



Recent developments towards SuperKEKB controls

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Accelerators at KEK

Several Accelerator Projects are Running



In this meeting

◆ J-PARC

❖ Norihiko Kamikubota (上窪田)

❖ Shuei Yamada (山田)

◆ PF, PF-AR, cERL

❖ Takashi Obina (帯名)

◆ SuperKEKB, Linac

❖ Masanori Satoh (佐藤)

❖ Kazuro Furukawa (古川)

Control Systems at KEK/Tsukuba (1)

◆ SuperKEKB

- ❖ Will inherit resources from KEKB (and TRISTAN)
 - ✧ Upgrade 2011-2014 was approved

◆ Linac (electron/positron)

- ❖ Inject beam to (Super)KEKB, PF, PF-AR
 - ✧ Pulse-to-pulse beam modulation

◆ PF (Photon Factory)

- ❖ Moved to EPICS environment
 - ✧ Mainly with Linux-VME

◆ PF-AR (Photon Factory Advanced Ring)

- ❖ Mostly the same environment as KEKB
 - ✧ Many CAMAC installations

Control Systems at KEK/Tsukuba (2)

◆ ATF (Accelerator Test Facility)

- ❖ Vista Controls environment with CAMAC

- ✧ Linux and socket environment with some EPICS devices

◆ STF (Superconducting RF Test Facility)

- ❖ Test facility for ILC

- ✧ EPICS with Linux, ATCA test, PLC, ...

◆ cERL (Compact ERL)

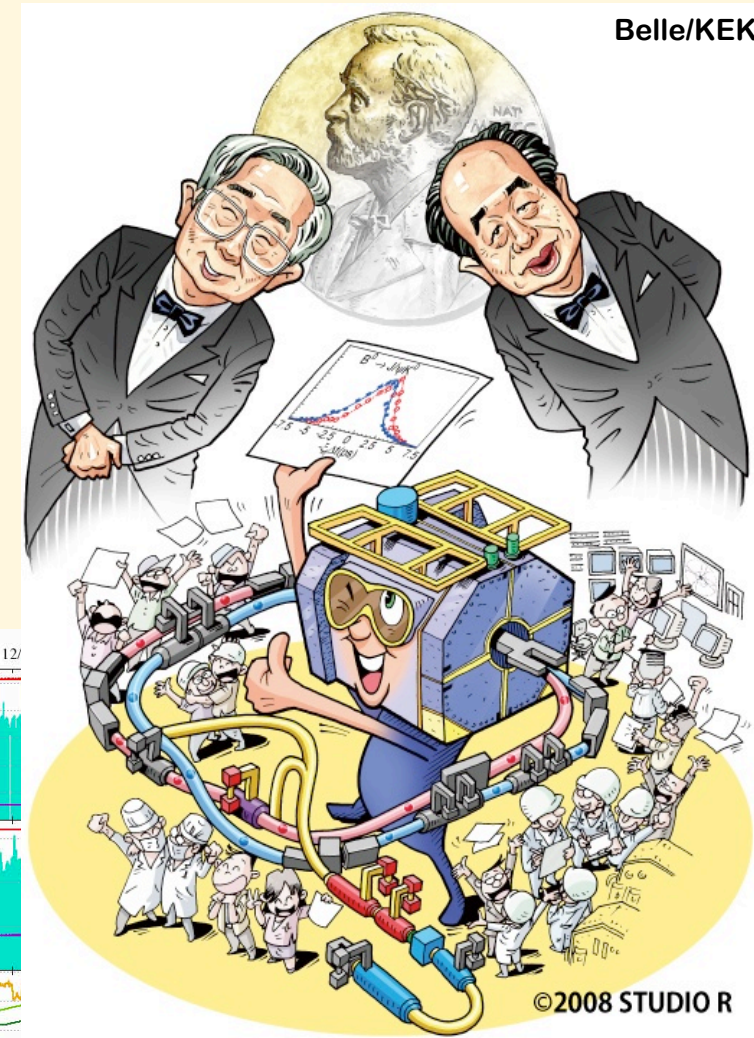
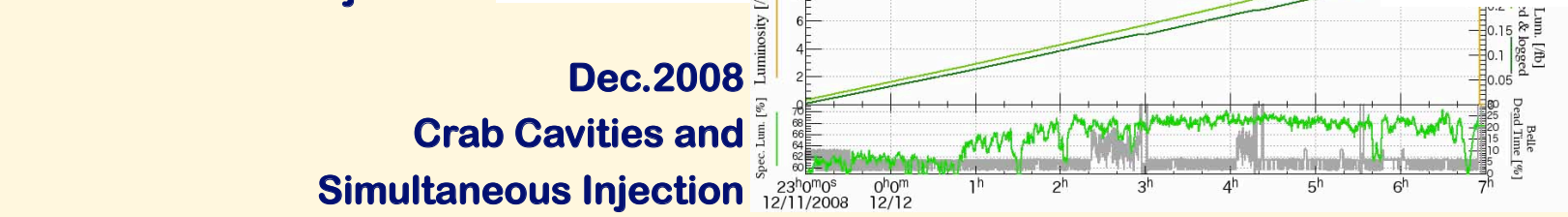
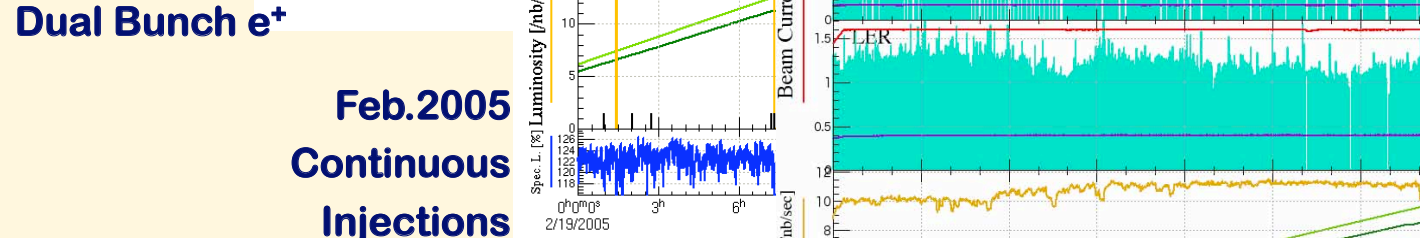
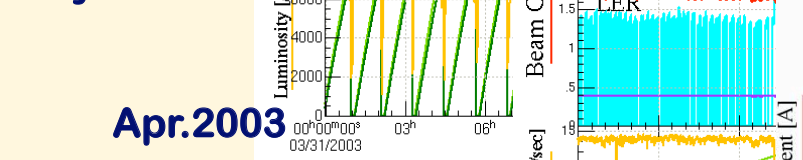
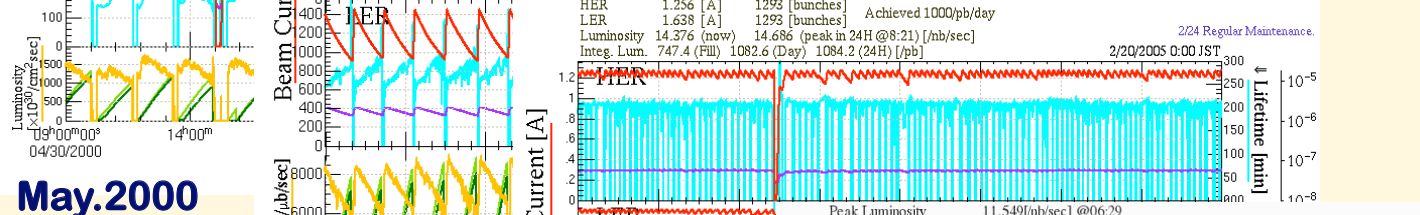
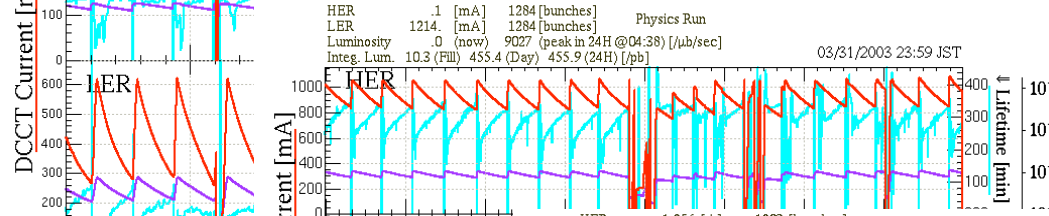
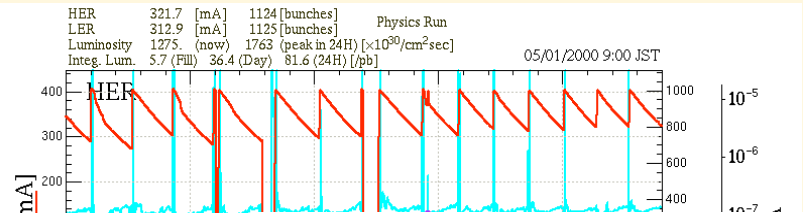
- ❖ Being built for ERL development

- ✧ May share the resources with other accelerators

◆ Sharing resources as much as possible



KEKB Operation Improvement (base of SuperKEKB)



