

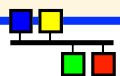


Timing system towards SuperKEKB controls

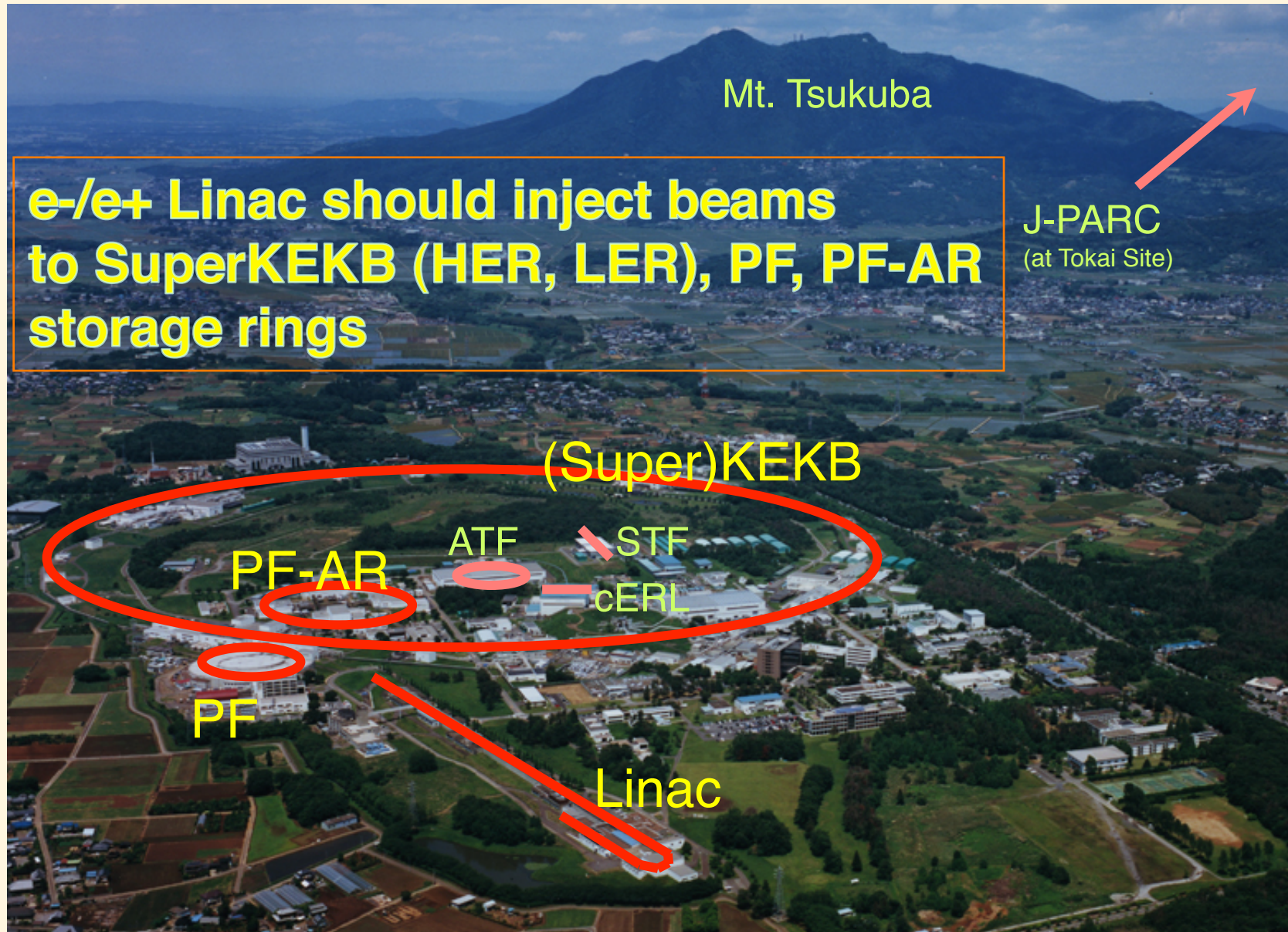
Kazuro Furukawa
for Control Group of SuperKEKB

< kazuro.Furukawa @ kek.jp >

June 2011.

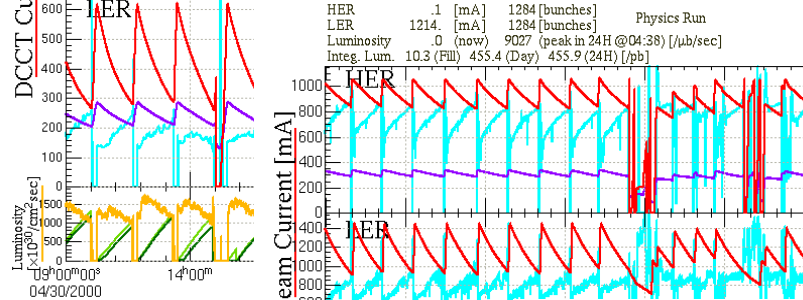
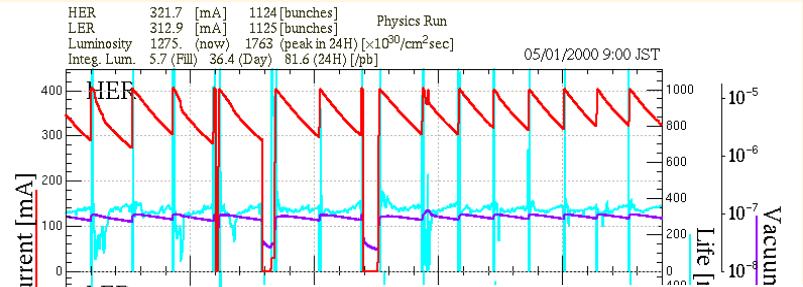


Accelerators at KEK



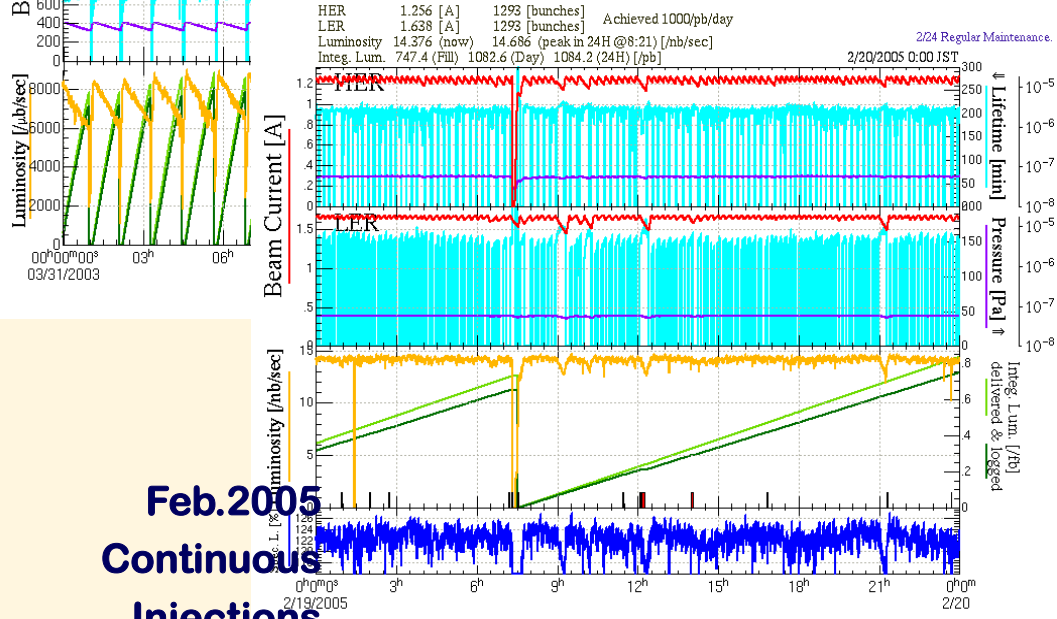


KEKB Operation Improvement up to 2007

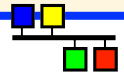
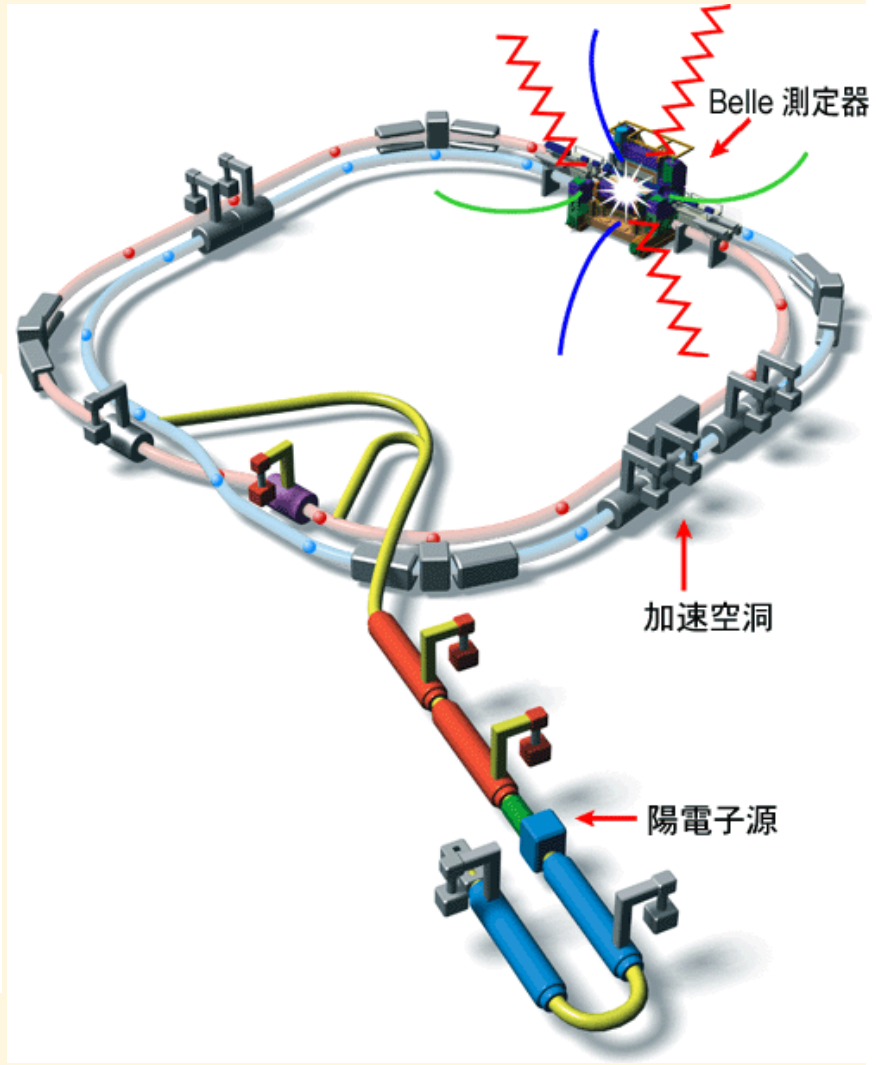


May.2000

Apr.2003
Dual Bunch e⁺

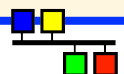
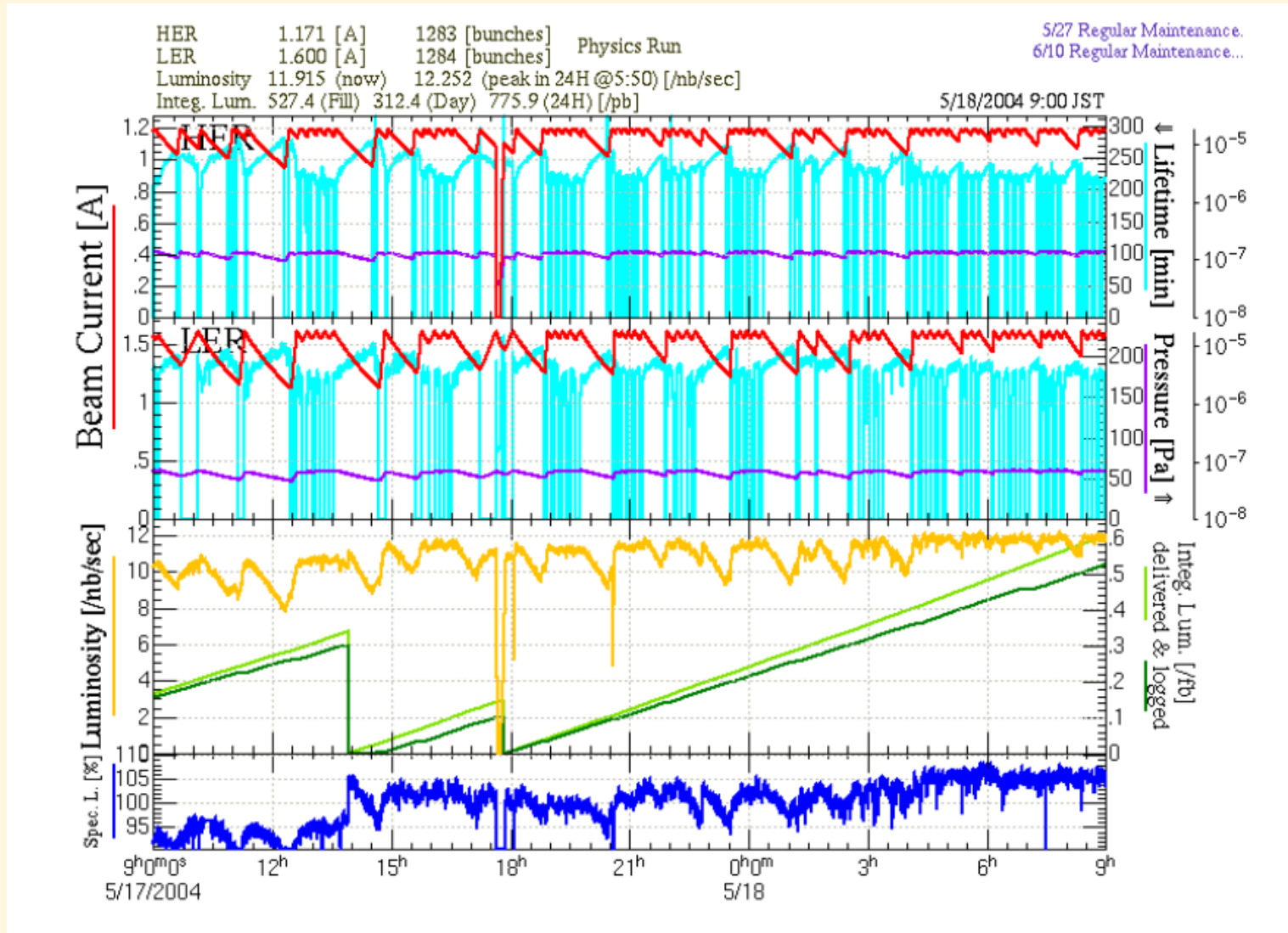


