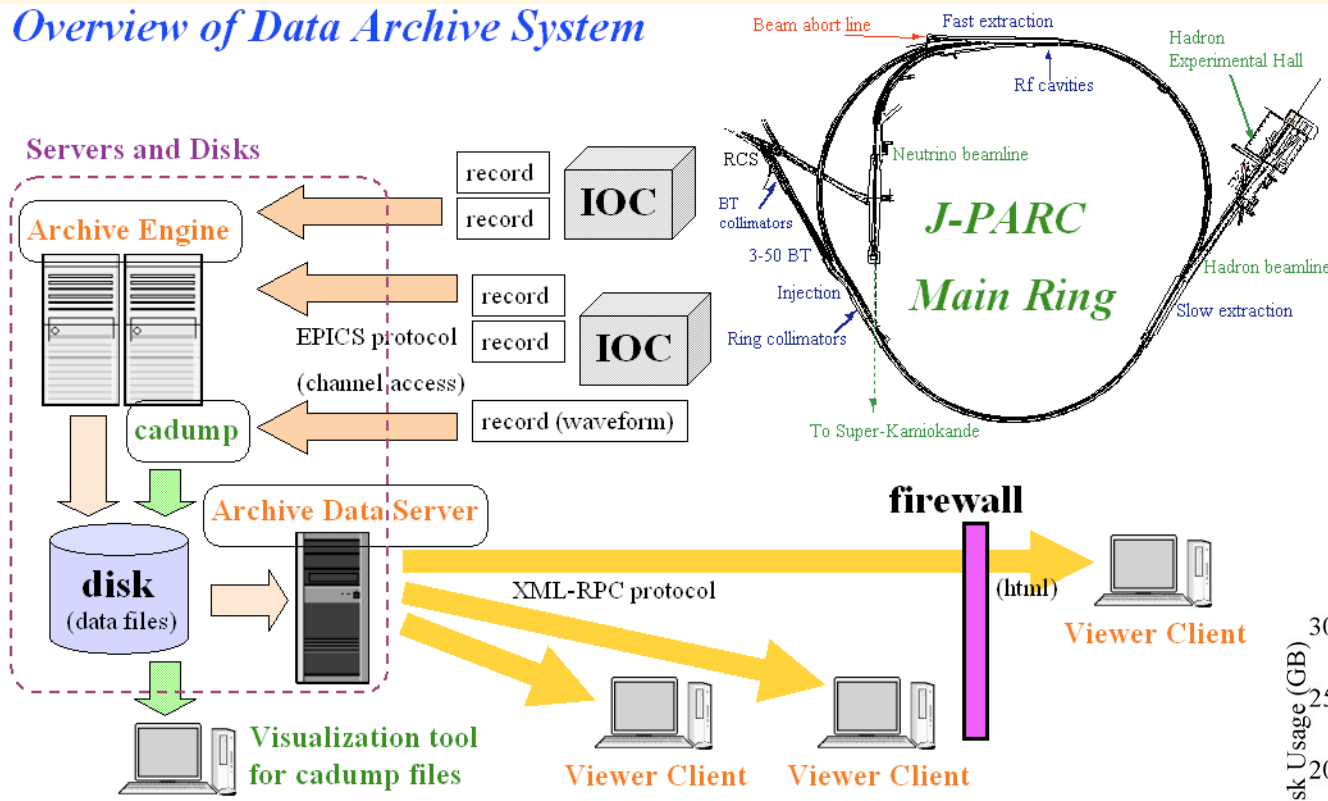
- Linac 400 MeV upgrade for Higher RCS beam power
- Higher MR rep. rate



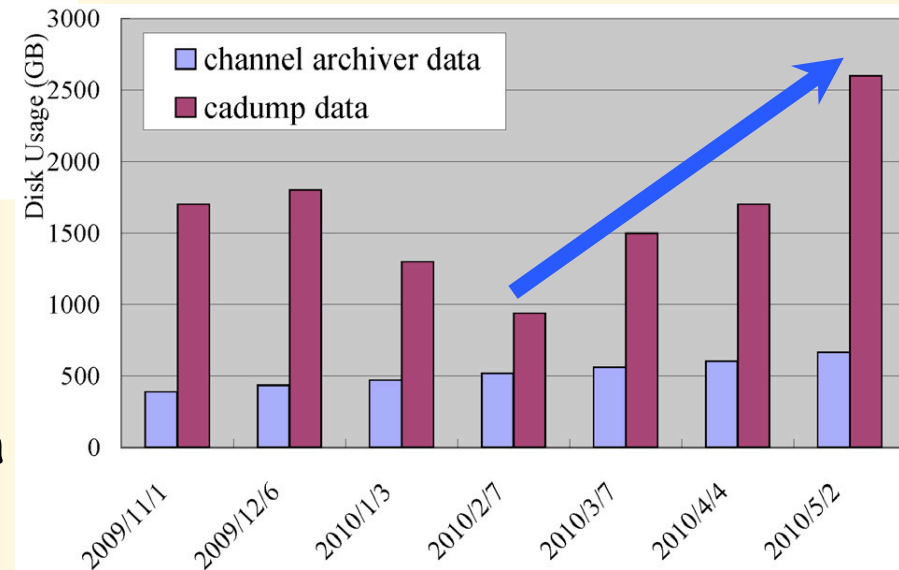
Data Archiving in J-PARC MR control system

Yamamoto/
Kamikubota

Overview of Data Archive System



Overview of J-PARC MR data archive system: “cadump” is a program storing snapshot data, including waveform, into disk system. ROOT and SAD data formats are supported. It also use data compression, after Feb. 2010.



Control Systems at KEK/Tsukuba (1)

◆ SuperKEKB

- ❖ Will inherit resources from KEKB (and TRISTAN)
 - ✧ Partial budget for positron was approved (?)