May.2000

Apr.2003

Dual Bunch e⁺

Feb.2005
Continuous
Injections

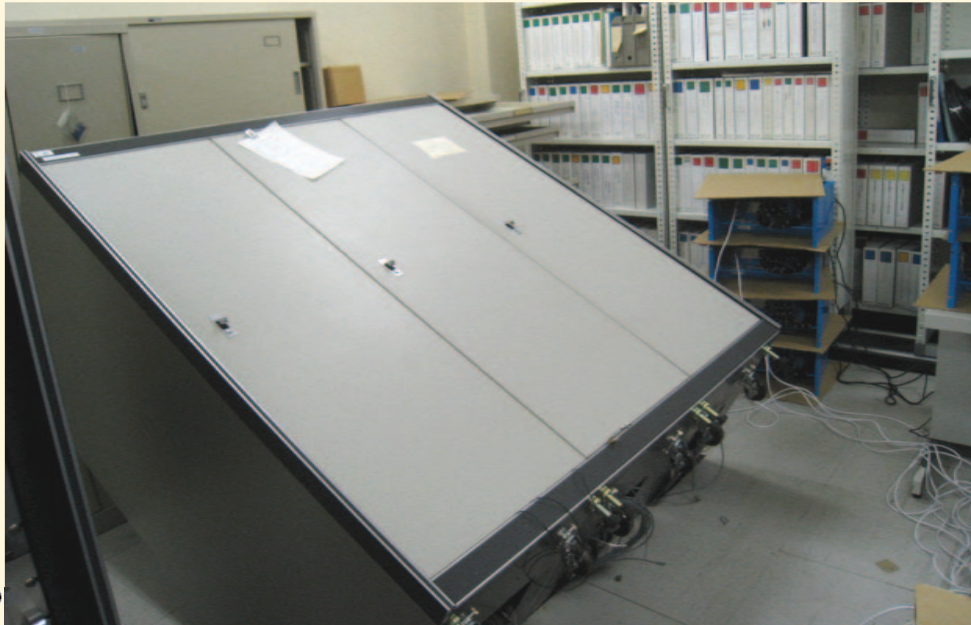
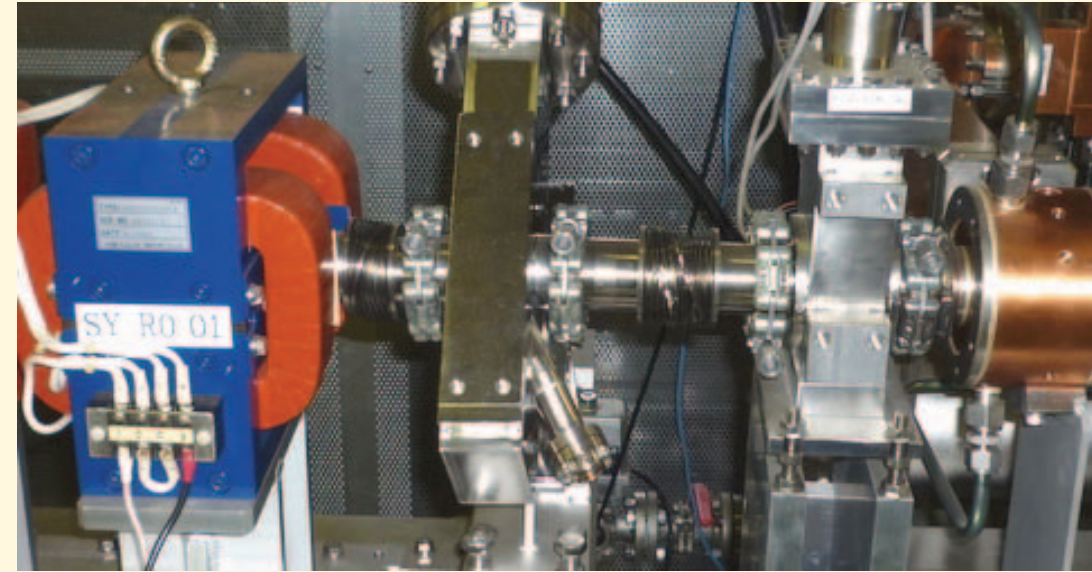
Dec.2008
Crab Cavities and
Simultaneous Injection



SuperKEKB

- ◆ **Electron-positron asymmetric collider**
 - ❖ Based on a decade of successful operation at KEKB
- ◆ **(Most part of) the budget was approved**
 - ❖ Have to start the operation in 2014
 - ❖ Have to recover the damages by earthquake
- ◆ **Aims at 40-times higher luminosity**
 - ❖ $8 \times 10^{35} \text{cm}^{-2}\text{s}^{-1}$ for further flavor physics studies
 - ❖ 7GeV / 2.6A electron, 4GeV / 3.6A positron
 - ❖ $\beta_y^* \sim 0.3\text{mm}$, $\varepsilon_x / \varepsilon_y \sim 4\text{nm}/9\text{pm}$, $\sigma_y \sim 50\text{nm}$, $\sigma_z \sim 6\text{mm}$
 - ❖ Ante chamber, longer bend, damping ring, rf gun, etc

Damages at electron Linac (as example)



Movie at Linac Tunnel (Soft-structure part)



Thank you

◆ Thanks to your concern and kind words from around the world

- ✧ ex. on TV program Yesterday, “cheer up, Japan” in Chinese and in Japanese



KEKB Controls

- ◆ **Large contribution to the success of KEKB**

- ◆ **EPICS as basic environment**
 - ❖ **Standard** software configuration as of 1997
 - ❖ **Several field networks, CAMAC, ArcNet, etc**

- ◆ **Scripting languages for operational tools**
 - ❖ **SADscript, Python/Tk, Tcl/Tk**
 - ❖ **Rapid** modifications based on daily meetings
 - ❖ **Any operators should be able to manipulate complicated feedback, and so on**

Controls at KEK

◆ VME + Unix (1990~)

❖ Standard EPICS configuration

✧ With many third layer field networks



◆ Every controller on network (1995~)

❖ Single layer in physical, two/three layers logical

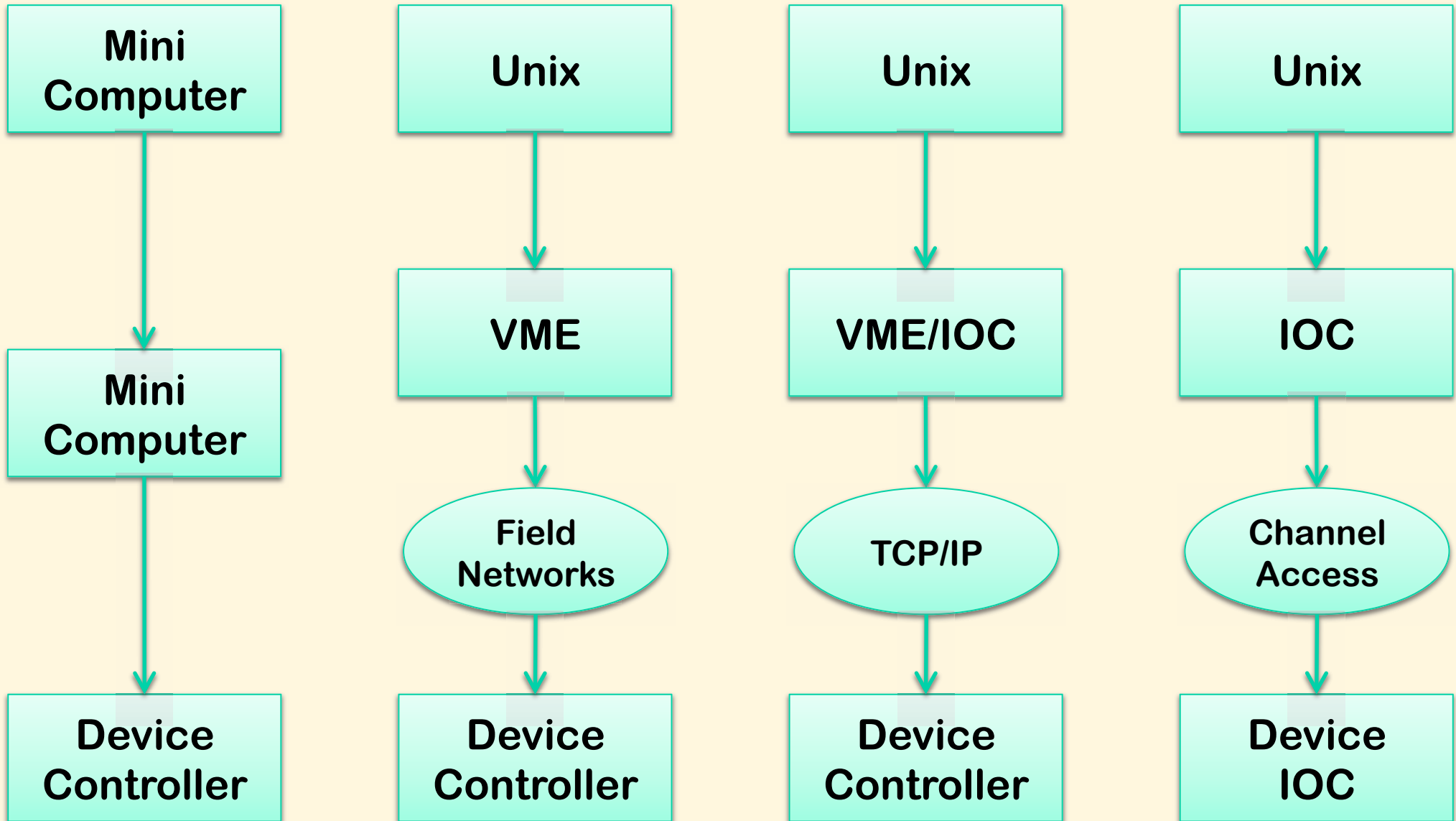


◆ Every controller with EPICS IOC (2005~)