Feb.2005
Continuous
Injections





Sometimes injection needed simultaneously



Fast beam switching or Simultaneous Injection

- ◆ **KEKB Luminosity degradation on beam studies at PF and PF/AR**
- ◆ **Future SuperKEKB injections with shorter lifetime**
- ◆ **Sensitive luminosity tuning with Crab cavities**
- ◆ **PF (and PF-AR) top-up injections for higher quality experiments**
 - ❖ **CERN/PS switches beams every 1.2s (PPM)**
 - ❖ **SLAC/SLC switched beams at 180 Hz**
 - ❖ **KEK Linac had switched beams 360 times a day in 2008 (just before simultaneous injection)**
 - ❖ **10~120seconds per switching**

Requirements

- ◆ **Maximum beam rate of 50Hz x 2bunches should be kept**
- ◆ **Most pulsed power supplies were designed to operate at constant rate (a restriction to beam mode pattern)**
- ◆ **Most linac magnets were not pulsed (except positron focusing coil)**
 - ❖ **Thus, it took much time for mag-field standardization**
- ◆ **Approx. 1000 devices in linac**
 - ❖ **600 active devices (gun, RF, magnets, etc), 100 passive devices (BPM, WS, etc), and static devices**
- ◆ **20ms beam switching became the solution**

Timing system domain

◆ Timing domain

- ❖ 20milli-second - Pulse-to-pulse, Beam mode flavors,
- ❖ Micro-second - pulsed power supplies
- ❖ Nano-second - Shape of pulses for pulsed microwave
- ❖ Pico-second - Beam timing, instrumentation
- ❖ < pico-second - Microwave phases

◆ Hardware media / software

- ❖ Microwave – we always need this
 - ✧ Pulse shape, phase control
- ❖ Event timing controls – intelligent timing
 - ✧ Pulse-by-pulse event manipulations

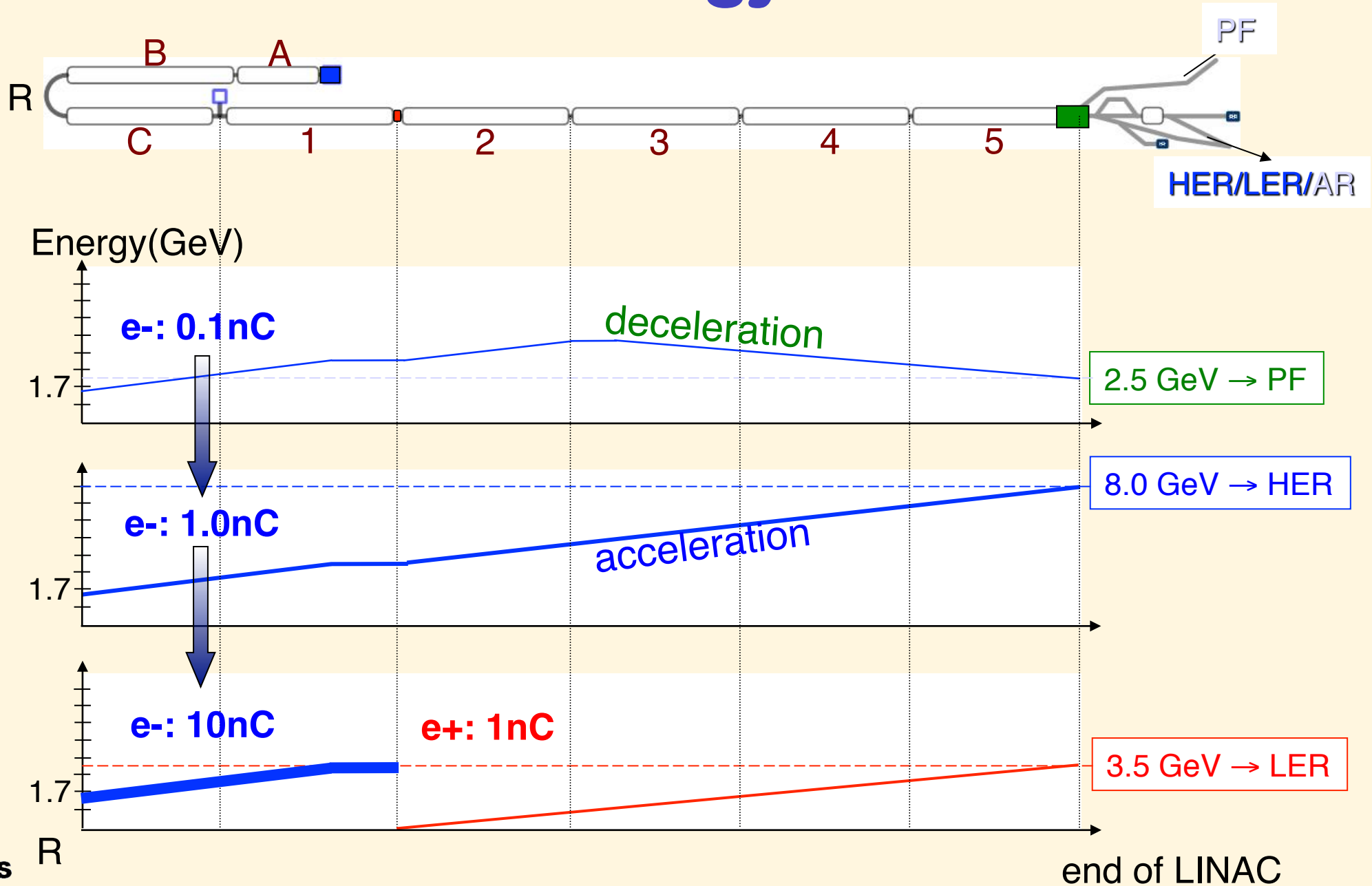
Detailed requirement at SuperKEKB

- ◆ **Stable multiple frequencies (114, 571, 1298, 2856, 509MHz)**
 - ❖ Beam bunching for large-current positron single-bunch generation
 - ❖ Need integer relations (common freq. 10.38MHz)
- ◆ **Injection timing precision of 30 picoseconds**
 - ❖ Integer relation to (Super)KEKB for aperture at IP
 - ✧ Accidental coincidence for PF and PF-AR with less severe condition
- ◆ **Independent Circumference corrections at KEKB, PF, PF-AR**
 - ❖ KEKB changes 4×10^{-7} , PF and PF-AR changes $4 \sim 20 \times 10^{-6}$
- ◆ **2bunches in a single pulse (50Hz)**
 - ❖ Separated by 96ns (common freq. 10.38MHz)
- ◆ **Simultaneous top-up injections to 4 rings SuperKEKB HER/ LER, PF and PF-AR**
 - ❖ Common beam transport to KEKB and PF-AR will be upgraded

Hardware and Operation Improvements

- ◆ **Separate BT for PF (2005)**
- ◆ **Pulsed bending magnet for PF (2007)**
- ◆ **PF beam from common gun (A1) (2007)**
- ◆ **Beam charge safety interlock (2007)**
- ◆ **Event-based fast control system (2008)**
- ◆ **Pulsed steering magnets (2008)**
- ◆ **Electron bypass hole at positron target (2008)**
- ◆ **Interface between ring-linac RF (2008)**
- ◆ **Multi-energy linac optics (2008)**
- ◆ **Simultaneous injections (Apr.2009)**

Linac Energy Profile



Power Management

◆ Power management at each power source

- ❖ of 60 50-MW power sources
- ❖ In order to maximize the power
- ❖ But not to increase the trip rate
 - ✧ Interlock at a reflection level VSWR of 1.4
 - ✧ If a trip rate is higher, the voltage is lowered
 - ✧ Surveyed statistically every week

◆ Some sources will be stand-by state

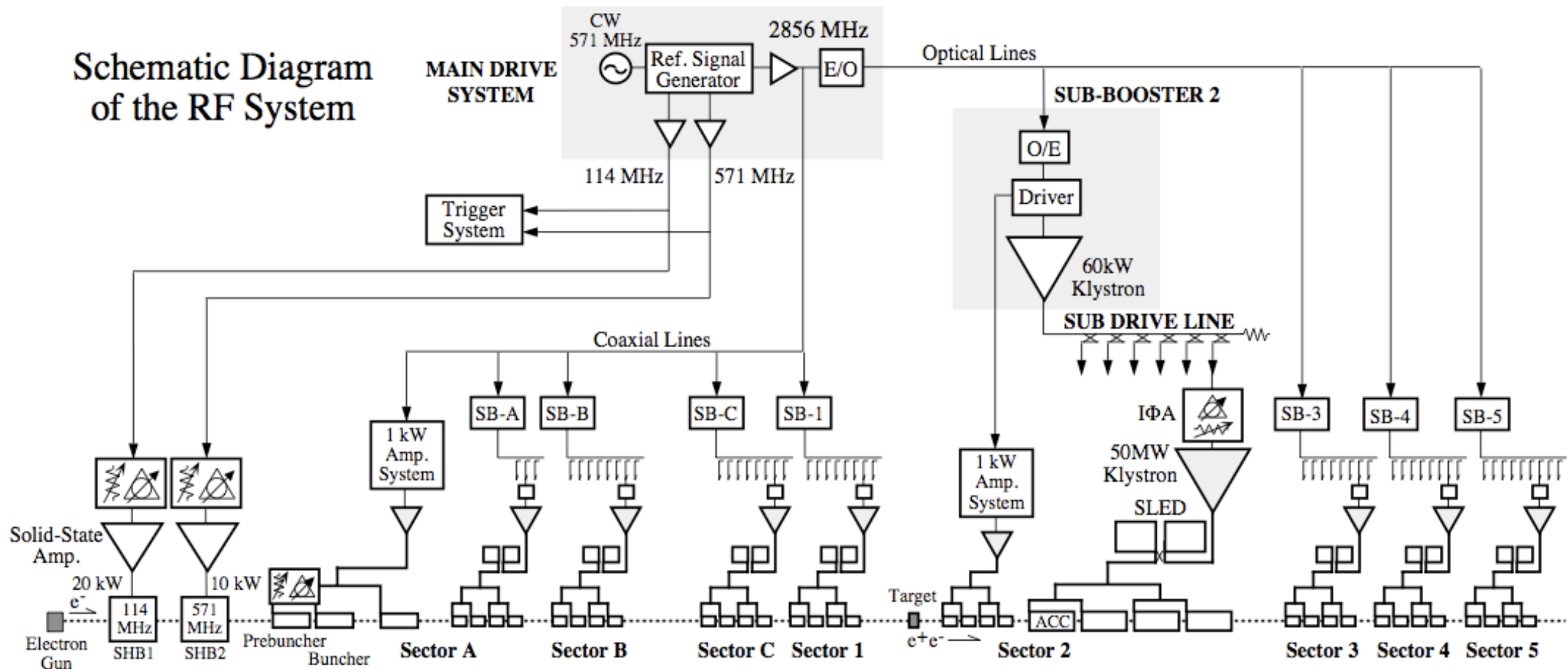
- ❖ As backups, if the energy is enough
 - ✧ KEKB e⁺ has several stand-by, KEKB e⁻ has typically one

◆ Energy conversion

- ❖ Energy gain = constant x sqrt(power)