◆ Linac (electron/positron)

- ❖ Inject beam to (Super)KEKB, PF, PF-AR
 - ✧ Pulse-to-pulse beam modulation

◆ PF (Photon Factory)

- ❖ Moved to EPICS environment
 - ✧ Mainly with Linux-VME

◆ PF-AR (Photon Factory Advanced Ring)

- ❖ Mostly the same environment as KEKB
 - ✧ Many CAMAC installations

Control Systems at KEK/Tsukuba (2)

◆ ATF (Accelerator Test Facility)

- ❖ Vista Controls environment with CAMAC

- ✧ Linux and socket environment with some EPICS devices

◆ STF (Superconducting RF Test Facility)

- ❖ Test facility for ILC

- ✧ EPICS with Linux, ATCA test, PLC, ...

◆ cERL (Compact ERL)

- ❖ Being built for ERL development

- ✧ May share the resources with other accelerators

◆ Sharing resources as much as possible

Accelerator Controls

◆ VME + Unix (~1995)

❖ Standard EPICS configuration

✧ With many third layer field networks



◆ Every controller on network (1993~1997)

❖ Single layer in physical, two layer logical

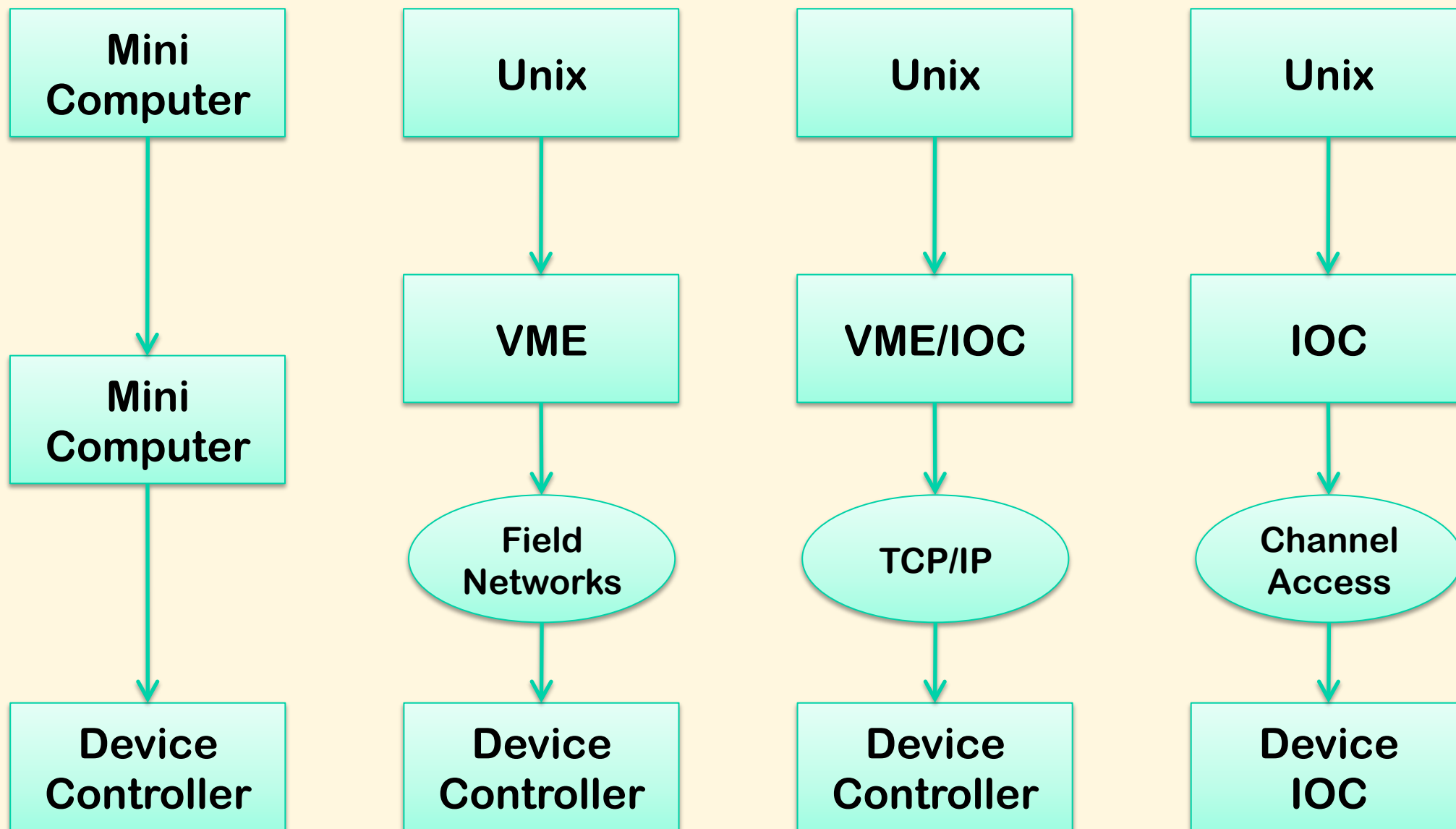


◆ Every controller with EPICS IOC (2005~)