❖ Channel Access everywhere (CA Everywhere)

✧ For longer term maintenance

Transition of Controls



IOC on MicroTCA

◆ Decided to put IOC on μ TCA LLRF Controller

- ✧ Natural after generations of LLRF Controllers
- ✧ Shared among STF, cERL, and SuperKEKB

◆ Chose GbEthernet as a main media on the backplane interconnect

- ✧ Somewhat unique
- ✧ Some other institutes chose PCIe as the media

◆ Chose PowerPC core on Virtex5

- ✧ ML507 of Xilinx as a good reference

◆ Linux on PowerPC (Windriver Linux)

- ✧ No realtime processing is necessary for now

EPICS ✧ Later, we may use realtime PREEMPT_RT (<100 μ s) of Linux



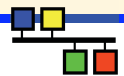
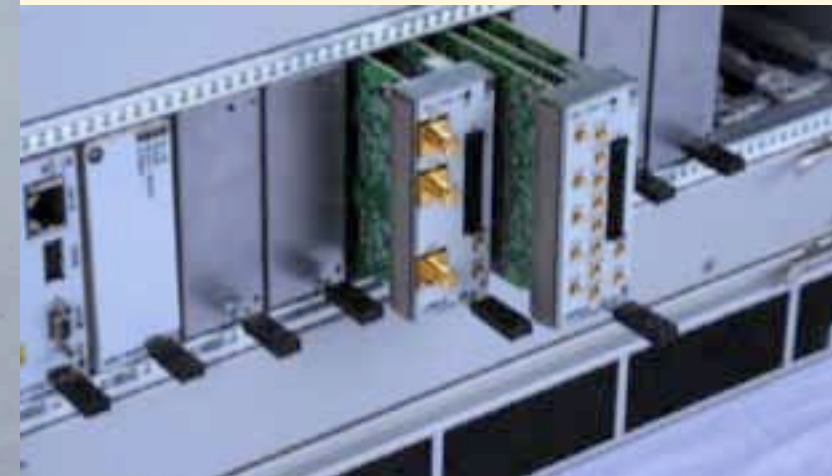
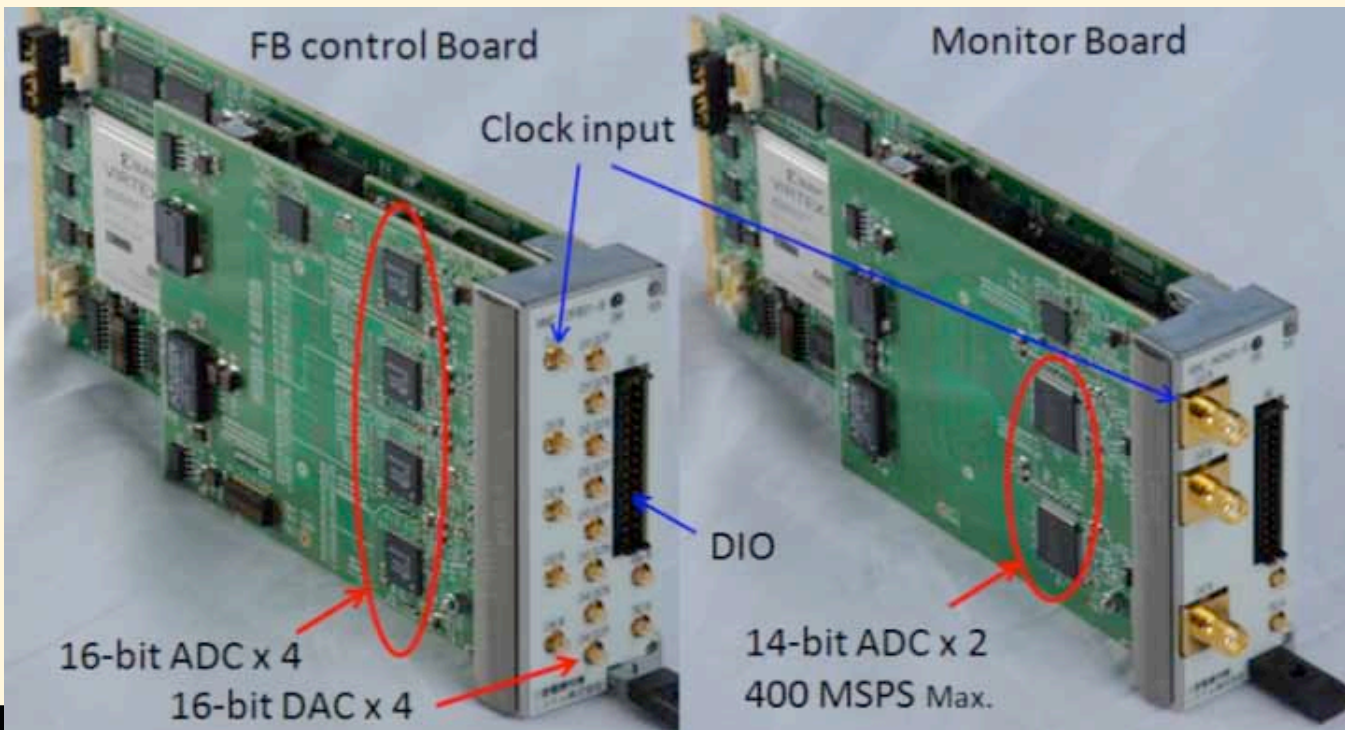
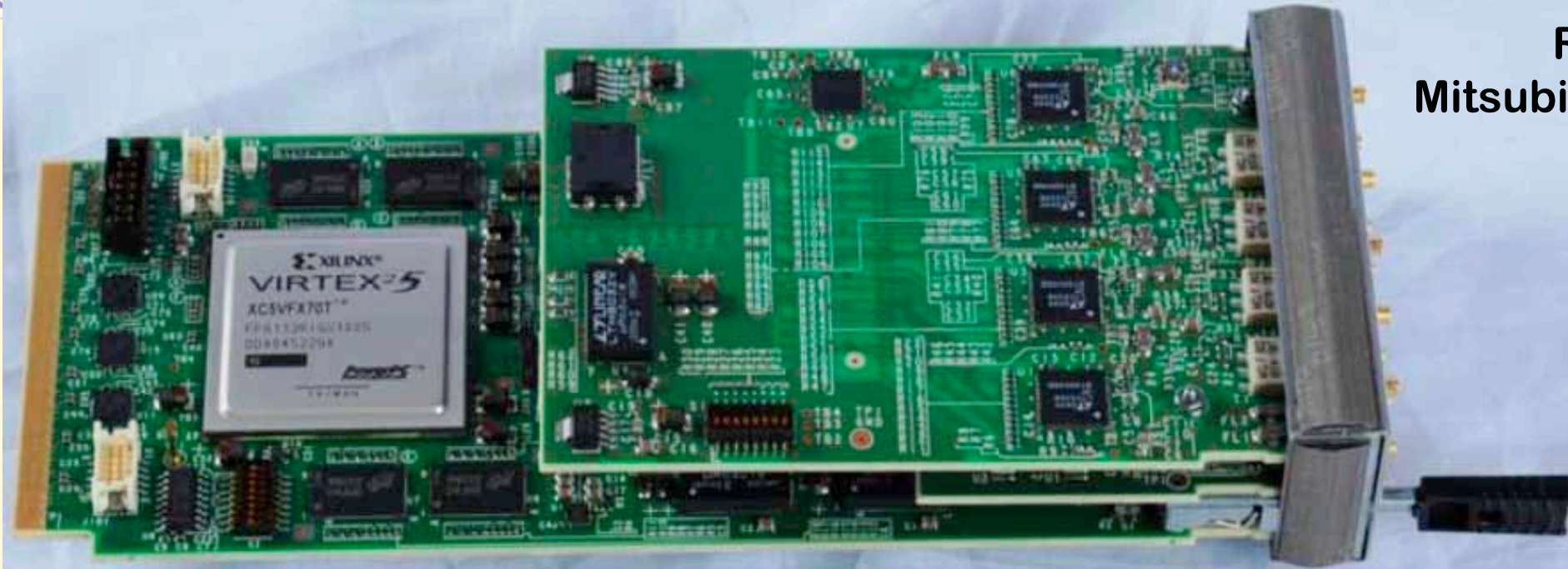
MicroTCA based LLRF Controller

- ❖ **Single-width full-height module**
- ❖ **Without physics experiment extension (we started earlier)**
 - ✧ **Front-panel connectors (rather busy)**
- ❖ **Digital part and Analog part are separate**
 - ✧ **ADC 16bit, 130Msps, x4**
 - ✧ **DAC 16bit, 500Msps, x4**
 - ✧ **Virtex5 with PPC440**
 - ✧ **RAM 640MB, Flash 64MB**
 - ✧ **Also monitor card with the same digital part**
 - ◆ **ADC 14bit, 400Msps, 1.4GHz, x2**
- ❖ **Fabrication subcontracted**
 - ✧ **Mitsubishi Electric Tokki System**
<<http://www-linac.kek.jp/cont/epics/mtca/>>