Linac Energy Management

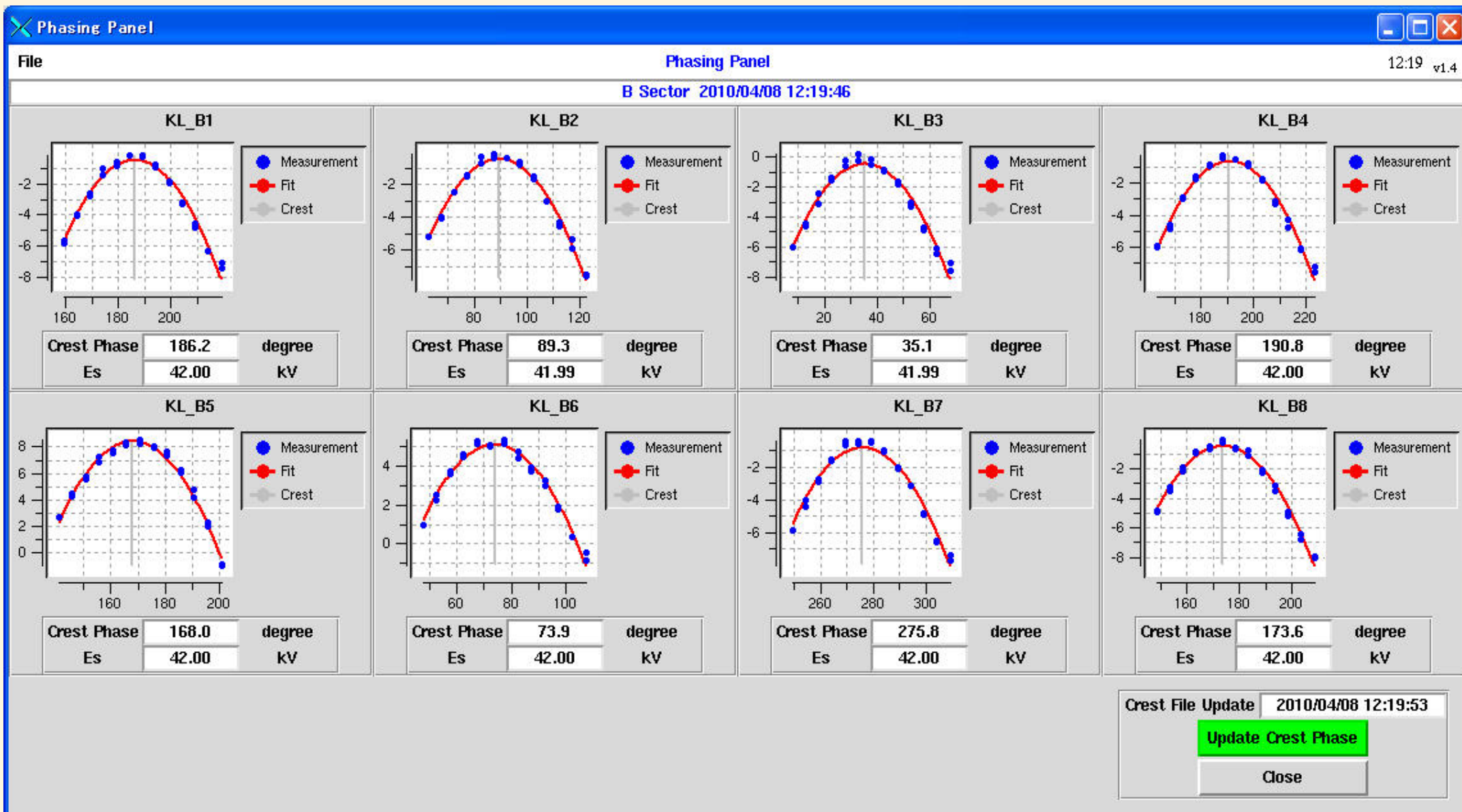
Schematic Diagram of the RF System



Crest Phase Calibration

- ◆ **Each power source with slow phase shifter**
 - ❖ **Energy measurement scanning the phase shifter**
 - ✧ Primitive but reliable, while there were several methods
 - ✧ Chicken and egg issue exists on bootstrap
 - ◆ If no beam at the end, no measurement possible
 - ❖ **Every several month at least after the long shutdown**
 - ✧ Automated measurement takes ~2hours for 60 sources
 - ❖ **Result is saved as a reference to other software**
 - ✧ If the voltage was changed, nominal crest change is applied (1kV => ~8degree) (to be measured later)

Typical Automated Phase Calibration



Two-bunch Energy Equalization

◆ Two bunch in a pulse

❖ Energy compensation

✧ Depending on beam charge

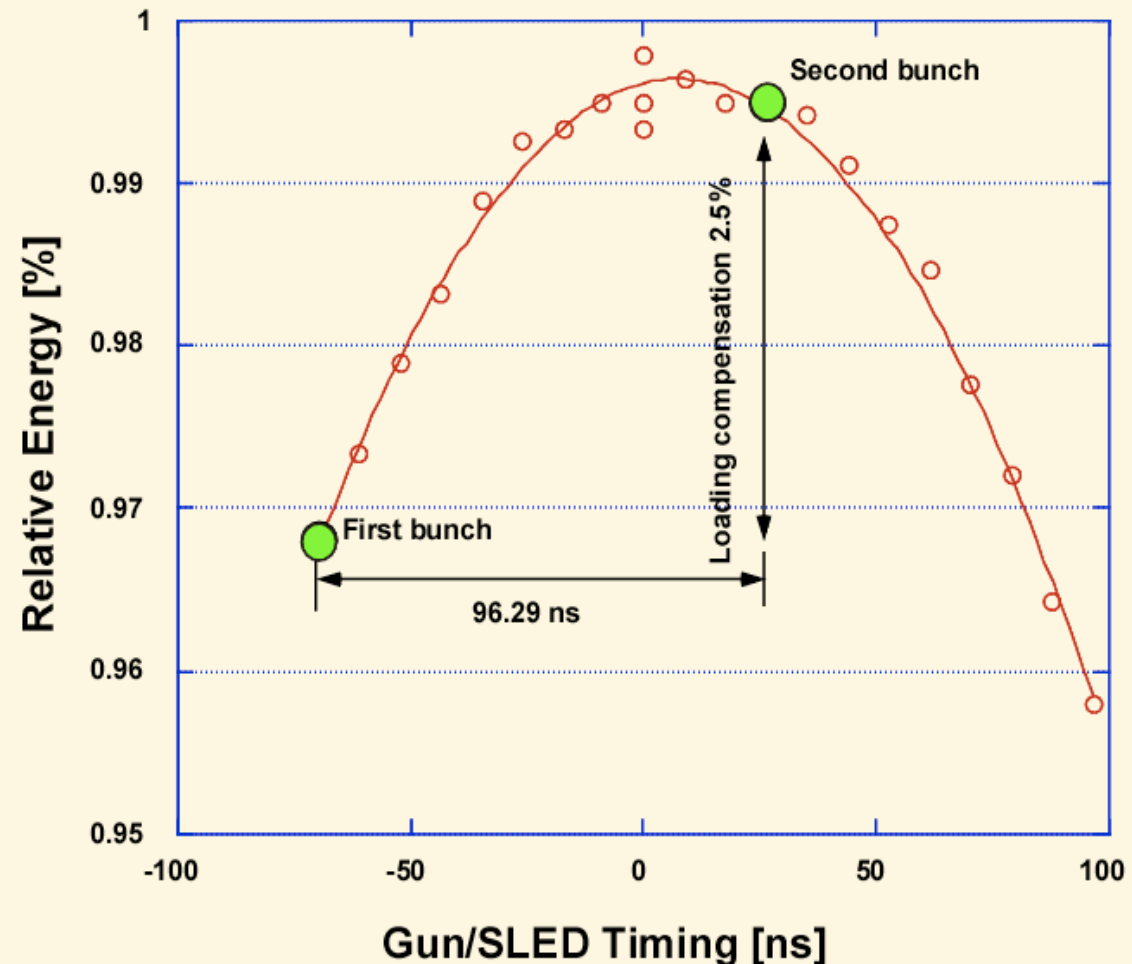
◆ Fast timing adjustment

❖ Automated measurement

❖ Same procedure

✧ As crest phase measurement

✧ With ns timing as a variable



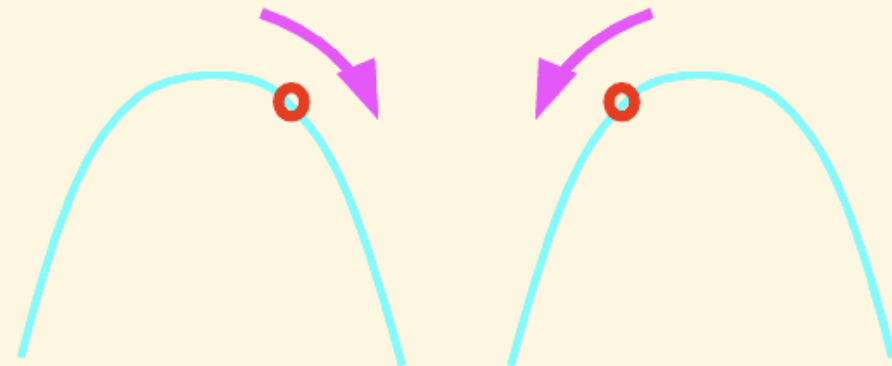
Energy Profile

◆ 8 driver klystrons with fast phase shifters

- ❖ Each manage ~8 high power klystrons
- ❖ Define the overall energy profile
- ❖ With Small phase angle (from the crest)
 - ✧ Energy spread compensation depending on beam charge

◆ 4 klystrons with fast phase shifters

- ❖ Forming two energy-knobs to adjust the energies
 - ✧ Before the arc and at the end of the linac
- ❖ Not to enlarge the energy spread
 - ✧ Two klystrons are grouped

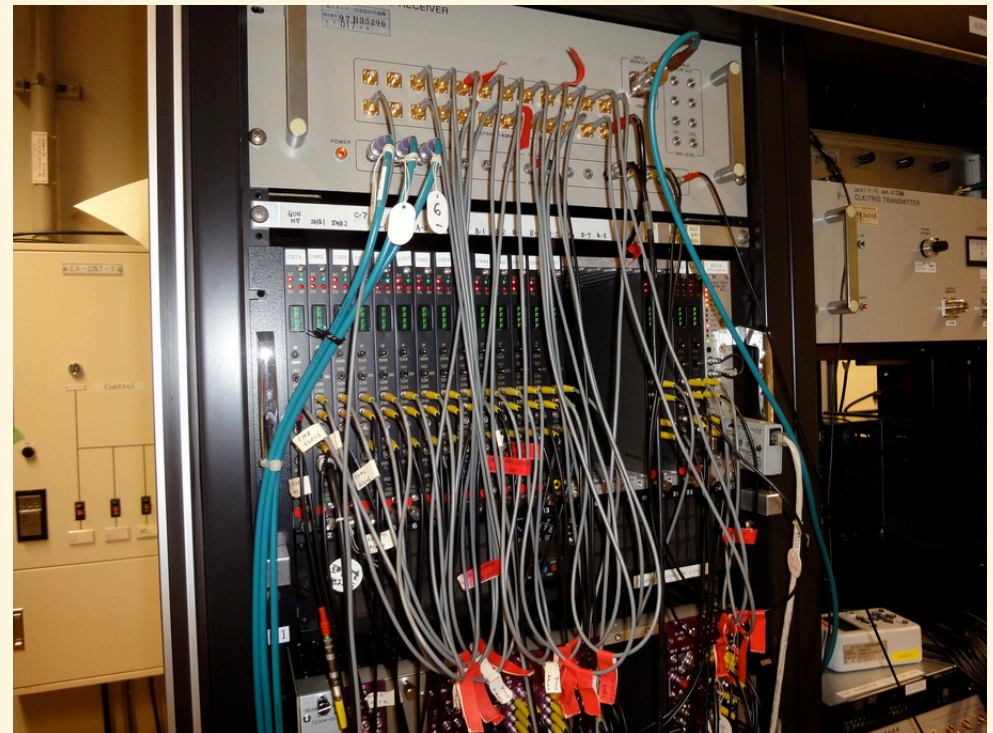
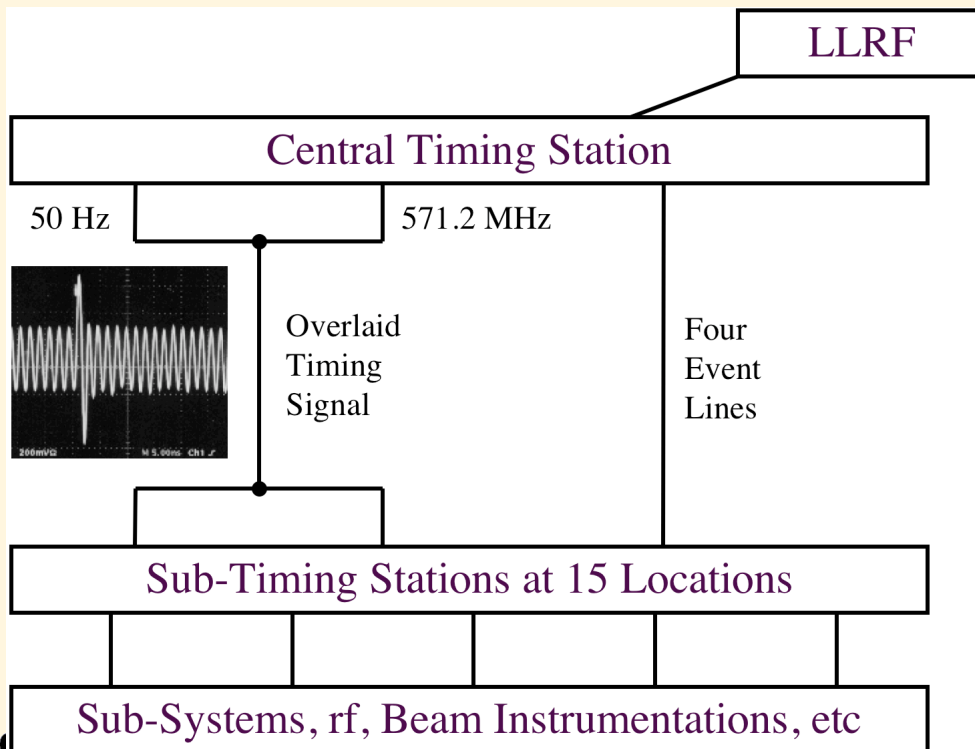