❖ Channel Access everywhere

✧ For longer term maintenance

Transition of Controls



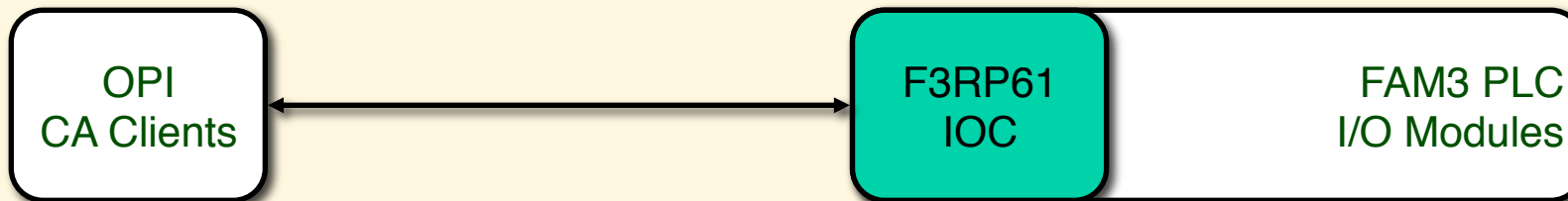
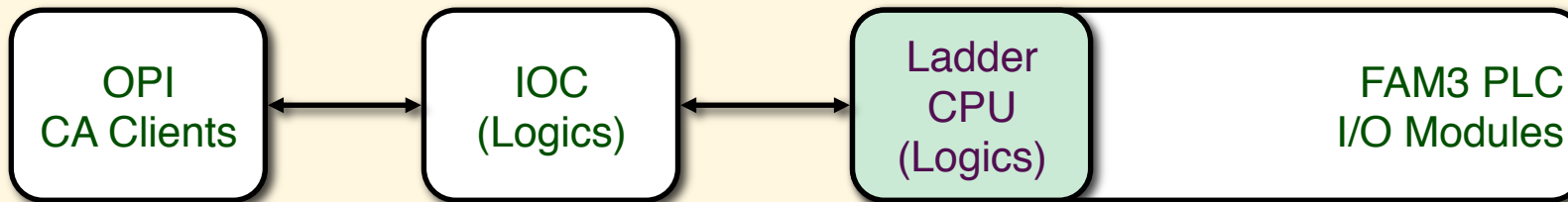
Embedded IOC in Yokogawa's PLC

- ◆ **More than 150 PLCs were employed at Linac**
 - ❖ **All through TCP/IP network since 1993**
 - ✧ **Successful to reduce resource consumption**
- ◆ **Now Linux CPU is available (2008~)**
 - ❖ **533MHz PPC, 128MB RAM, 2xEthernet, USB**
 - ❖ **Utilize realtime feature of Kernel 2.6 (J. Odagiri et al)**
 - ✧ **EPICS PV response time $<150\mu\text{sec}$ (incl. module delay)**
- ◆ **Ladder sequence CPU can coexist**
 - ❖ **Variable sharing possible**