RF Group Mitsubishi Tokki



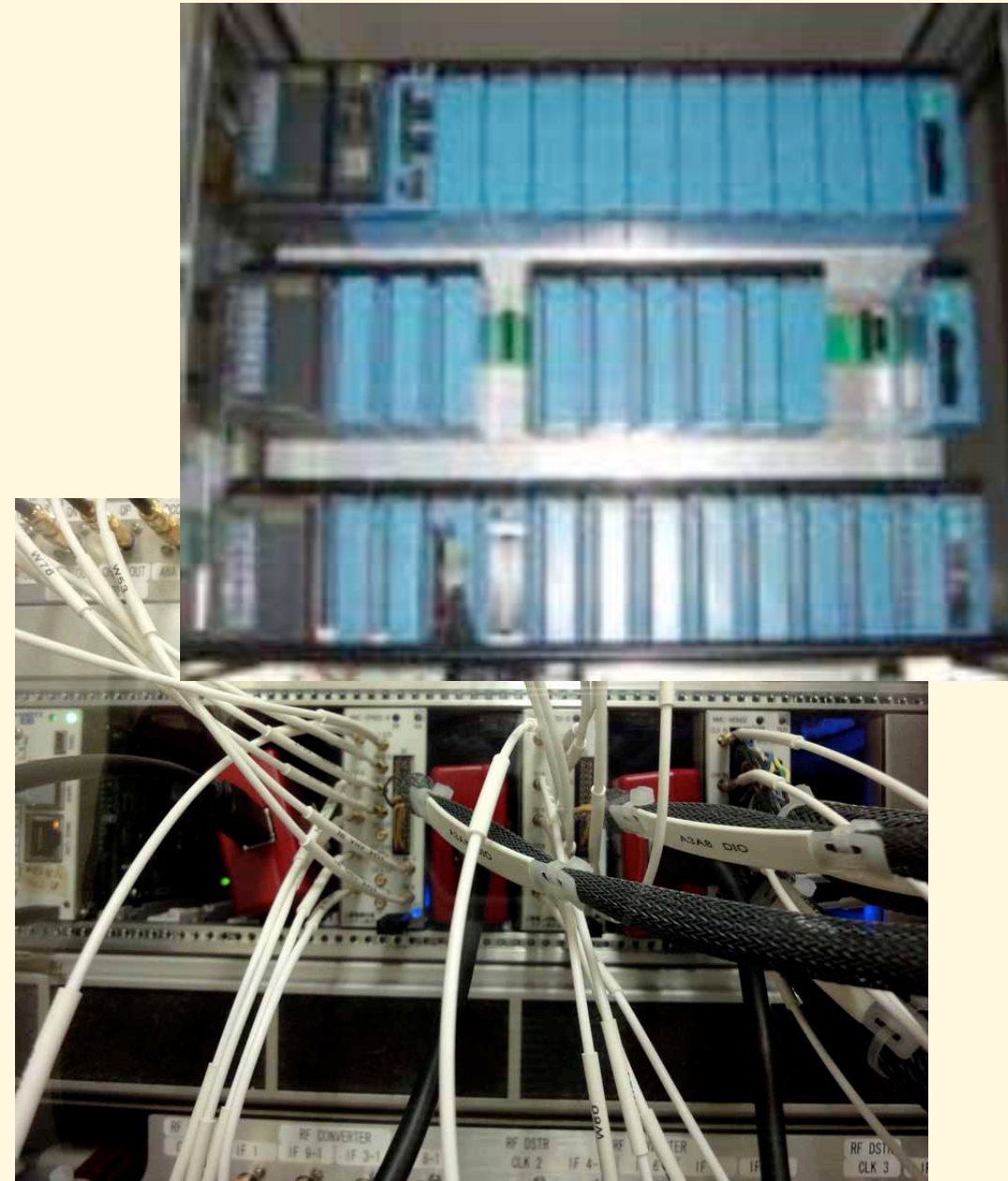
RF Controls



CAMAC and NIM modules



MicroTCA and PLC



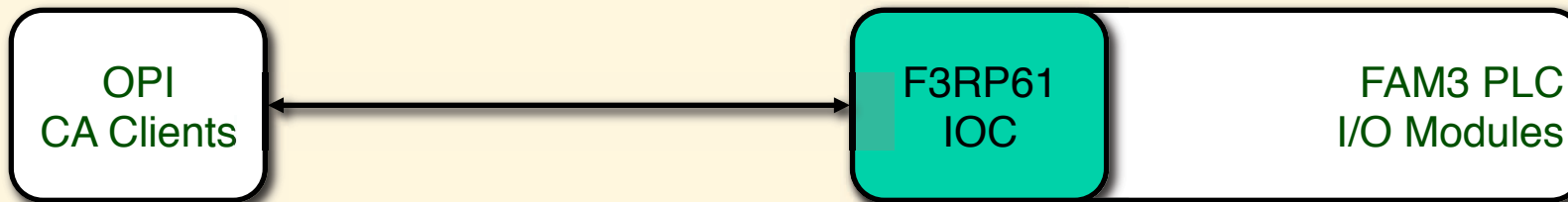
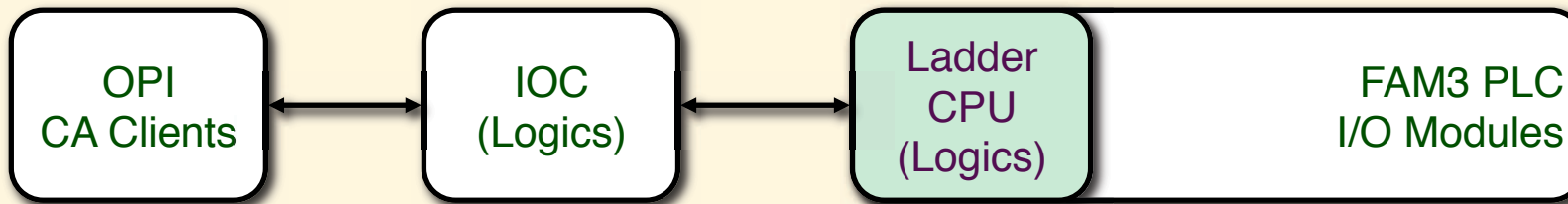
Embedded IOC in Yokogawa's PLC

- ◆ **More than 150 PLCs were employed at Linac**
 - ❖ **All through TCP/IP network since 1993**
 - ✧ **Successful to reduce resource consumption**
- ◆ **Now Linux CPU is available (2008~)**
 - ❖ **533MHz PPC, 128MB RAM, 2xEthernet, USB**
 - ❖ **Utilize realtime feature of Kernel 2.6 (J. Odagiri et al)**
 - ✧ **EPICS PV response time $<150\mu\text{sec}$ (incl. module delay)**
- ◆ **Ladder sequence CPU can coexist**
 - ❖ **Register variables can be shared**