Fast Controls

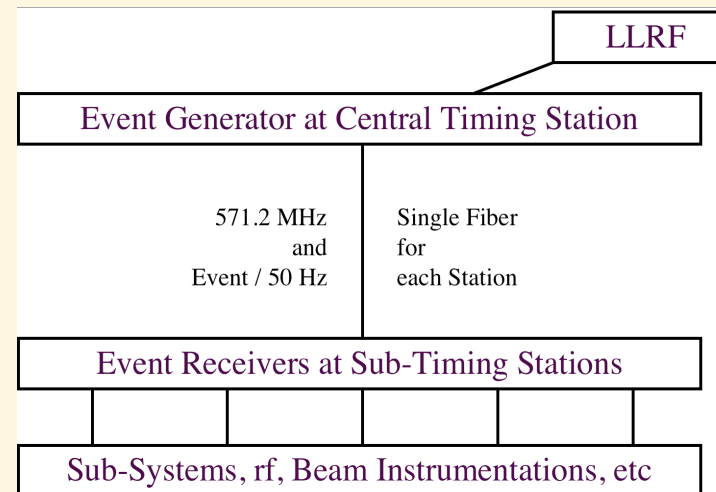
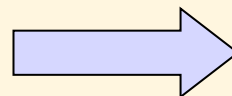
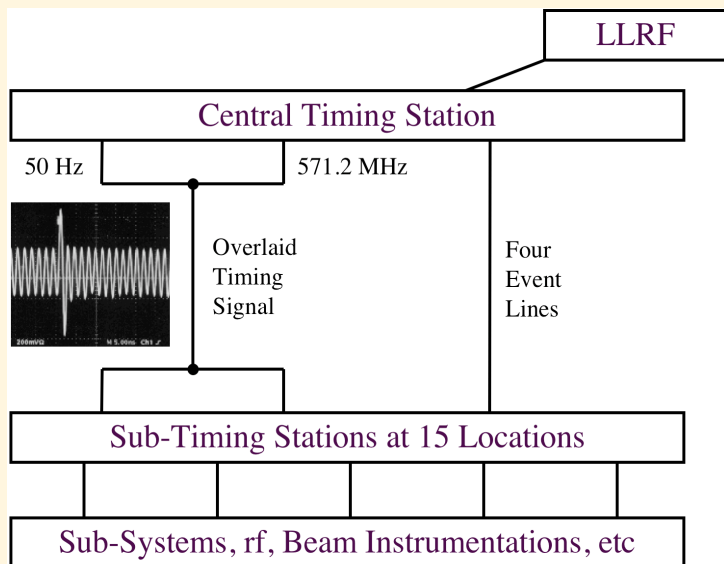
- ◆ **~150 parameter switching within 20ms**
 - ❖ **Keep most of magnet fields with compatible optics**
 - ❖ **Control Ilrf to change energy**
- ◆ **Pulsed magnet triggers and delays**
 - ❖ **Delays to keep the constant rate for certain power-supplies**
- ◆ **LLRF phases and delays**
- ◆ **Gun voltage and fine delay**
- ◆ **Interface to bucket selection, etc**
- ◆ **(Ethernet-based controls are not reliable enough?)**
- ◆ **FPGA and fiber-optic RocketIO might be the way ?**

Old timing system

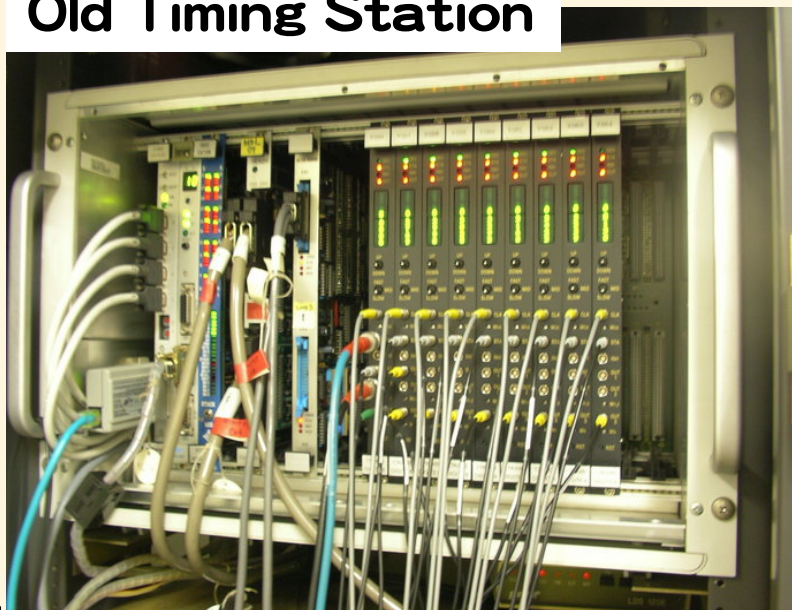
- ◆ Distribution of RF and trigger fiducial
- ◆ Many delay modules (~200)
- ◆ Did not need fast controls
- ◆ KEKB ring has additional slow (μs) events (8bits)



Timing System



Old Timing Station



New Event Receiver Station with 14 outputs



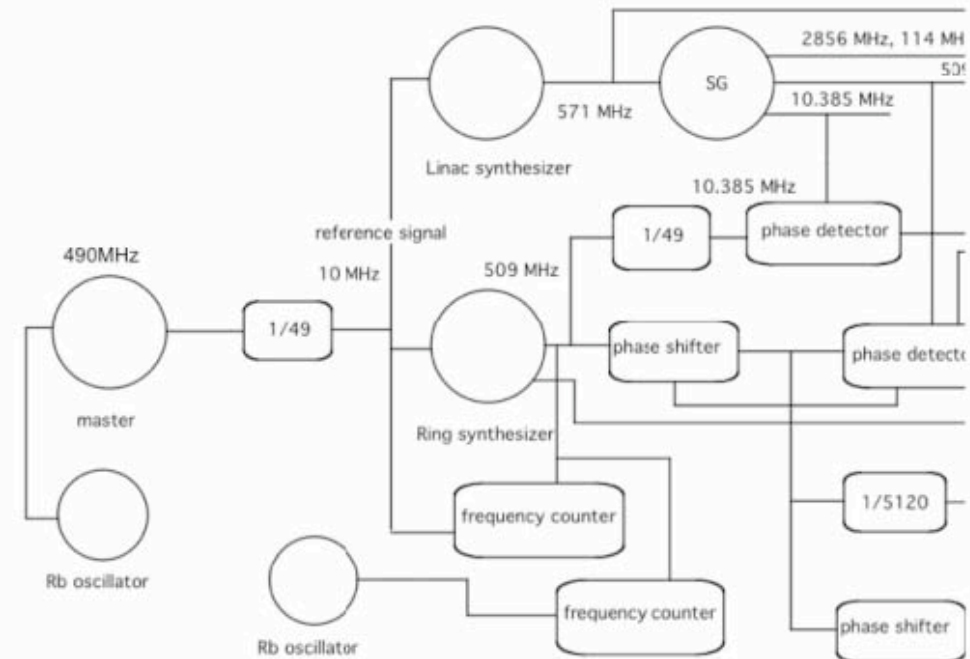
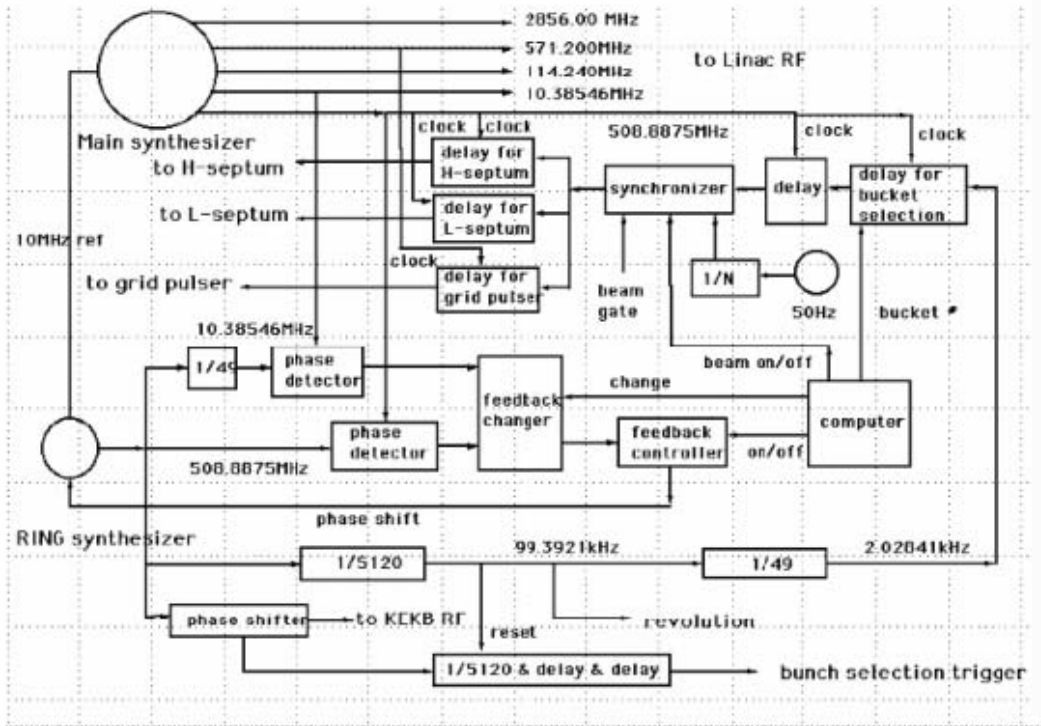
Ring - Linac

◆ Separate oscillators

- ❖ Dispersion measurement at ring
- ❖ Phase lock / release at high (rf) / low (revolution) frequencies

◆ Precision < 30ps

- ❖ Small aperture at the collision point

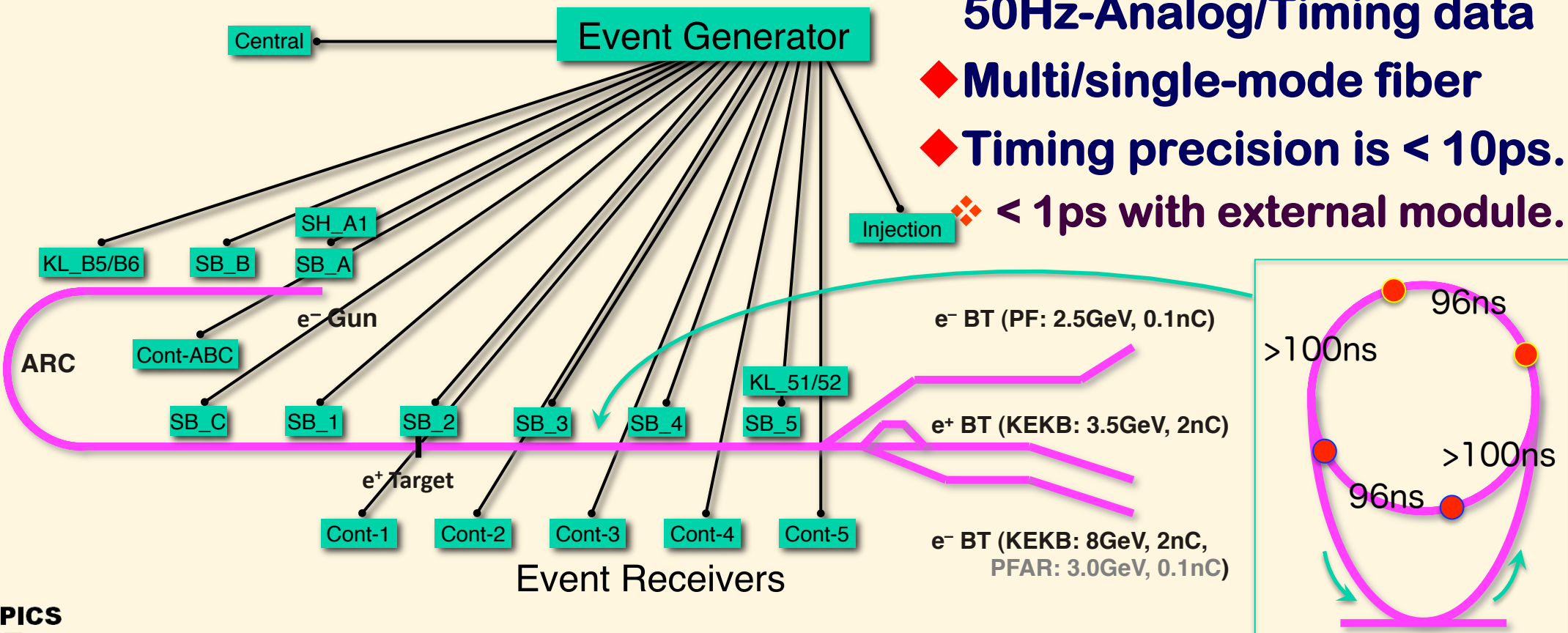


Event System

- ◆ **Simultaneous Injection**
 - ❖ to KEKB-HER, KEKB-LER, and PF, PF-AR
 - ❖ 2.5GeV to 8GeV, 0.1nC to 10nC
- ◆ **Stable stored beam current at three rings**
 - ❖ Should improve collision tuning with Crab cavities
 - ❖ Should improve the quality of experimental data at PF
- ◆ **Fast switching of many device parameters**
 - ❖ In 20ms / 50Hz
 - ❖ Should be reliable because beam power is much different
- ◆ **MRF Series 230 Event Generator / Receiver**
 - ❖ VxWorks 5.5.1, MVME5500 (Originally with RTEMS but...)
 - ❖ Timing precision less than 10ps is sufficient (TD4 provides 3ps)
 - ❖ Multi-mode fiber, and single-mode fiber for longer distance

Event System for Simultaneous Injection

- ◆ MRF's series-230 Event Generator / Receivers
- ◆ VME64x and VxWorks v5.5.1
- ◆ EPICS R3.14.9 with DevSup v2.4.1
- ◆ 17 event receivers up to now
- ◆ 114.24MHz event rate, 50Hz fiducials
- ◆ More than **hundred** 50Hz-Analog/Timing data
- ◆ Multi/single-mode fiber
- ◆ Timing precision is $< 10\text{ps}$.
◆ $< 1\text{ps}$ with external module.