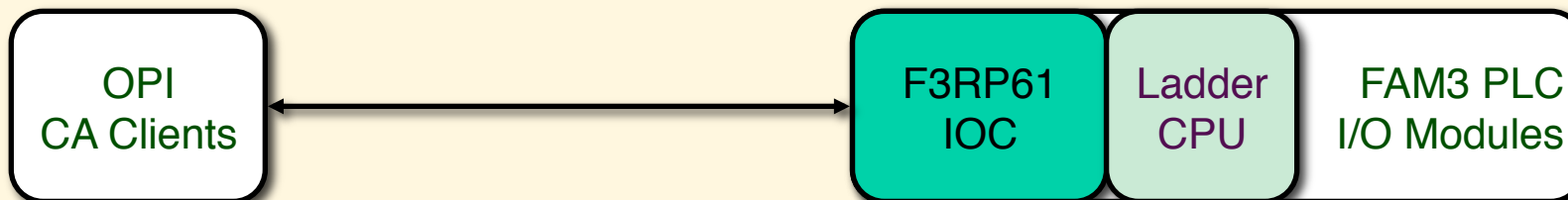
Simpler PLC Usage under EPICS

Conventional PLC usage

with asynchronous access



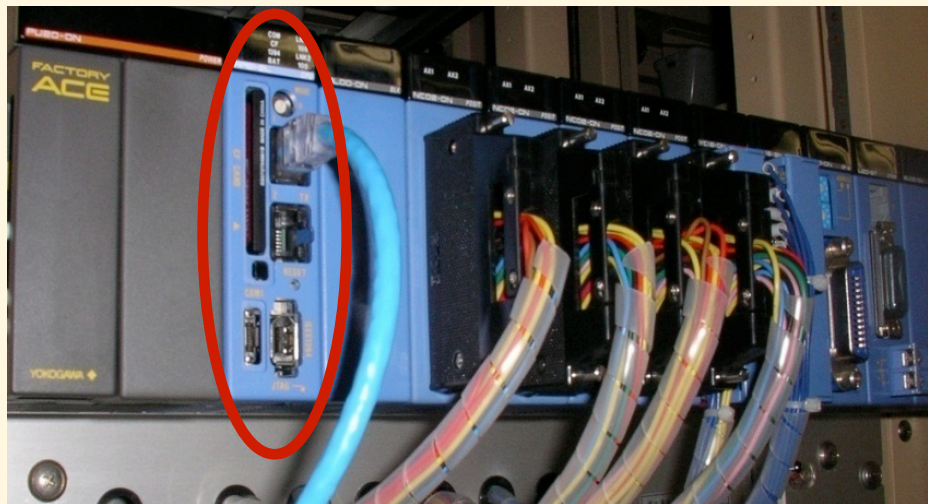
If necessary, we can combine



Logics are confined in PLC, and management is easier

◆ **Many medium-speed controllers implemented**

❖ **KEKB, Linac, J-PARC, PF, cERL, ..., Taiwan/TLS, (Korea/PAL, Beijing/IHEP)**



◆ **Image processing module available**

◆ **Discussing on EVR module with SSRF/ Shanghai**

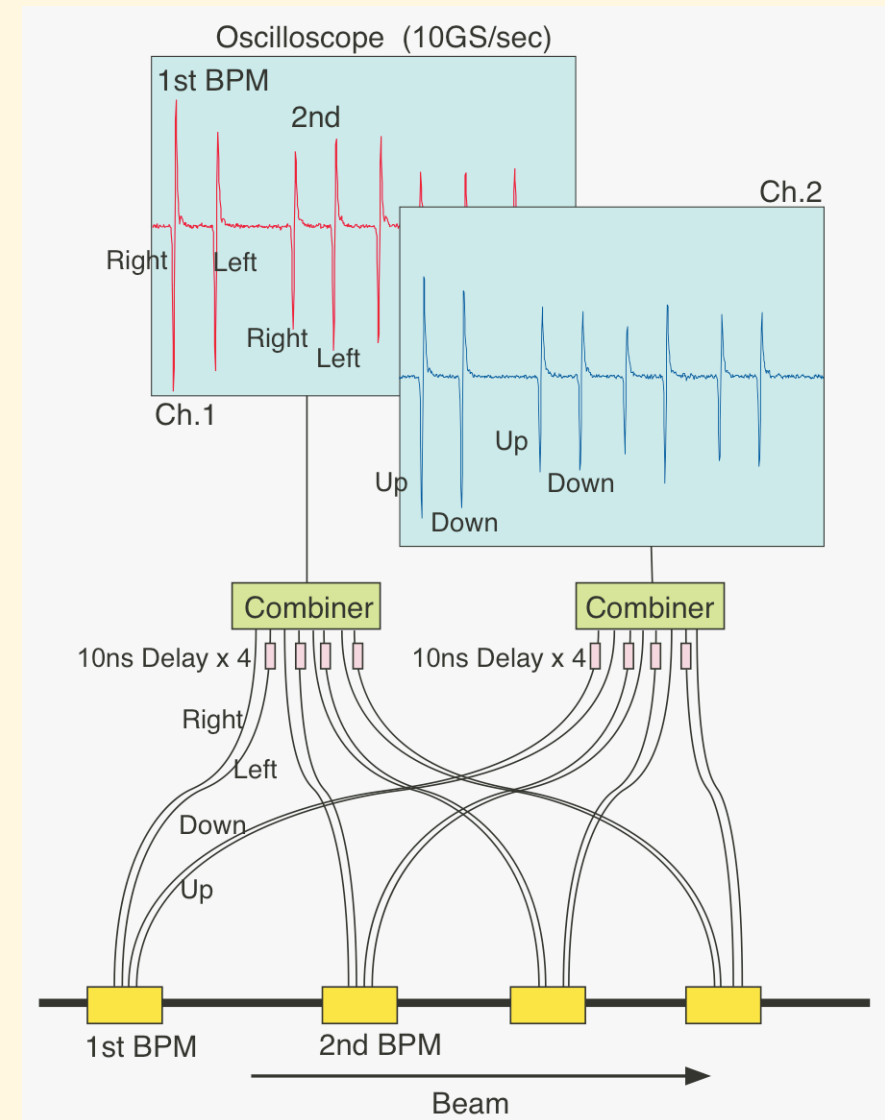
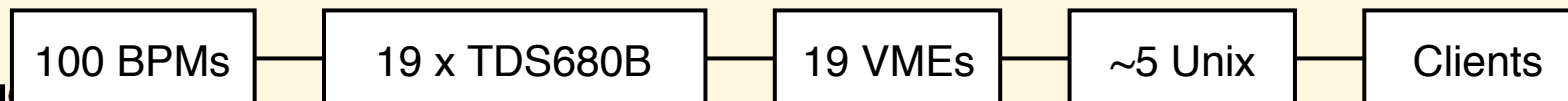
◆ **<<http://www-linac.kek.jp/cont/epics/f3rp61/>>**

BPM at Linac and BT

- ◆ **BPM need only 0.1mm resolution**
 - ❖ **Using ~30 coefficients per BPM**
- ◆ **Many signals are combined into one waveform digitizer**
- ◆ **Again reduction of resources**
- ◆ **Recent Embedded IOC Solution**
 - ❖ **Much helped by Dr. Yong Hu**

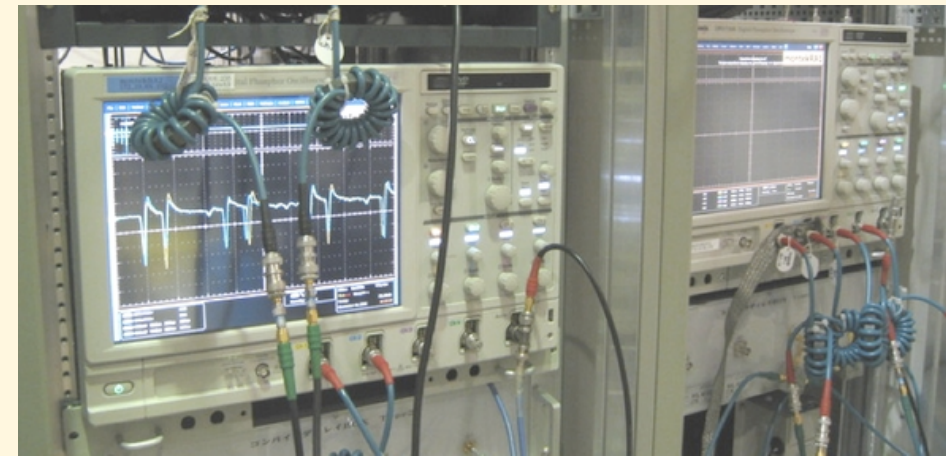
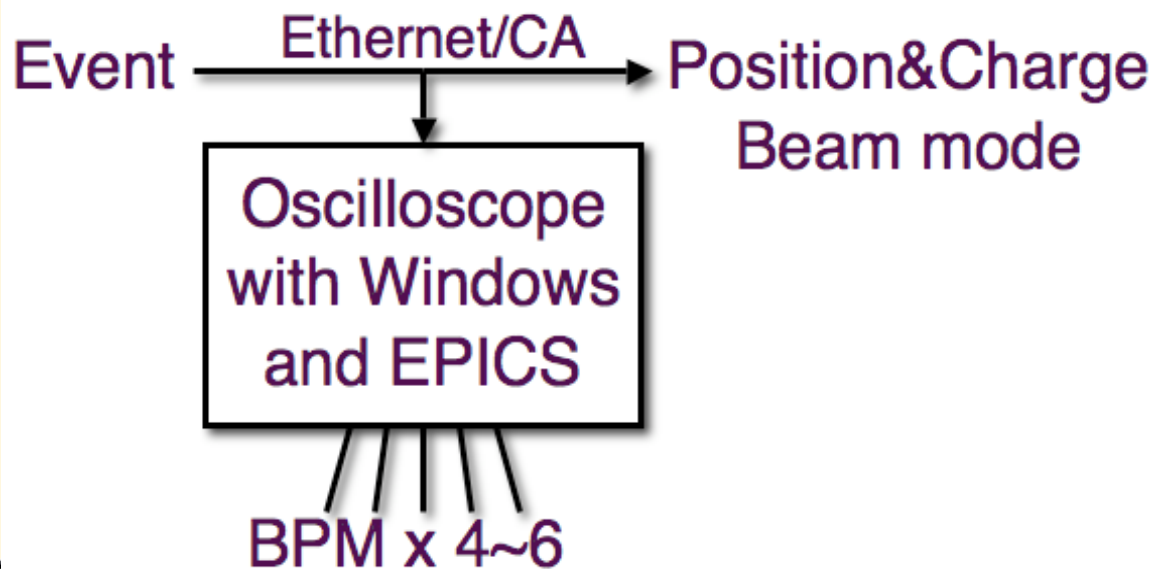