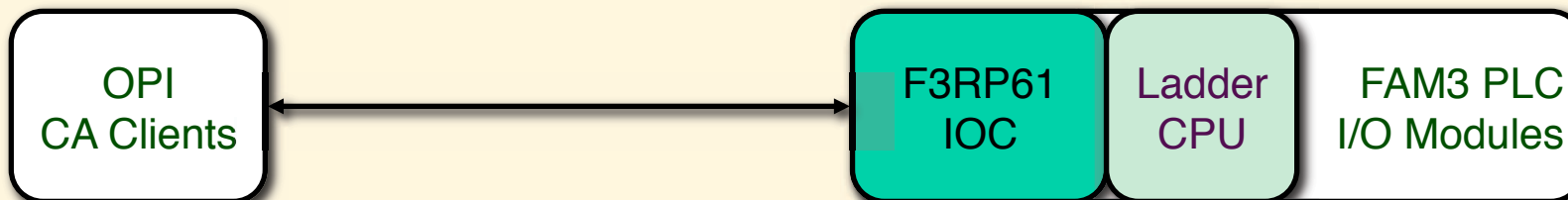
Simpler PLC Usage under EPICS

Conventional PLC usage

with asynchronous access



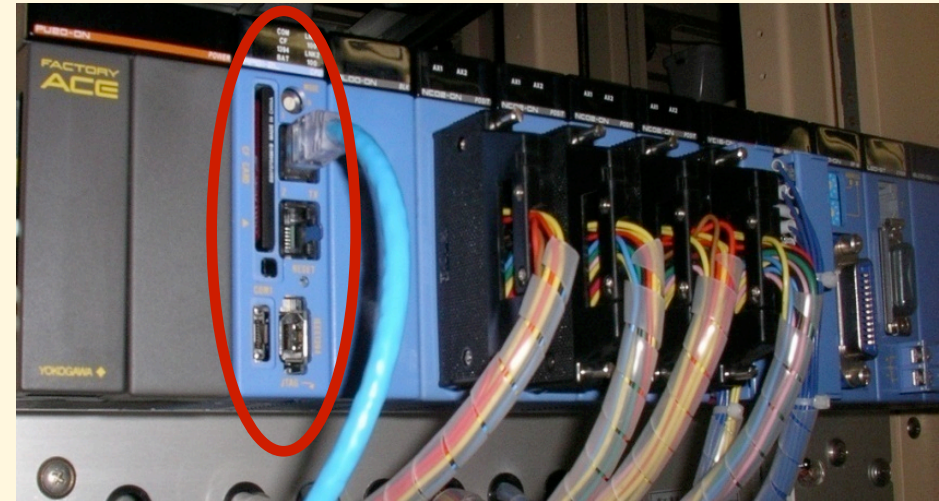
If necessary, we can combine



Logics are confined in PLC, and management is easier

- ◆ **Many medium-speed controllers implemented**

- ❖ **KEKB, Linac, J-PARC, PF, cERL, RIKEN, NSRRC, (Korea/PAL, Beijing/IHEP)**



- ◆ **Image processing module available**

- ◆ **Discussing on EVR module production with SINAP/Shanghai**

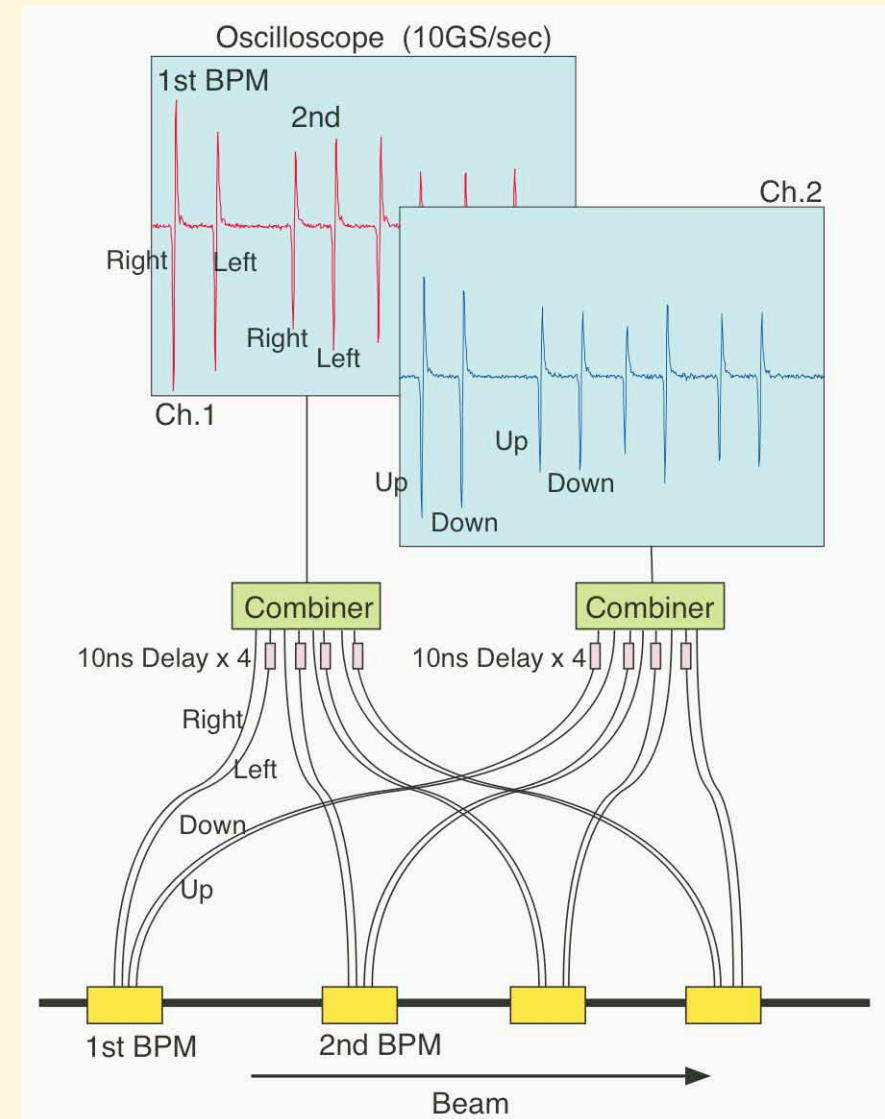
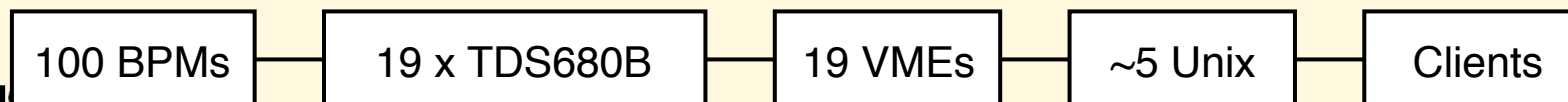
<<http://www-linac.kek.jp/cont/epics/f3rp61/>>

BPM at Linac and BT

- ◆ **BPM need only 0.1mm resolution**
 - ❖ **Using ~30 coefficients per BPM**
- ◆ **Many signals are combined into one waveform digitizer**
- ◆ **Again reduction of resources**
- ◆ **Recent Embedded IOC Solution**
 - ❖ **Much helped by Dr. Yong Hu**

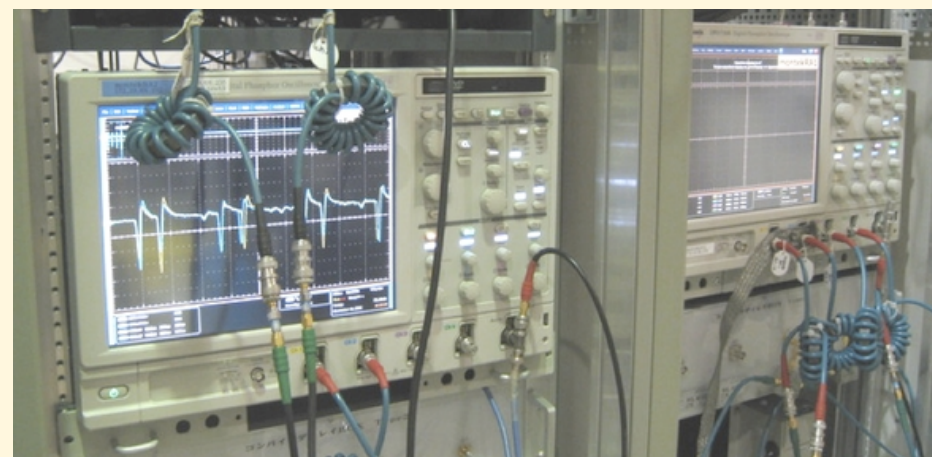
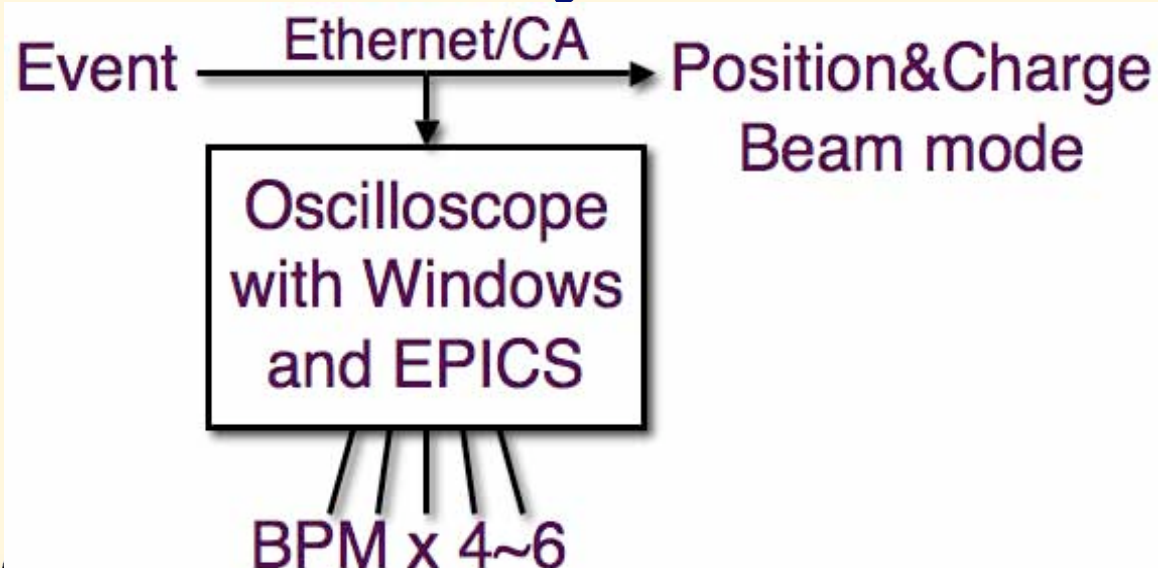


◆ Old configuration



BPM DAQ

- ◆ Tektronix DPO7104 can acquire data at $>50\text{Hz}$.
 - ❖ With embedded EPICS, under pulse-to-pulse beam modulation
- ◆ Beam modes are recognized by events through CA network.
 - ❖ Missed less than once in million times
- ◆ Clients can monitor data of an interested beam mode.
- ◆ 24 oscilloscopes are installed for Linac, and 4 for BT.
- ◆ 200 BPMs are synchronized for Linac and BT.