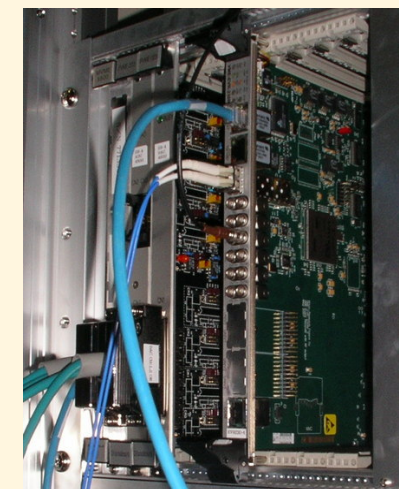
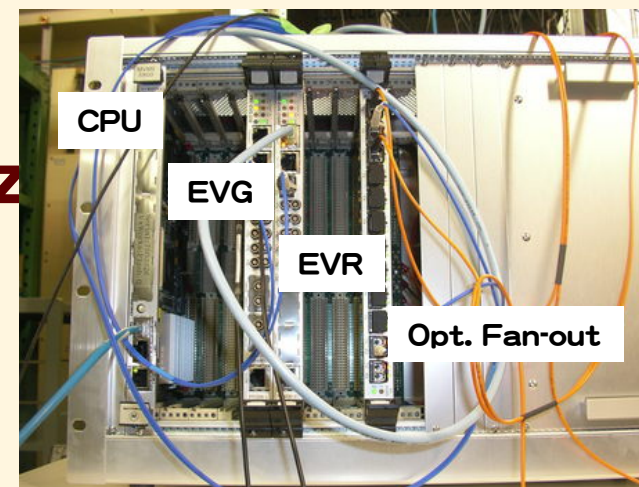


Linac Event System

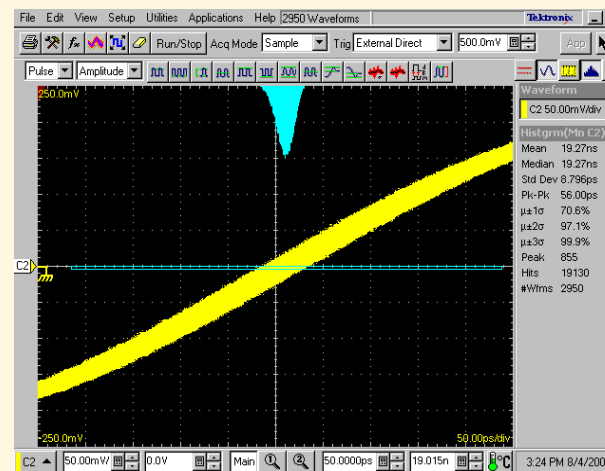
◆ Satisfies the requirements

- ❖ Event rate : 114.24MHz (bit rate : ~2.3GHz)
- ❖ Fiducial rate : 50Hz
- ❖ Timing jitter (Short term) : ~8ps
- ❖ No. of defined events : ~50
- ❖ No. of receiver stations : 17
- ❖ No. of Fast parameters : ~130

- ❖ CPU stopped 4 times since Sep.2008 for 18 stations

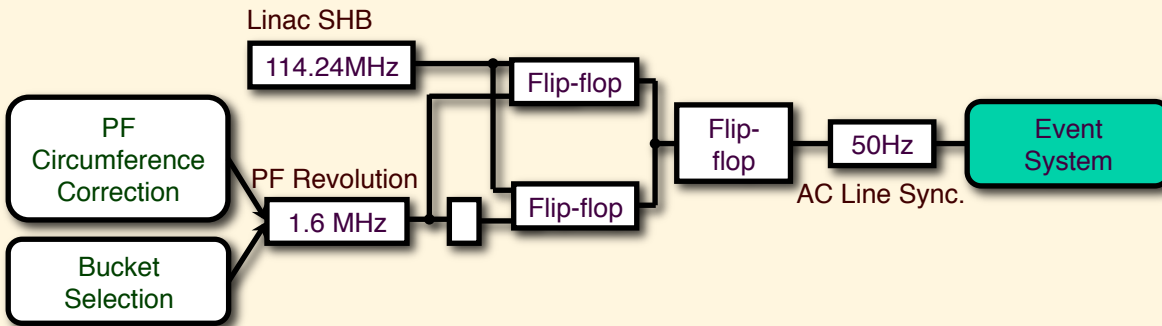


EVR & LLRF

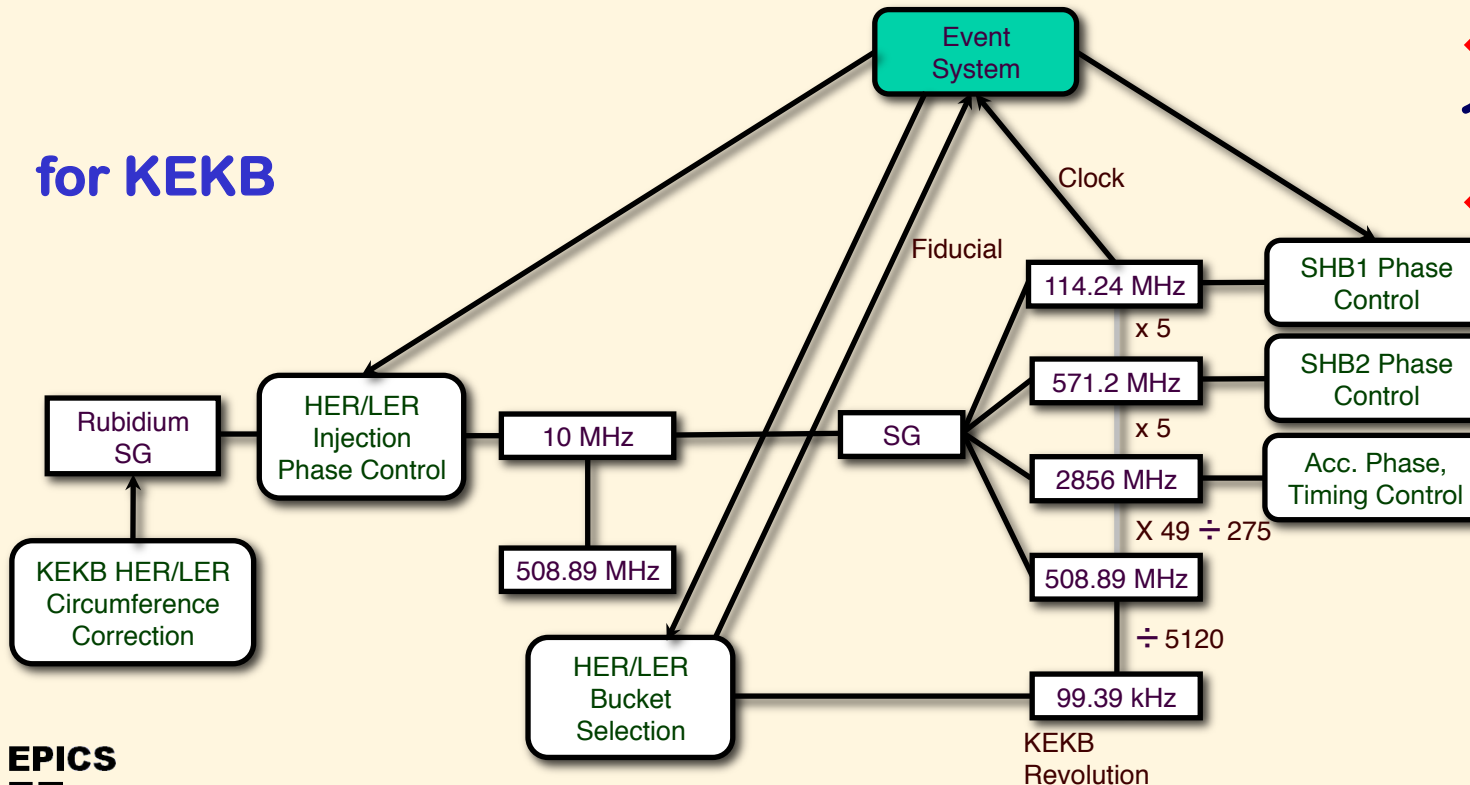


Synchronization Scheme

for PF



for KEKB



◆ Synchronization Req.

❖ KEKB : < 30ps

❖ PF : < 300~700ps

◆ Linac rf is Synchronized to KEKB rf

◆ Event Clock is 114.24MHz

◆ We have to manage

❖ Circumference compensation

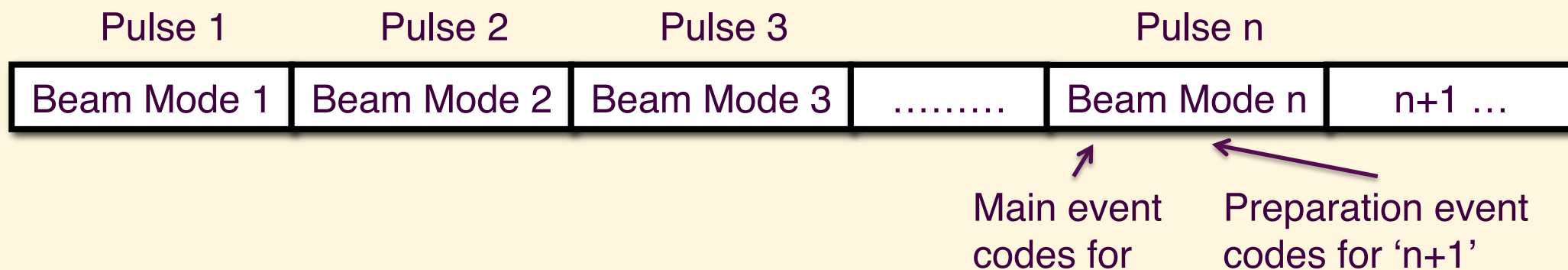
❖ Bucket selection

❖ Injection phase controls

Beam bucket selection at KEKB

- ◆ **Beam pattern restrictions for beam intervals**
- ◆ **Select bucket where the stored current is low, partially independent on the fast timing**
 - ❖ **KEKB has 5120 buckets at 509MHz**
 - ❖ **Common frequency between Linac – Ring, 10.38MHz corresponds to 49 buckets (96ns)**
 - ❖ **We can select any buckets if we wait maximum of $5120 \times 96\text{ns} = \sim 500\mu\text{s}$**

Beam Mode Pattern Generation



- ◆ Every pulse (every 20ms) corresponds to a beam mode
- ◆ 10 different beam modes are defined (for KEKB e+, etc)
- ◆ One beam pulse may contain several event codes
 - ❖ At least one main code and a preparation code for the next pulse
- ◆ About 50 event codes are defined
 - ❖ Some events correspond to many functions, and others to specific devices
- ◆ Beam pattern buffer length (n) can be 2 to 500 (20ms x 500 = 10 seconds)
- ◆ A new pattern can be loaded at the end of the previous pattern
 - ❖ Otherwise, the pattern repeats forever.
- ◆ Main events and preparation events in sequence
 - ❖ Main events trigger timing signals
 - ❖ Preparation events trigger software to exchange analog and delay parameters

Event Manipulation

Human Operator

Injection Programs

Arbitrate and Generate Beam Mode Pattern (in PythonTk)
considering priorities of the rings
equalizing pulsed power supply interval
in 4 arrays (waveforms) of length 2 (40ms) to 500 (10s)
each element corresponds to a 20-ms time slot and a beam mode

Generate Events for the Next 20-ms Time Slot (in Event Generator)
reading two consecutive elements from the beam mode pattern
generate several events for the next pulse
generate preparation events for the next after next

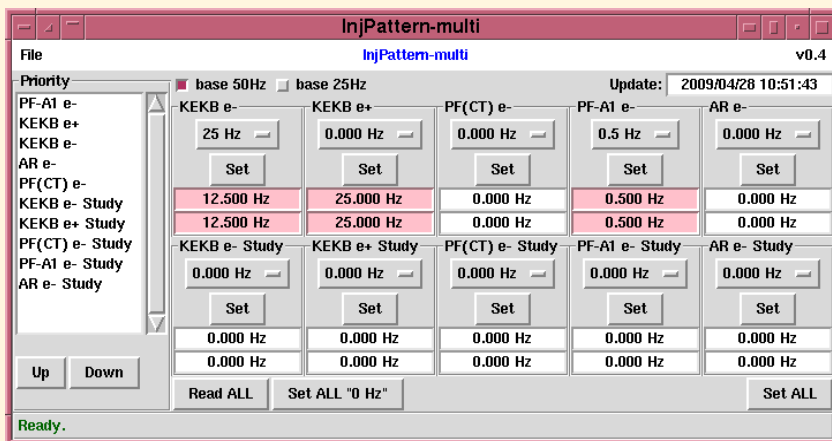
Generate Signals based on Received Events (in Event Receiver)
generate pulsed signals as prepared in the previous time slot
program the signals (enable/disable, delays, etc) for the next
start to generate analog signals for the next

Beam Mode Pattern Generators

◆ Pattern panel arbitrates requests

- ❖ From downstream rings with priorities, or human operators
- ❖ There are several pattern rules due to pulse device features and limitations
- ❖ Pattern arbitrator software was written in scripting languages to meet daily changes during the commissioning stage

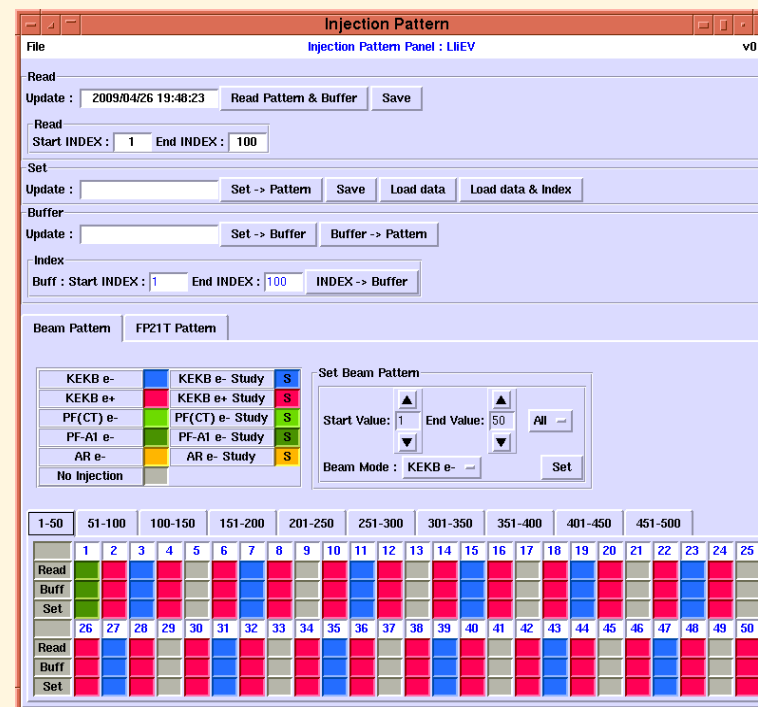
Remote controlled automatic pattern arbitrator



❖ Typical operation in 2009.