◆ Old configuration



BPM DAQ

- ◆ Tektronix DPO7104 can acquire data at $>50\text{Hz}$.
 - ❖ With embedded EPICS, under pulse-to-pulse beam modulation
- ◆ Beam modes are recognized by events through CA network.
 - ❖ Missed less than once in million times
- ◆ Clients can monitor data of an interested beam mode.
- ◆ 24 oscilloscopes are installed for Linac, and 4 for BT.
- ◆ 200 BPMs are synchronized for Linac and BT.

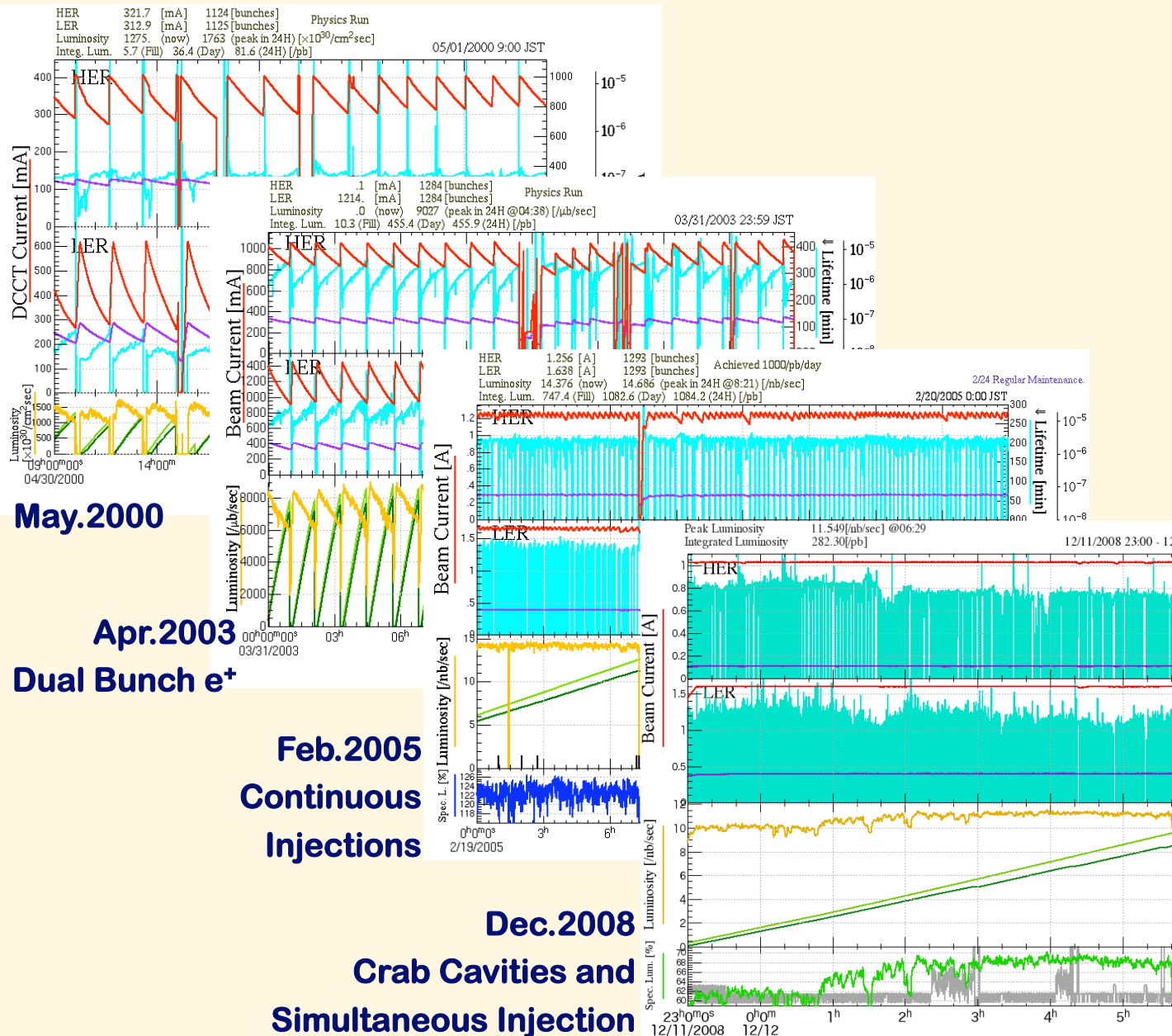


Many other Embedded IOC

- ◆ **Other oscilloscope-based IOCs**
 - ❖ For pulsed device monitors (M. Satoh et al)
- ◆ **TDC/Linac with Linux/ARM (Armadillo)**
 - ❖ Timing consistency surveillance (S. Kusano et al)
- ◆ **MPS manager with Linux/FPGA (Suzaku)**
 - ❖ For J-PARC and cERL, etc (A. Akiyama et al)
- ◆ **Magnet PS with Linux/ARM(or FPGA)**
 - ❖ Two prototypes for SuperKEKB (T. Nakamura et al)