Many other Embedded IOC

- ◆ **Other oscilloscope-based IOCs**
 - ❖ For pulsed device monitors (M. Satoh et al)
- ◆ **TDC/Linac with Linux/ARM (Armadillo)**
 - ❖ Timing consistency surveillance (S. Kusano et al)
- ◆ **MPS manager with Linux/FPGA (Suzaku)**
 - ❖ For J-PARC and cERL, etc (A. Akiyama et al)
- ◆ **Magnet PS with Linux/ARM(or FPGA)**
 - ❖ One of Two prototypes for SuperKEKB (T. Nakamura et al)
- ◆ **Possible Libera BPM readout (?)**
 - ❖ with modifications for simultaneous injections
- ◆ **Vacuum measurement with cRIO (?)**
 - ❖ with Channel Access enabled

KEKB Commissioning Groups

◆ Formation of Commissioning Group (KCG)

❖ Linac Commissioning (LCG)

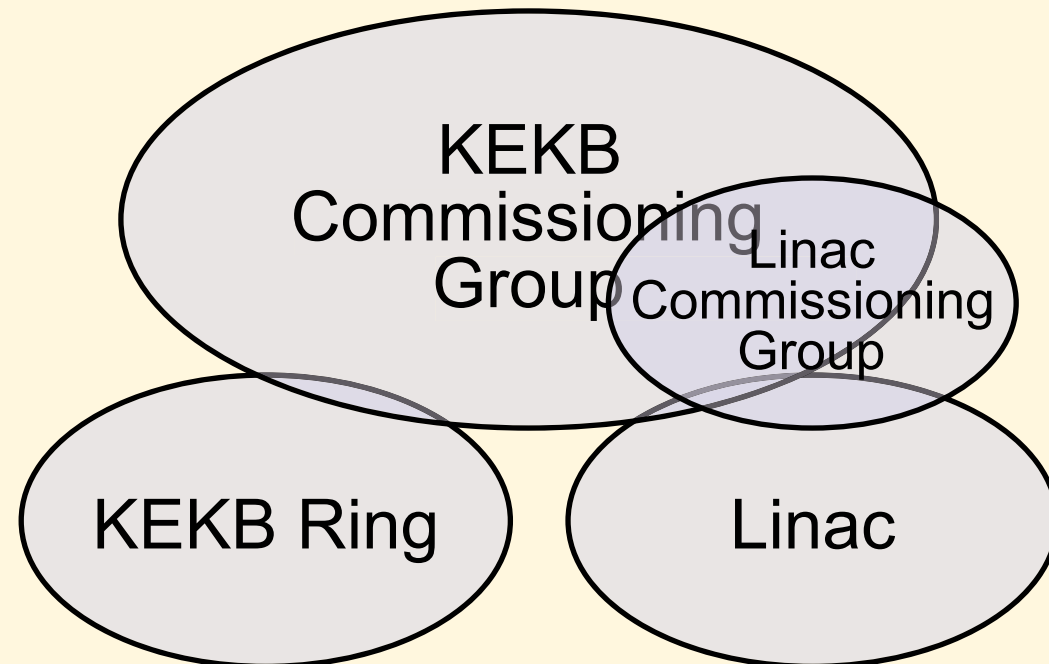
- ✧ 7 from Linac
- ✧ ~10 from Ring

❖ KEBK Ring Commissioning Group (KCG)

- ✧ All LCG
- ✧ ~20 from Ring
- ✧ Several from Detector (BCG)

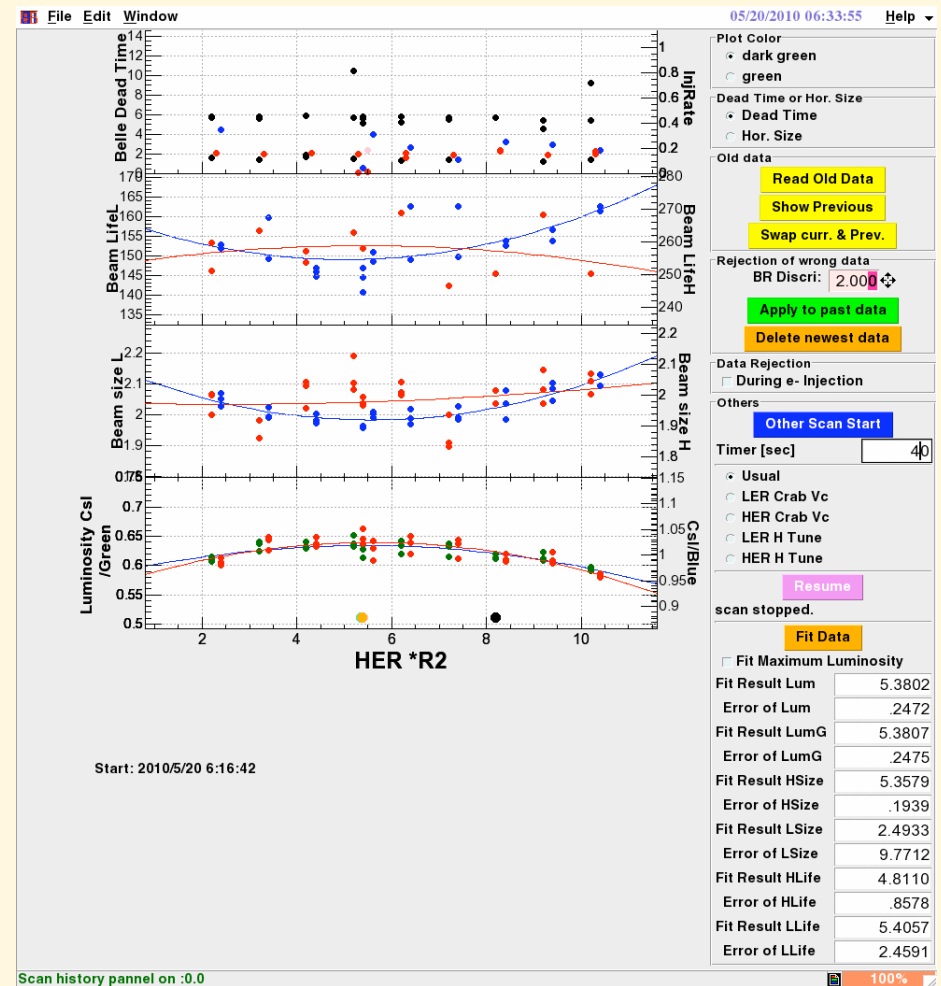
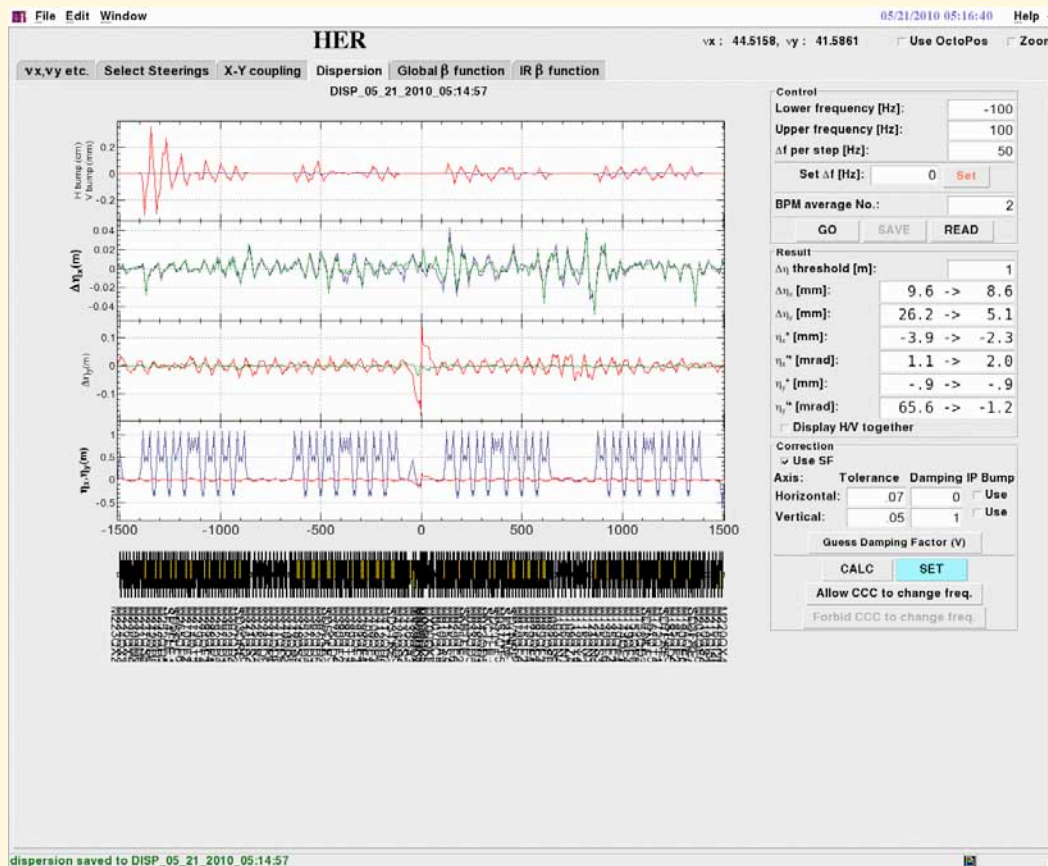
❖ Commissioning software base was formed during Linac Commissioning (1997~)