- ❖ ~25Hz for KEKB LER
- ❖ ~12.5Hz for KEKB HER
- ❖ ~0.5Hz for PF

Manual pattern generator



Parameters

◆ Parameters switching via Event system

- ❖ LLRF phase/timing : 14x4
- ❖ HP RF timing : ~60
- ❖ Gun voltages, picosecond delay : 4
- ❖ Pulsed magnets/solenoid : 14
- ❖ Injection phase : 2
- ❖ Bucket selection : 2
- ❖ BPM : ~100x3

◆ Basically sufficient for fast beam mode switching

◆ More parameters coming

◆ Integrity monitors

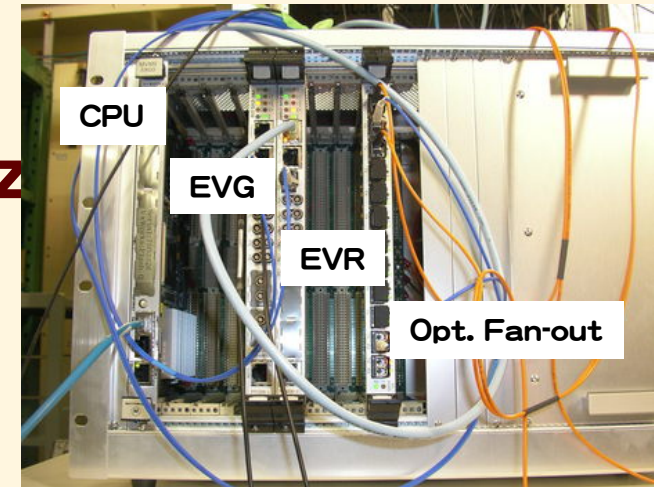
◆ Improved slow beam feedback, fast feedback, etc.

Linac Event System

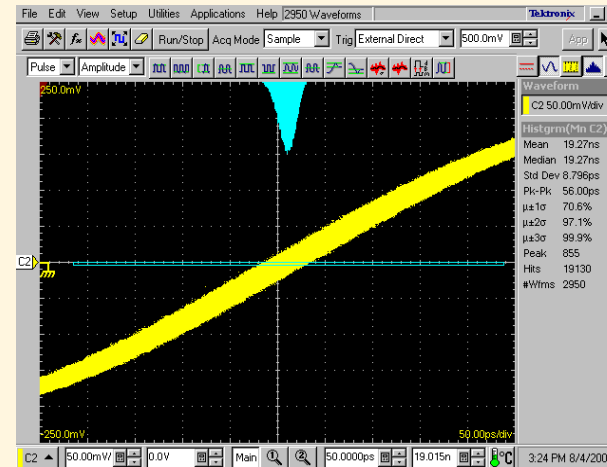
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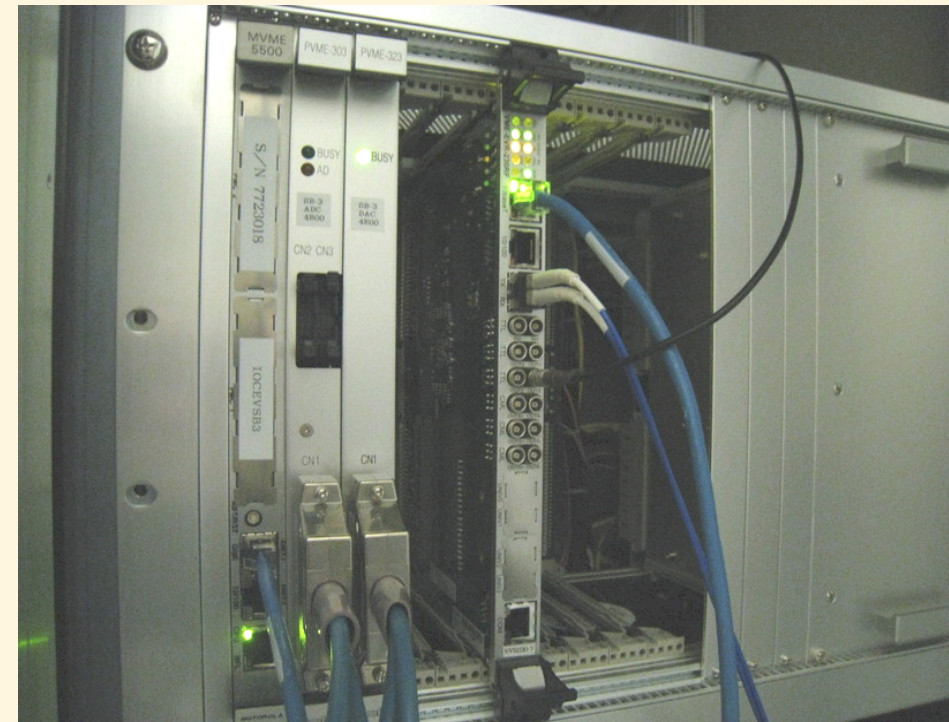
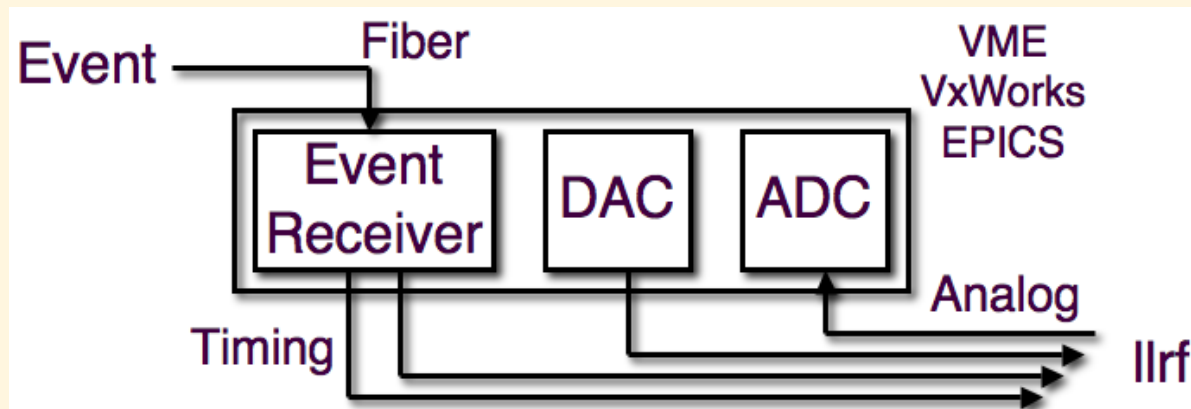


EVR & LLRF



LLRF

- ◆ LLRF Timing/analog signals are essential for absolute energy, energy spread, and dual-bunch energy equalization
- ◆ Signals are switched pulse-by-pulse
- ◆ Value changes are triggered by a preparation event
- ◆ Driver klystrons (SB), energy tuner klystron (KL), and sub-harmonic bunchers (SH) are managed by the event system



More Measurement Technique

◆ Switching between Four Rings

- ❖ Challenging to improve beams during operation

◆ Event-based Controls may Help More

- ❖ No-destructive measurements with four beams

- ❖ Stealth (used beam-pulse) measurements

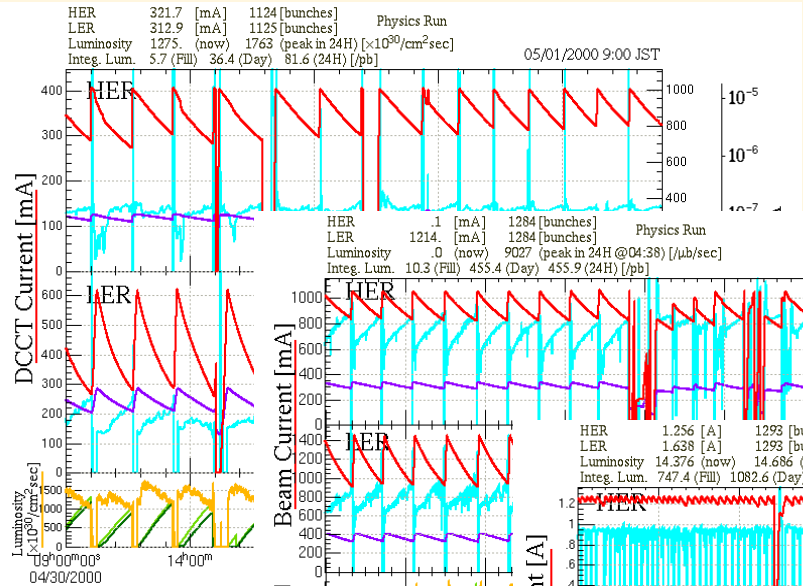
- ✧ With beam deflector

- ❖ Dithering pulse-by-pulse

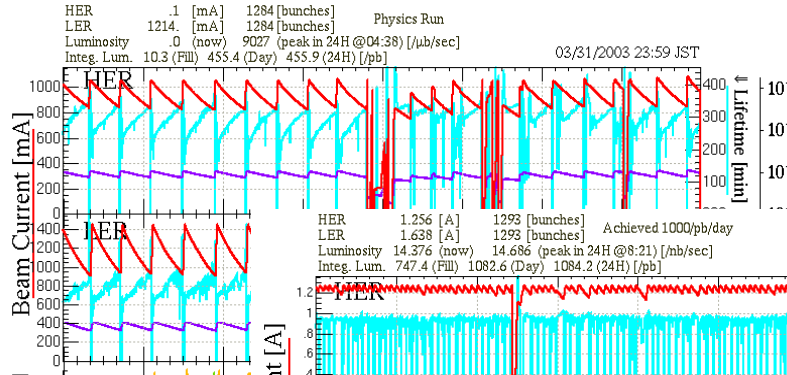
- ✧ If very good resolution was achieved



KEKB Operation Improvement (base of SuperKEKB)

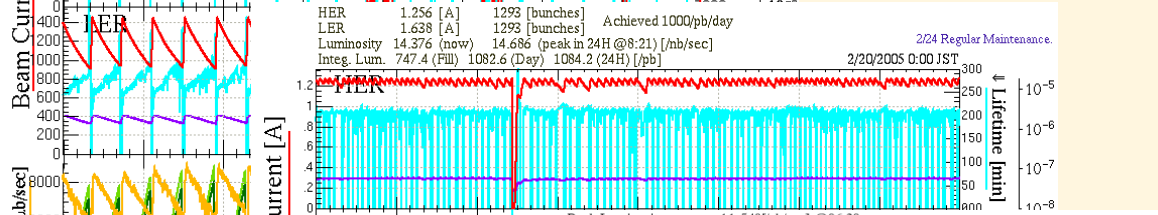


May.2000

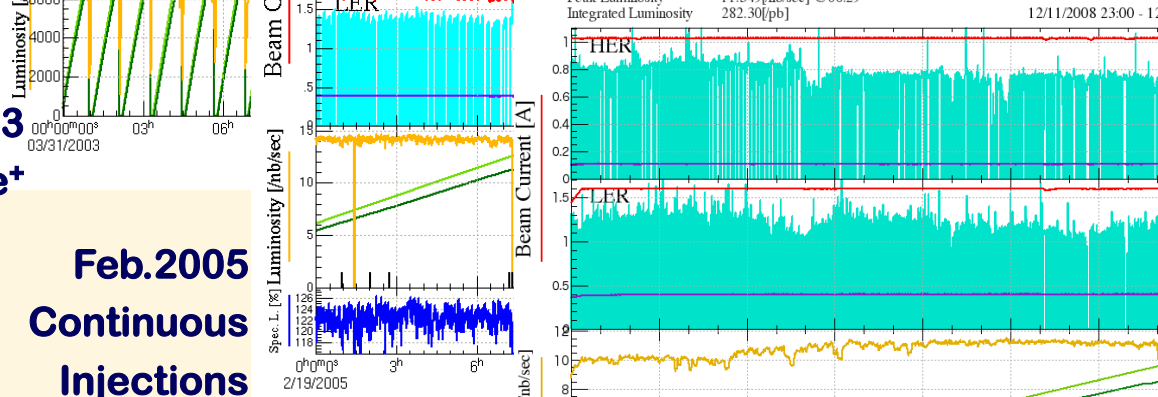


Apr.2003

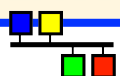
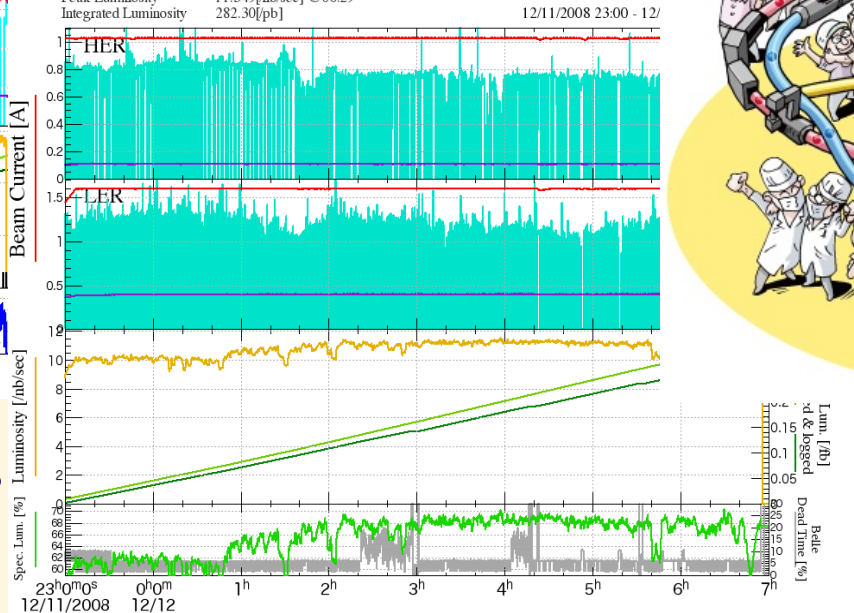
Dual Bunch e^+