KEKB Operation Improvement (base of SuperKEKB)



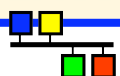
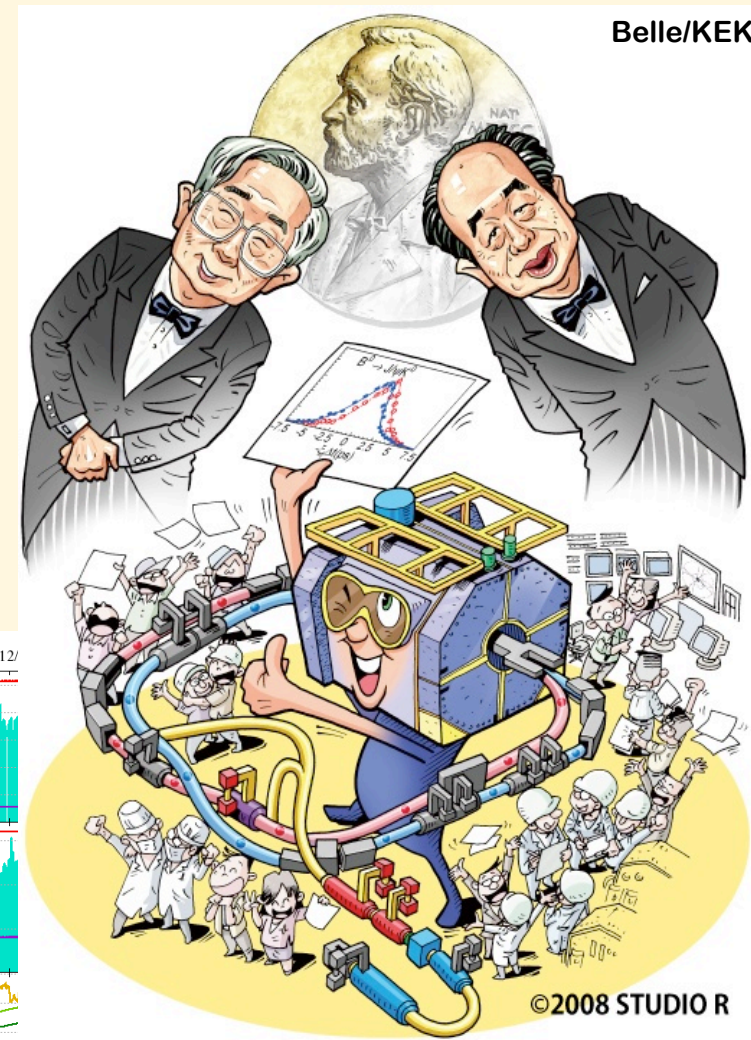
May.2000

Apr.2003

Dual Bunch e^+

Feb.2005
Continuous
Injections

Dec.2008
Crab Cavities and
Simultaneous Injection



SuperKEKB Plan (1)

- ◆ **For nano-beam scheme with 40-times higher luminosity**
 - ❖ Many new facilities should be required
- ◆ **Start based on the existent environment**
 - ❖ With additional concept of CA everywhere
- ◆ **Help device groups to have better global controls**
 - ❖ Replacement of old installations such as CAMAC
 - ❖ Solutions not only VME but also other types of controllers, embedded EPICS if possible
- ◆ **Faster networks for the groups who can build controllers by themselves**
- ◆ **Better connection to operational environments**
 - ❖ Keeping SAD environment, etc
 - ❖ Monitoring at offices

SuperKEKB Plan (2)

◆ Archiving scheme and viewer

- ❖ Maybe existing KEKBlog and channel archivers
 - ✧ New viewer should be developed

◆ Alarm handler

- ❖ CSS or Python (to simulate KEKBalarm)
 - ✧ Should evaluate soon

◆ Operational Log

- ❖ In house, two versions with different origins
 - ✧ Postgres + (Python/Zope and Flash/Flex)

◆ Scripts

- ❖ SADscript/Tk, Python/Tk, (decreasing Tcl/Tk)

◆ Displays

- ❖ Edm and/or CSS

SuperKEKB Plan (3)