SADscript/Tk , Python/Tk



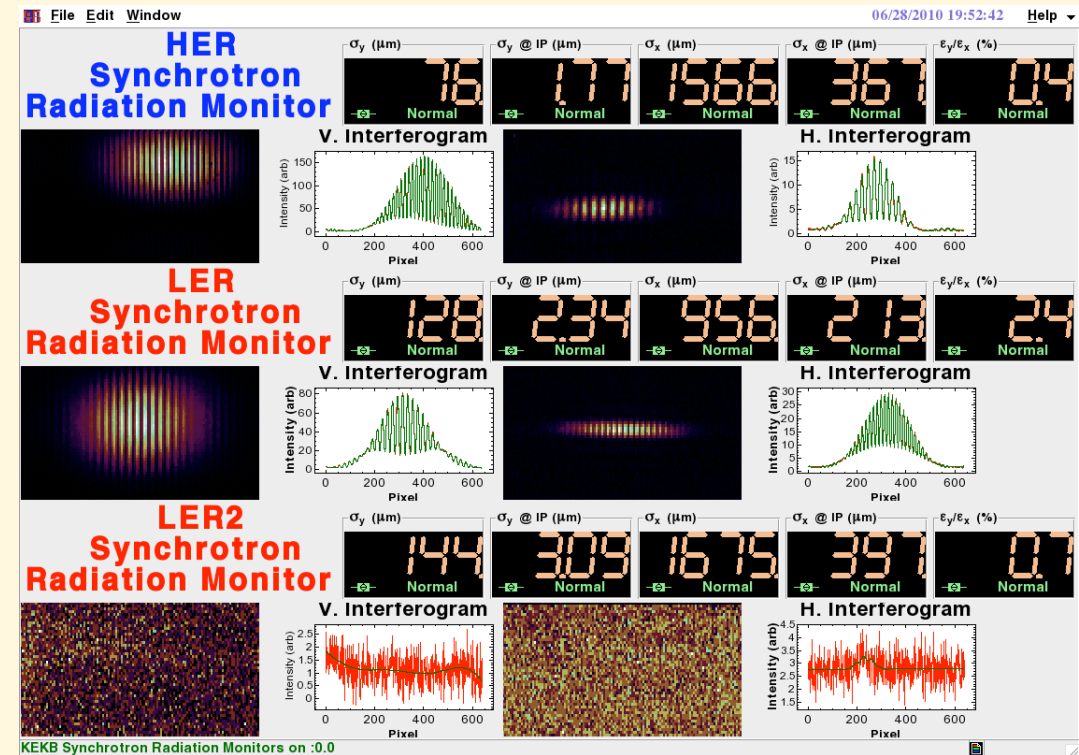
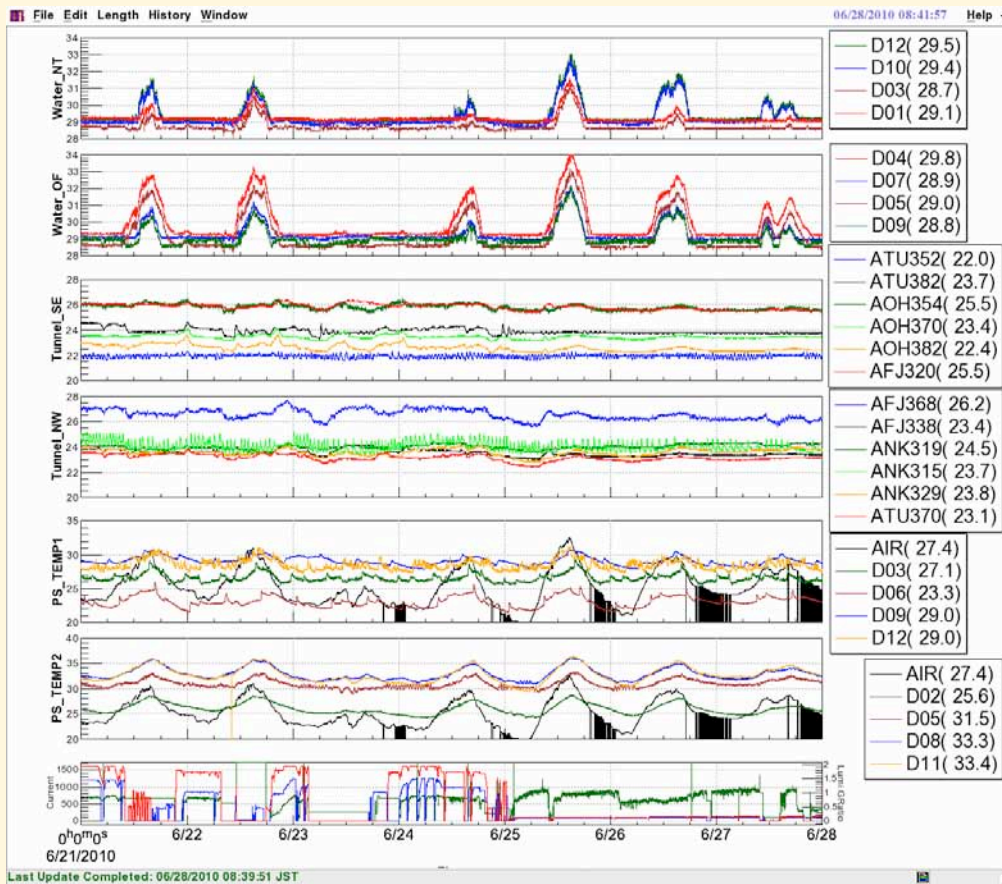
SADscripts/Tk

◆ Many machine diagnostic and correction/feedback tools



Archive viewers and Strip charts

◆ Visualization is important



SuperKEKB Plan (1)

- ◆ **For nano-beam scheme with 40-times higher luminosity**
 - ❖ Many new facilities should be required
- ◆ **Will start based on the existent environment**
 - ❖ With additional concept of CA everywhere
- ◆ **Help device groups to have better global controls**
 - ❖ Replacement of old installations such as CAMAC
 - ❖ Solutions not only VME but also other types of controllers, embedded EPICS if possible
- ◆ **Faster networks for the groups who can build controllers by themselves**
- ◆ **Better connection to operational environments**
 - ❖ Keeping SAD environment, etc
 - ❖ Monitoring at offices

SuperKEKB Plan (2)

◆ Archiving scheme and viewer

- ❖ Maybe existing KEKBlog and channel archivers
 - ✧ New viewer should be developed

◆ Alarm handler

- ❖ CSS or Python (to simulate KEKBalarm)
 - ✧ Should evaluate soon

◆ Operational Log

- ❖ In house, two versions with different origins
 - ✧ Postgres + (Python/Zope and Flash/Flex)

◆ Scripts

- ❖ SADscript/Tk, Python/Tk, (decreasing Tcl/Tk)

◆ Displays

- ❖ CSS and MEDM/EDM

SuperKEKB Plan (3)

◆ Interviews to each device groups

❖ Planning to have monthly meeting and training

- ✧ To collect user requirements

❖ Partially successful for old hardware replacements

- ✧ Not yet effective for new functionalities

- ◆ Whether both sides do not have experiences

◆ ex. Global orbit feedback

- ◆ We don't need to stabilize the orbit other than the collision point

❖ Monitor group is basically responsible for this

- ✧ Under development with several candidates

- ✧ But they still need some data path



Simultaneous Injection

- ◆ SuperKEKB injector need simultaneous injections to four rings, HER, LER, PF, and PF-AR, with different beam characteristics
- ◆ Event timing controls will be described some more in Timing session

Summary

- ◆ **Controls Have Interface to Every System in Accelerators**
 - ❖ **We can Enjoy Accelerator**
- ◆ **There should be Room to Establish Further Controls Utilizing Beam Monitors, RF Monitors, and More**
 - ❖ **With Phronesis, Ability to understand the Universal Truth**



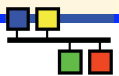
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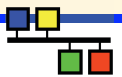


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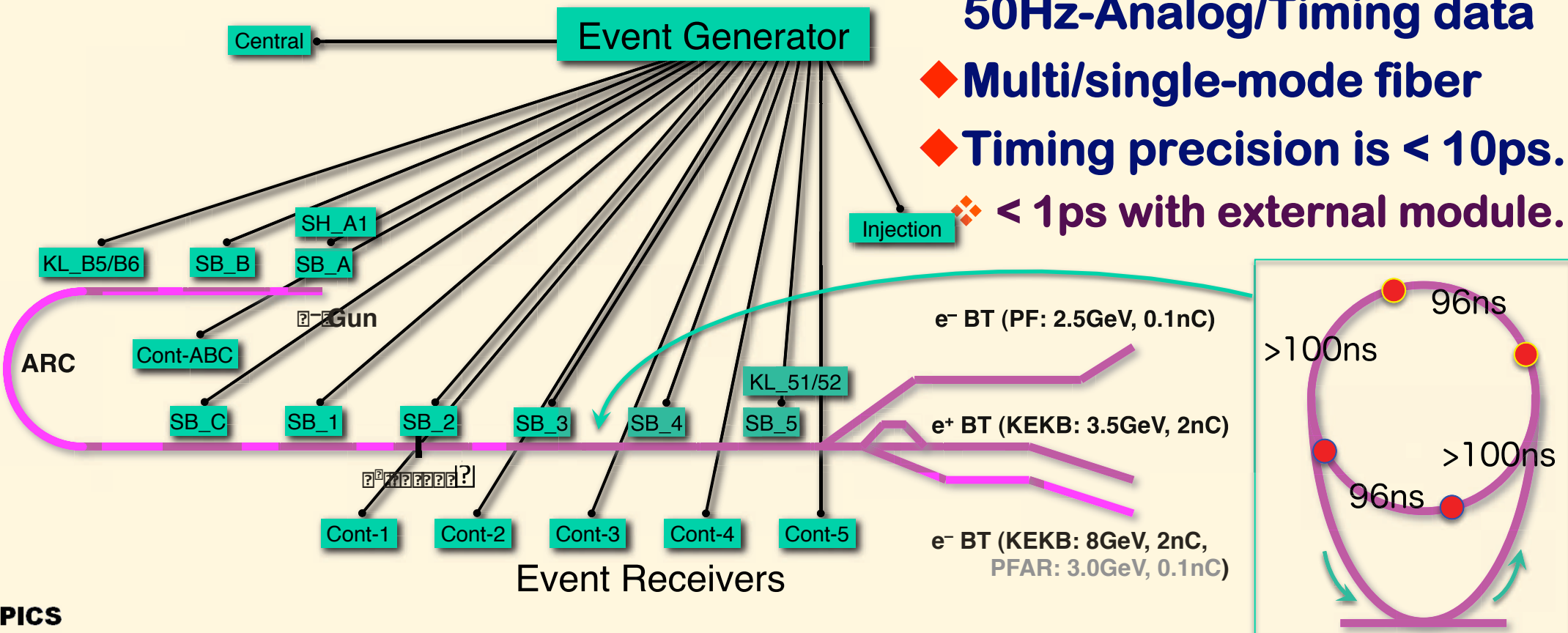


Backup



Event System for Simultaneous Injection

- ◆ MRF's series-230 Event Generator / Receivers
- ◆ VME64x and VxWorks v5.5.1
- ◆ EPICS R3.14.9 with DevSup v2.4.1
- ◆ 17 event receivers up to now
- ◆ 114.24MHz event rate, 50Hz fiducials
- ◆ More than **hundred** 50Hz-Analog/Timing data
- ◆ Multi/single-mode fiber
- ◆ Timing precision is $< 10\text{ps}$.
- ◆ $< 1\text{ps}$ with external module.