Feb.2005
Continuous
Injections



Dec.2008
Crab Cavities and
Simultaneous Injection



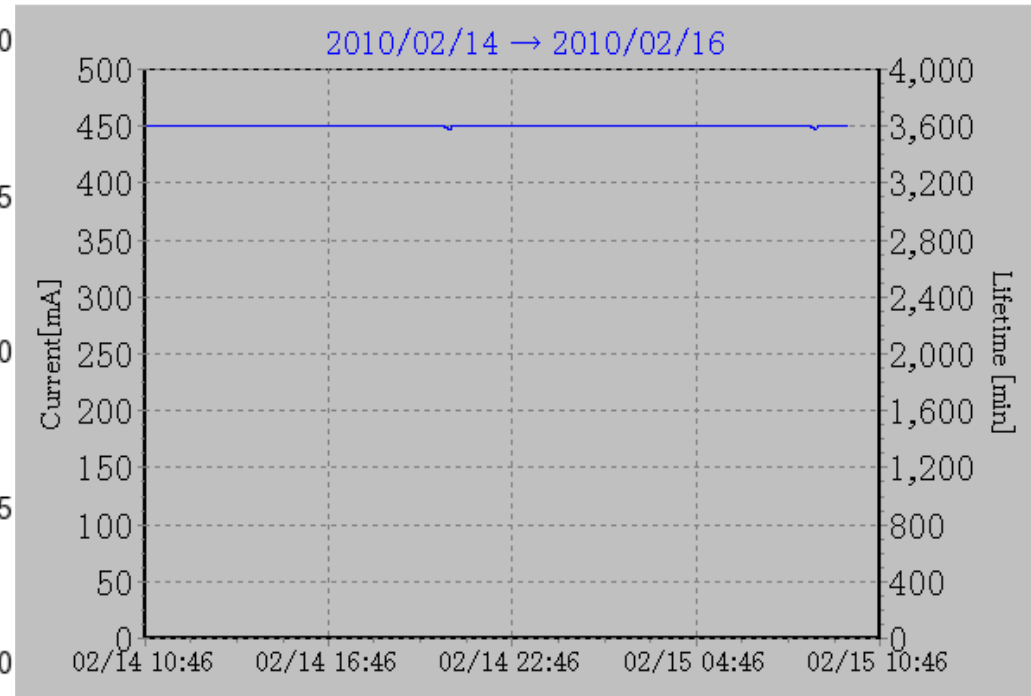
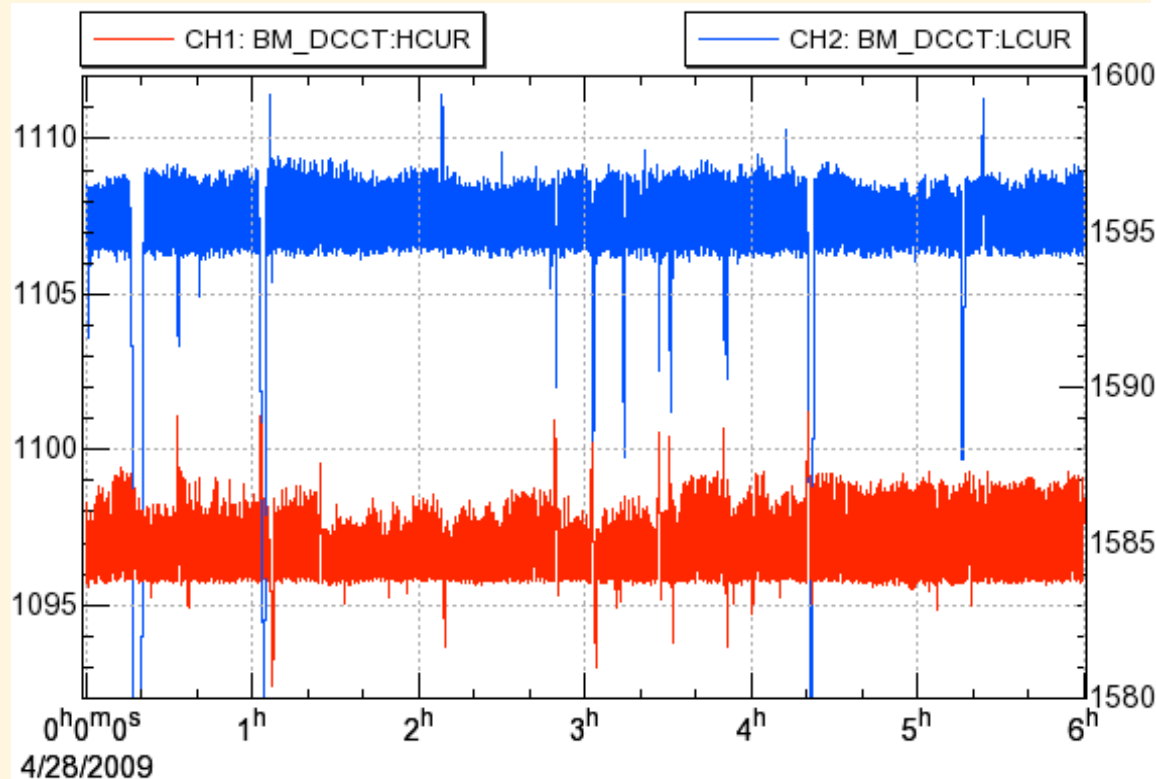
Top-up Beam Currents at Storage Rings

◆ Beam currents were kept

- ❖ KEKB 1mA (~0.05%)
- ❖ PF 0.05mA (~0.01%)

Time: 2010/02/15 09:46:27
 Beam Current: 449.9 [mA] I*τ : 0.0 [A·min]
 Lifetime : 0.0 [hours] Vacuum : 2.1E-8 [Pa]
 Idt: 7000.0 [A·h]

BL01 CLOSE	BL02 OPEN	BL03 OPEN	BL04 OPEN
BL05 OPEN	BL06 OPEN	BL07 OPEN	BL08 OPEN
BL09 OPEN	BL10 OPEN	BL11 OPEN	BL12 OPEN
BL13 OPEN	BL14 OPEN	BL15 OPEN	BL16 OPEN
BL17 OPEN	BL18 OPEN	BL19 OPEN	BL20 CLOSE
BL21 OPEN	BL22	BL23	BL24
BL25	BL26	BL27 OPEN	BL28 OPEN



Towards SuperKEKB

◆ Nano-beam scheme at SuperKEKB

❖ Requires low-emittance large current beams

✧ Photo cathode RF gun for e⁻ 7GeV, 5nC

✧ New capture section and new damping ring for e⁺ 4GeV, 4nC

✧ 40 times more luminosity

❖ Design of damping ring

✧ Selection of RF

✧ Selection of harmonic number

❖ Injection to PF-AR

✧ Common BT to KEKB

◆ PF-AR Injection needs 5-10 minutes

◆ Shorter life time of 10min at SuperKEKB

KEKB		SuperKEKB	
e ⁻	e ⁺	e ⁻	e ⁺
8GeV	3.5GeV	7GeV	4GeV
1nC	1nC	5nC	4nC
100 μ m	2000 μ m	20 μ m	10 μ m
2bunch	2bunch	2bunch	2bunch

Damping ring injection for SuperKEKB

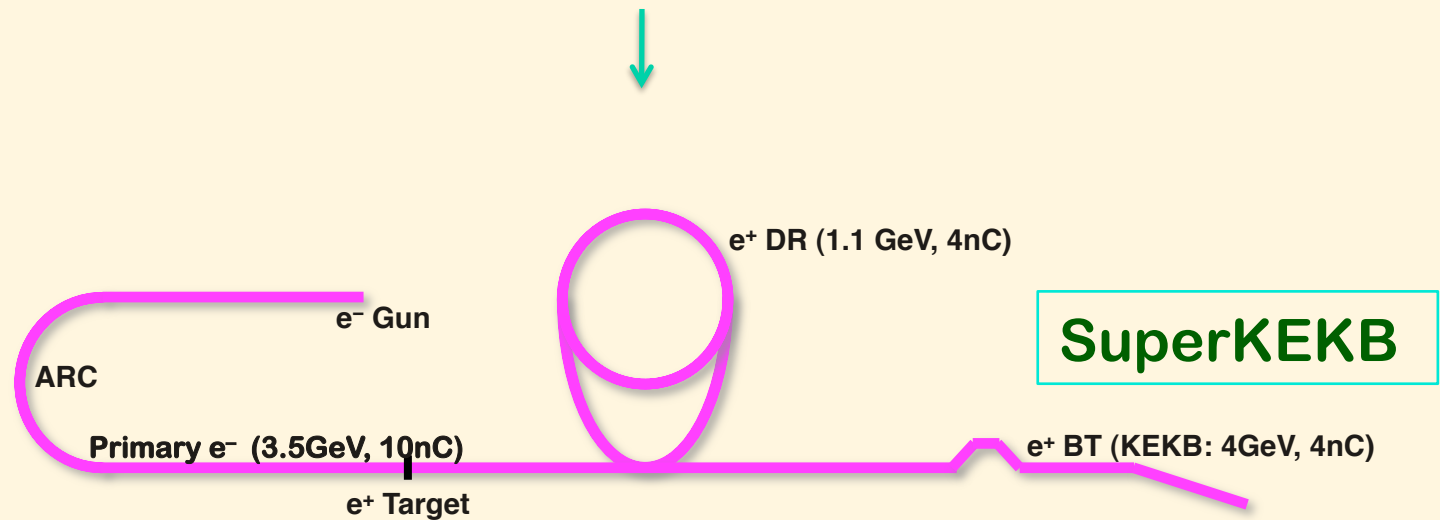
◆ Accommodate 2 bunches 2 pulses

For e+ 25Hz e- 25Hz

Inj.	D.R.	Ext.
e+ 1	e+ 1	
e- 2	e+ 1	e- 2
e+ 3	e+ 3,1	e+ 1
e- 4	e+ 3	e- 4
e+ 5	e+ 5,3	e+ 3
e- 6	e+ 5	e- 6