◆ Interviews to each device groups

❖ Planning to have monthly meeting and training

✧ To collect user requirements

❖ Partially successful for old hardware replacements

✧ Not yet effective for new functionalities

◆ Whether both sides do not have experiences

◆ ex. Global orbit feedback

◆ We don't need to stabilize the orbit other than the collision point

❖ Monitor group is basically responsible for this

✧ Under development with several candidates

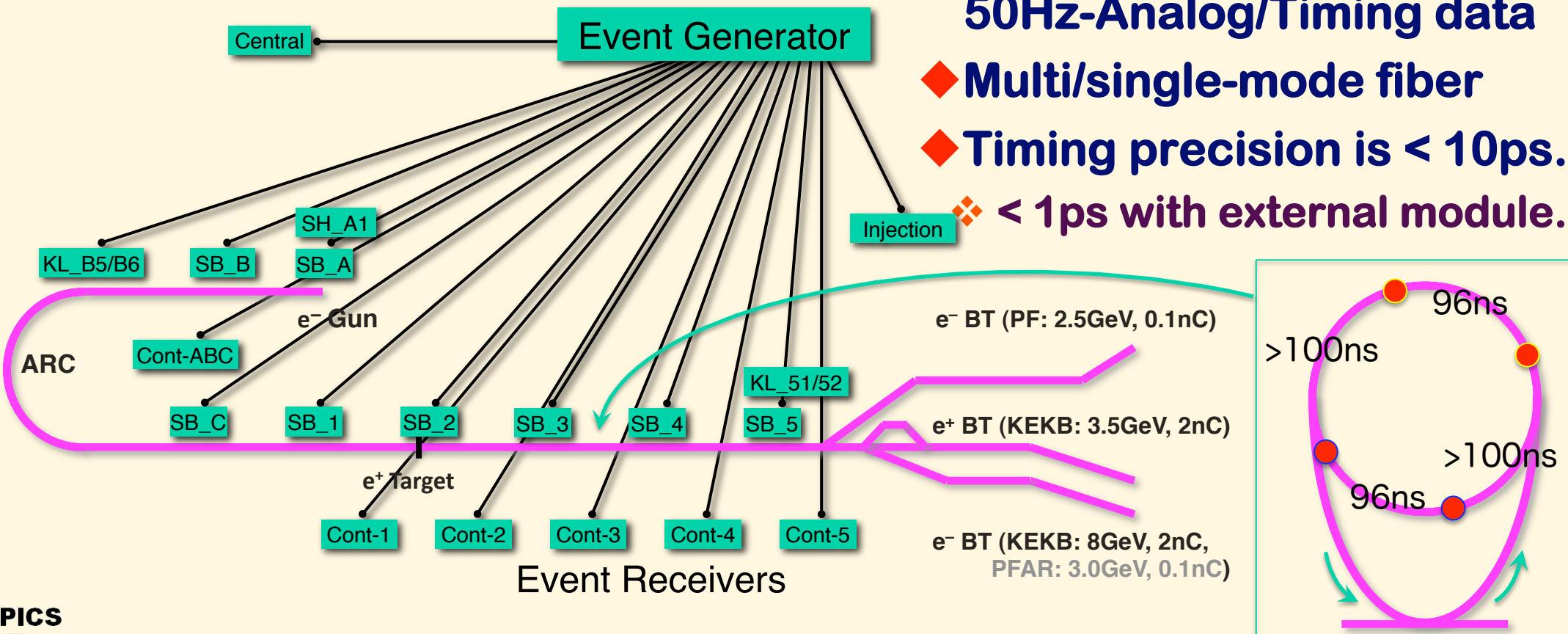
✧ But they still need some data path

Simultaneous Injection

- ◆ SuperKEKB injections with shorter lifetime
- ◆ PF top-up injection for higher quality experiments
- ◆ Enjoyed Hardware and Software Installation One by one
- ◆ Reduced the Beam Switch Time from 10-120 seconds to 20ms
- ◆ Beam currents are kept within 1mA ($\sim 0.05\%$ for KEKB), 0.05mA ($\sim 0.01\%$, PF)
- ◆ Much more complicated with bucket selections at damping ring and main ring
- ◆ Should add PF-AR as well (4rings! with different beams)

Event System for Simultaneous Injection

- ◆ MRF's series-230 Event Generator / Receivers
- ◆ VME64x and VxWorks v5.5.1
- ◆ EPICS R3.14.9 with DevSup v2.4.1
- ◆ 17 event receivers up to now
- ◆ 114.24MHz event rate, 50Hz fiducials
- ◆ More than **hundred** 50Hz-Analog/Timing data
- ◆ Multi/single-mode fiber
- ◆ Timing precision is $< 10\text{ps}$.
◆ $< 1\text{ps}$ with external module.



Parameters

◆ Parameters switched via event system

❖ LLRF phase/timing : 14x4

✧ Overall energy profile, dual-bunch energy equalization, final energy adjustment