Parameters

◆ Parameters switched via event system

❖ LLRF phase/timing : 14x4

✧ Overall energy profile, dual-bunch energy equalization, final energy adjustment

❖ HP RF timing : ~60

✧ Energy profile and backup management

❖ Gun voltages, picosecond delay : 4

✧ Beam charge selection, dual bunch selection, bunching

❖ Pulsed magnets/solenoid : 14

✧ Beam transport selection, orbit controls, positron focusing

❖ Injection phase interface : 2

❖ Bucket selection interface : 2

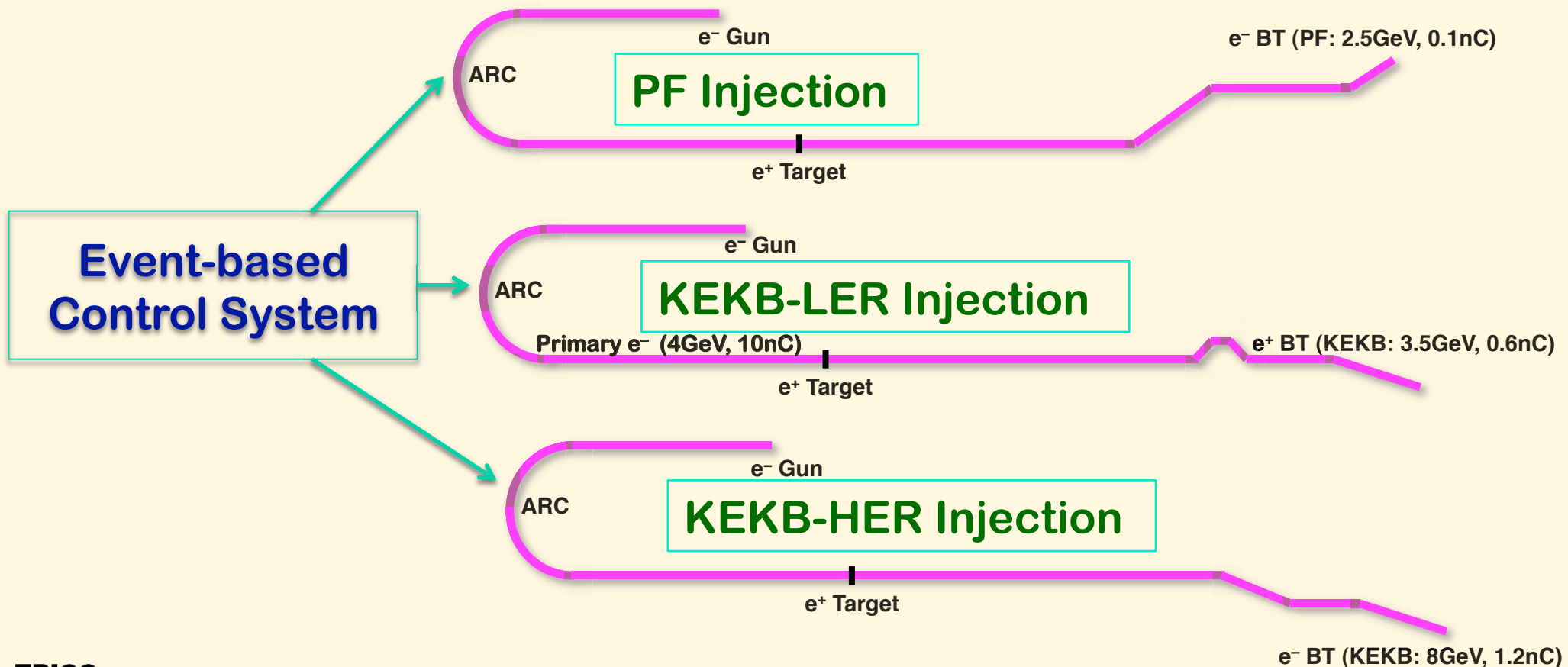
❖ BPM : ~100x3

◆ Sufficient for fast beam mode switching

◆ Integrity monitors soon

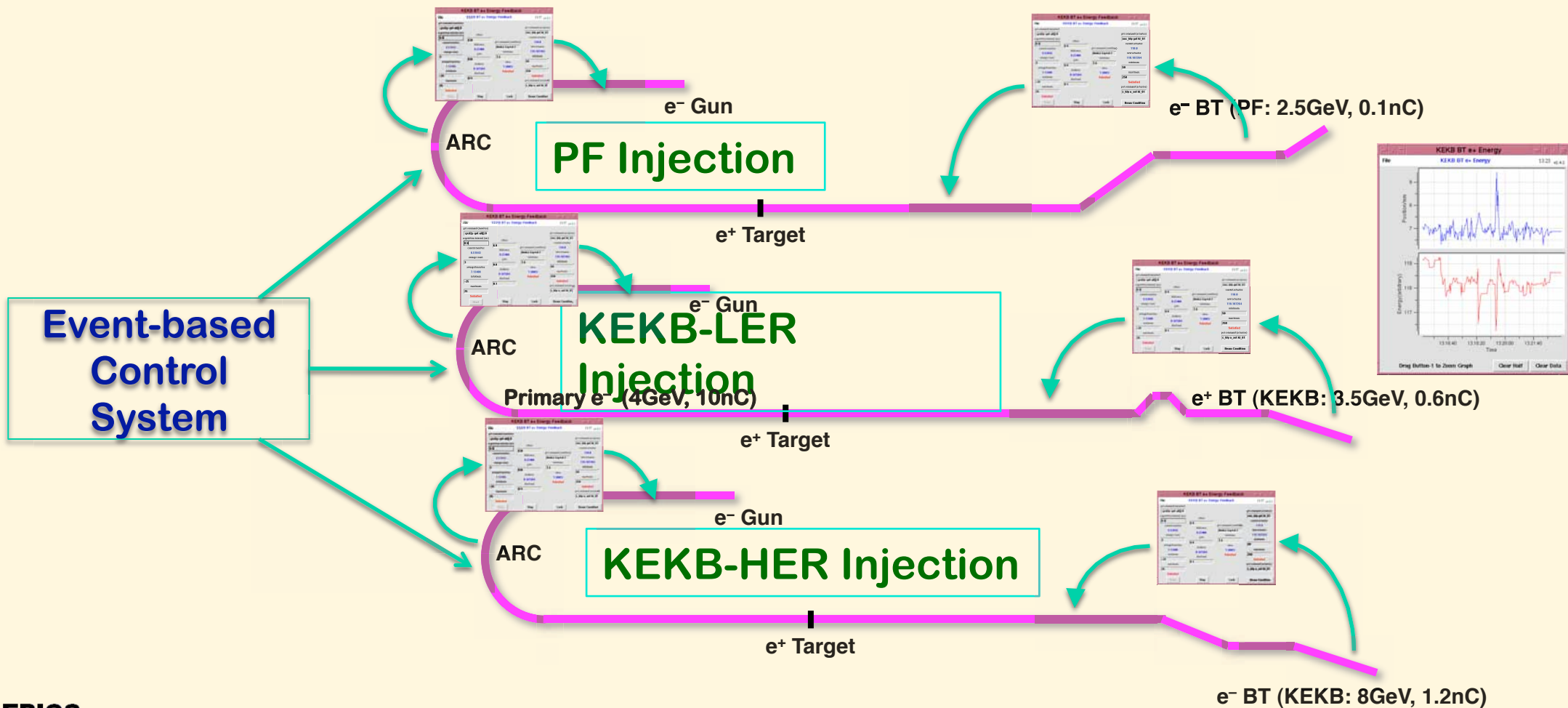
Three Virtual Accelerators

- ◆ Controls and instrumentations are essentially mode-dependent, and mutually independent
- ◆ Selecting a real machine out of three virtual machines
 - ❖ Managing three parameter sets (four under SuperKEKB environment)



Three-fold Independent Closed Loops

- ◆ Feedback loop software act on one of three virtual machines
 - ❖ Managing independent parameter sets



Event System Consideration for SuperKEKB

◆ Possibly Cascaded Event Systems

- ❖ For damping ring, main ring and other sub-systems

◆ New firmware with new register map

- ❖ For newer device support software in EPICS community
 - ✧ Several local modification already, want to synchronize with other institutes
- ❖ Several institutes in Asia may use CompactPCI as well
 - ✧ Whether PLC version can use the same environment??

◆ Several fast control projects for SuperKEKB

- ❖ Several embedded systems with PLC EVRs for RF stations
- ❖ Bucket selection to cover both damping and main rings
 - ✧ In KEKB, separate system was used and selection signal was used as AC to EVG
- ❖ Fast feedbacks in Linac and in main ring

◆ Several others