❖ HP RF timing : ~60

✧ Energy profile and backup management

❖ Gun voltages, picosecond delay : 4

✧ Beam charge selection, dual bunch selection, bunching

❖ Pulsed magnets/solenoid : 14

✧ Beam transport selection, orbit controls, positron focusing

❖ Injection phase interface : 2

❖ Bucket selection interface : 2

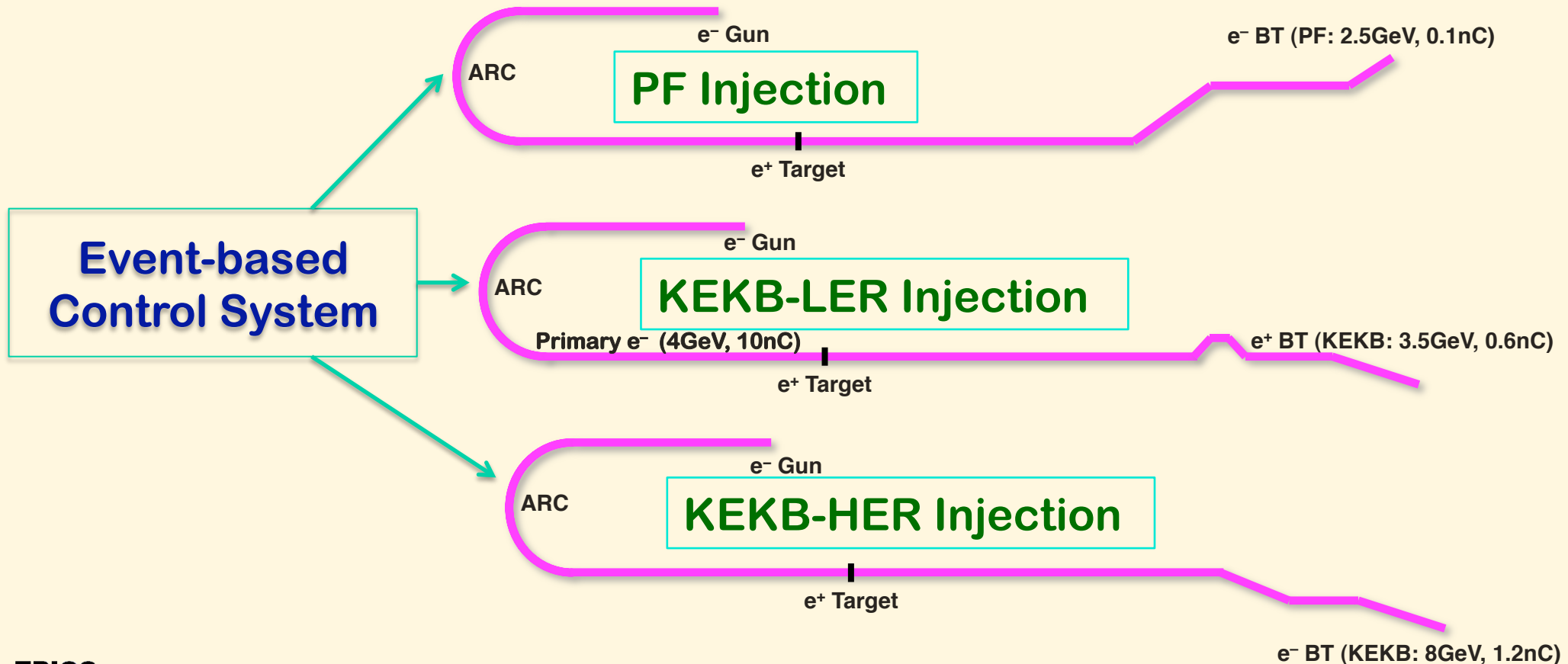
❖ BPM : ~100x3

◆ Sufficient for fast beam mode switching

◆ Integrity monitors soon

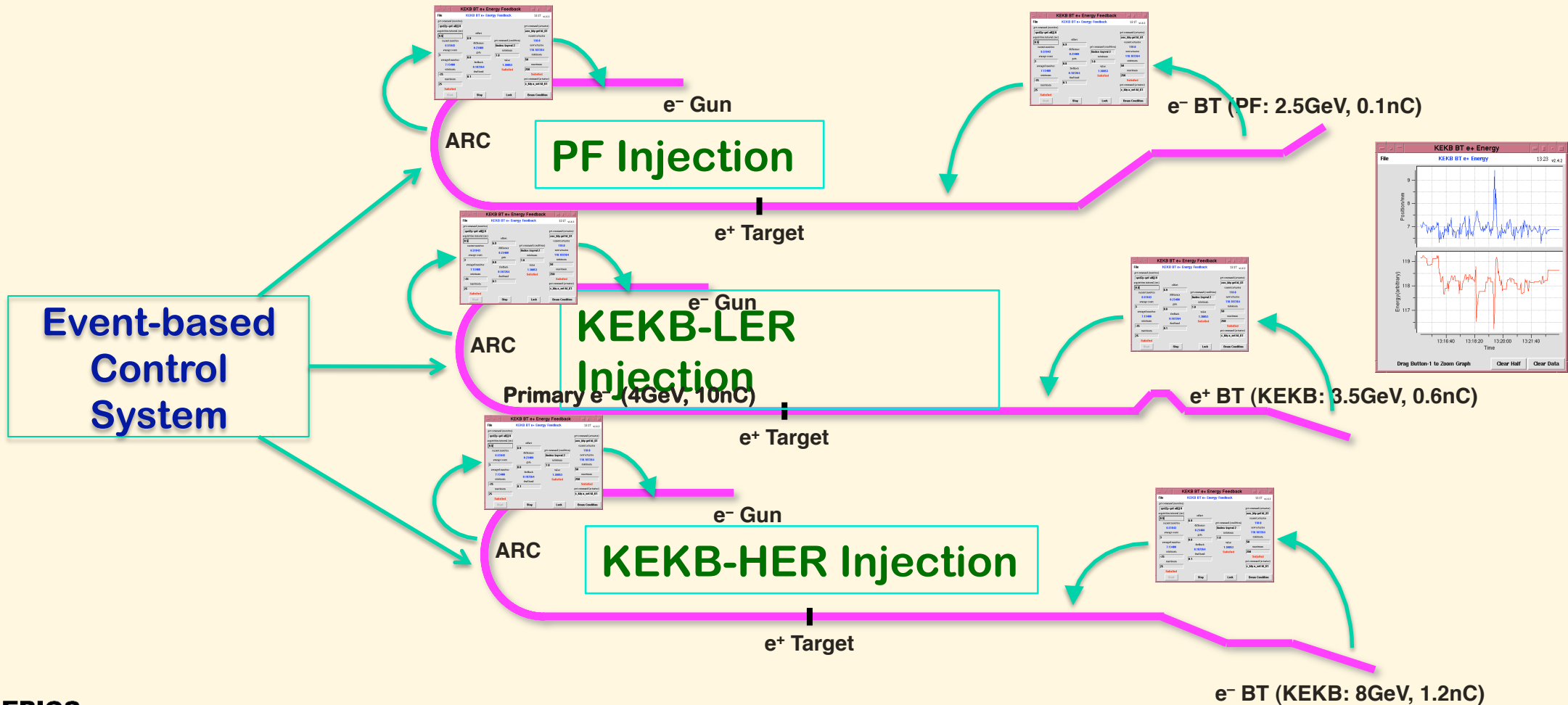
Three Virtual Accelerators

- ◆ Controls and instrumentations are essentially mode-dependent, and mutually independent
- ◆ Selecting a real machine out of three virtual machines
 - ❖ Managing three parameter sets (four under SuperKEKB environment)



Three-fold Independent Closed Loops

- ◆ Feedback loop software act on one of three virtual machines
- ❖ Managing independent parameter sets



Summary

- ◆ **Controls Have Interface to Every System in Accelerators**
 - ❖ **We can Enjoy Accelerator**

- ◆ **There should be Room to Establish Further Controls Utilizing Beam Monitors, RF Monitors, and More**
 - ❖ **With Phronesis, Ability to understand the Universal Truth**



Thank you