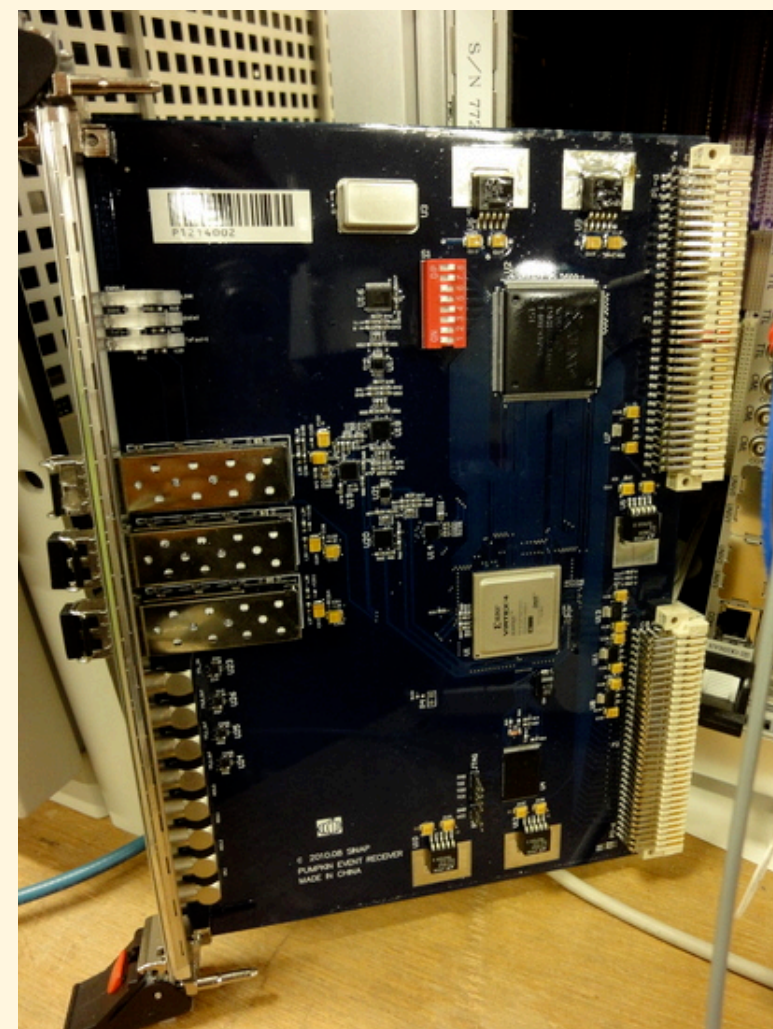
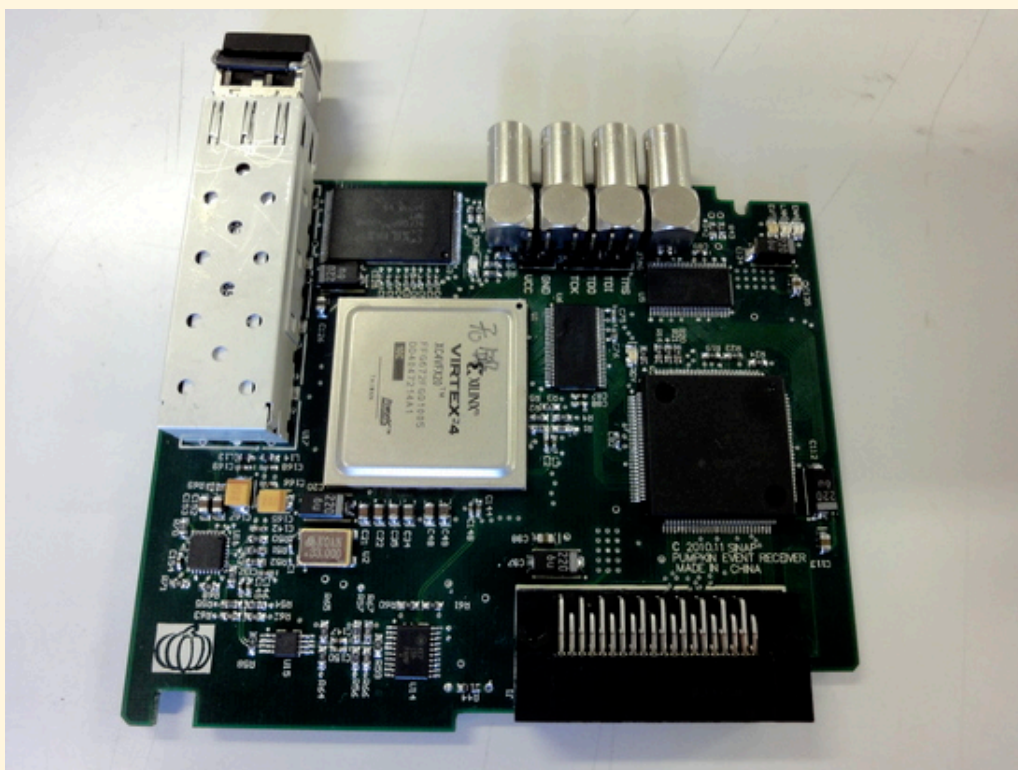
KEKB



SuperKEKB

Development of EVR/PLC at SSRF

- ◆ For Yokogawa FAM3 PLC with F3RP61 linux CPU
- ◆ Prototype in 2010
- ◆ Production version at Oct.2011
- ◆ Will simplify the additional stations



SuperKEKB timing software upgrade

- ◆ **Basically the same configuration as KEKB**
 - ❖ Intelligent panels – pulse-by-pulse EVG Sequences – EVR PV databases
- ◆ **Need to upgrade to newer device driver/support with new register mapping**
 - ❖ Under evaluation with newer firmware/EPICS support
- ◆ **Need more coordinated beam pattern generation**
 - ❖ Need dependencies between pulses
 - ❖ Need to decide whether to change phases at DR
- ◆ **Need synchronization to laser rf gun**
 - ❖ Laser based on local oscillator, need PLL and stabilization strategy
- ◆ **Possible more addition of event receivers to BT and Rings**
- ◆ **Possible upward links for bucket selection data (SSRF or MRF)**
- ◆ **Linux-based device support for EVR/PLC from SSRF on F3RP61**
 - ❖ Should be simple (?) based on standard FAM3 bus access

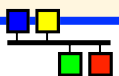
Summary

- ◆ Simultaneous injections to three rings (KEKB HER/LER and PF) achieved
- ◆ Challenging for four rings (incl. PF-AR) with a damping ring
- ◆ Event-based controls : another layer of controls bellow EPICS slow controls
- ◆ <http://www-linac.kek.jp/cont/epics/event/>
- ◆ There should be much room to establish further controls utilizing beam monitors, rf monitors, and more
 - ❖ With Phronesis (Ability to understand the universal truth, Greek word) we can enjoy our accelerator more



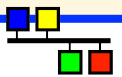
Thank You

谢谢您



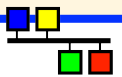


Thank you





Backup



Parameters

◆ Parameters switched via event system

❖ LLRF phase/timing : 14x4

- ✧ Overall energy profile, dual-bunch energy equalization, final energy adjustment

❖ HP RF timing : ~60

- ✧ Energy profile and backup management

❖ Gun voltages, picosecond delay : 4

- ✧ Beam charge selection, dual bunch selection, bunching

❖ Pulsed magnets/solenoid : 14

- ✧ Beam transport selection, orbit controls, positron focusing

❖ Injection phase interface : 2

❖ Bucket selection interface : 2

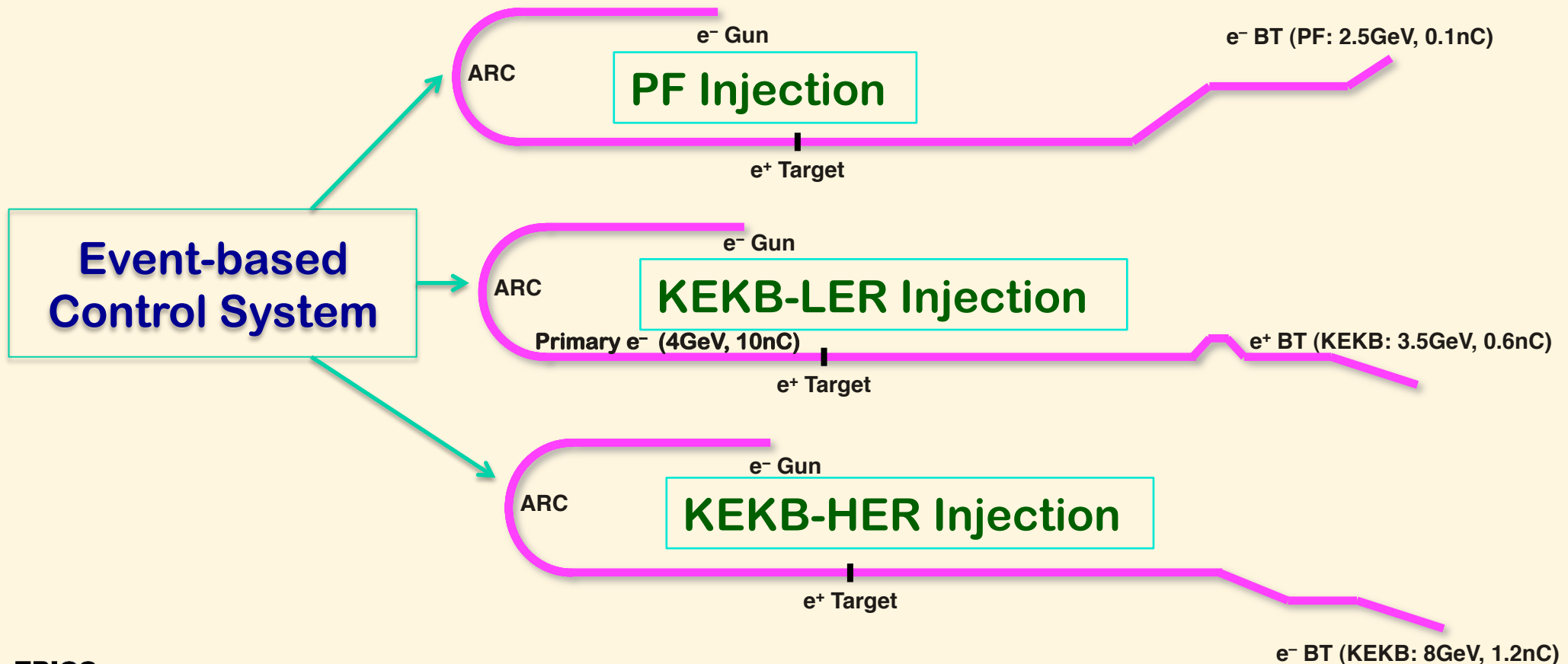
❖ BPM : ~100x3

◆ Sufficient for fast beam mode switching

◆ Integrity monitors soon

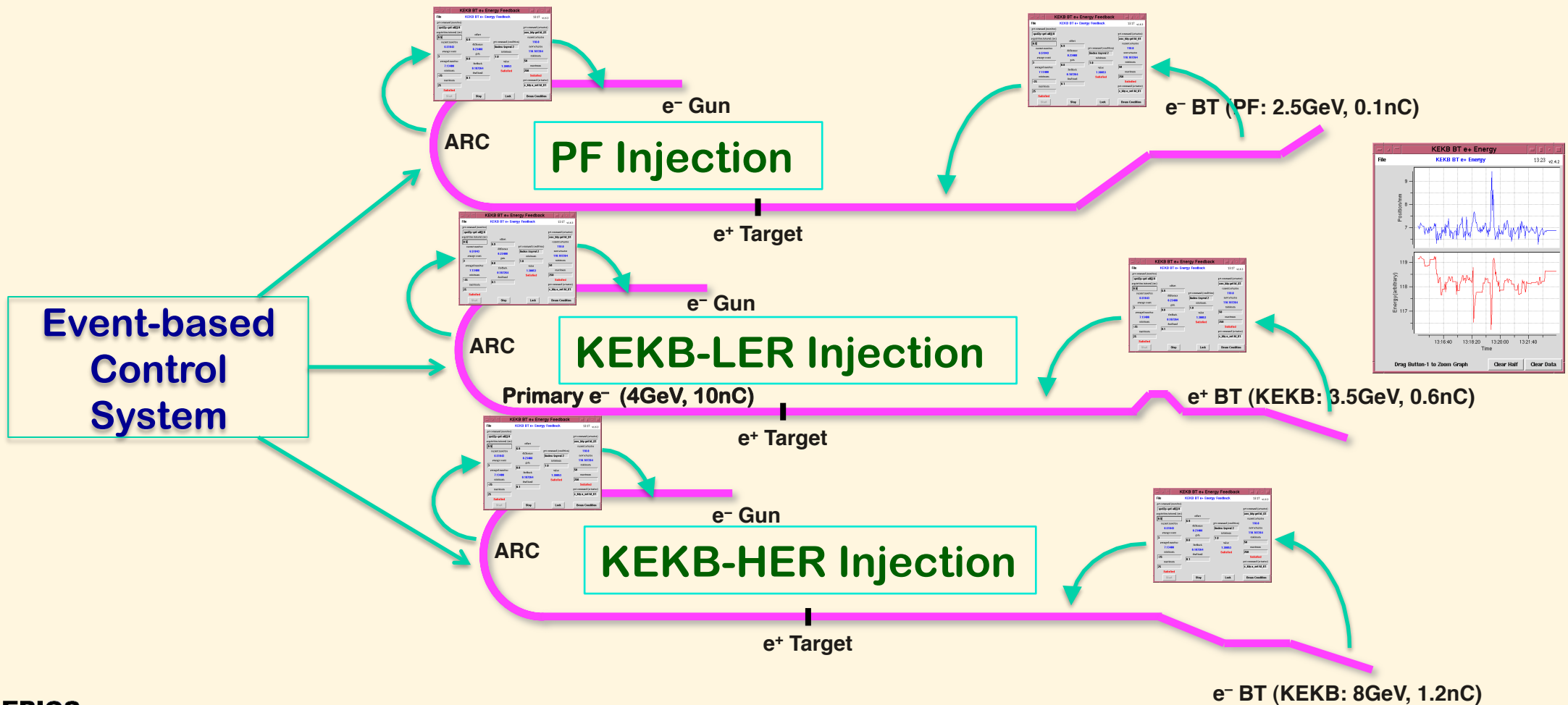
Three Virtual Accelerators

- ◆ Controls and instrumentations are essentially mode-dependent, and mutually independent
- ◆ Selecting a real machine out of three virtual machines
 - ❖ Managing three parameter sets (four under SuperKEKB environment)



Three-fold Independent Closed Loops

- ◆ Feedback loop software act on one of three virtual machines
 - ❖ Managing independent parameter sets



For SuperKEKB Complex

◆ Slightly More Complicated Conditions with DR

- ✧ Harmonic number of SuperKEKB-MR (509MHz) is 5120
- ✧ Common frequency between Linac-MR is 10.38MHz (49 buckets, 96ns)
- ✧ DR should have common frequency, RF chosen to be 509MHz
- ✧ 2x2 bunches, bunch separation of 49-bucket, kicker rise/fall time of 100ns
- ✧ Jitter (wait-time) of HP modulator (50Hz) must be $< \sim 2\text{ms}$
- ❖ Harmonic number of DR was chosen to be 230

◆ In order to Select All the Buckets in SuperKEKB MR

- ❖ Active (Pulse-to-pulse) LLRF controls necessary at linac
 - ✧ Better LLRF monitor is required
- ❖ Dependency between pulses increases

◆ For PFAR Injection

- ❖ Positron have to be used to share the beam-transport
- ❖ Independent circumference controls will interfere
 - ◆ PF can use 2.5GeV electron with accidental synchronization ($< \sim 300\text{ps}$)

✧ More investigation underway

Event System Consideration for SuperKEKB

◆ Possibly Cascaded Event Systems

- ❖ For damping ring, main ring and other sub-systems

◆ New firmware with new register map

- ❖ For newer device support software in EPICS community
 - ✧ Several local modification already, want to synchronize with other institutes
- ❖ Several institutes in Asia may use CompactPCI as well
 - ✧ Whether PLC version can use the same environment??

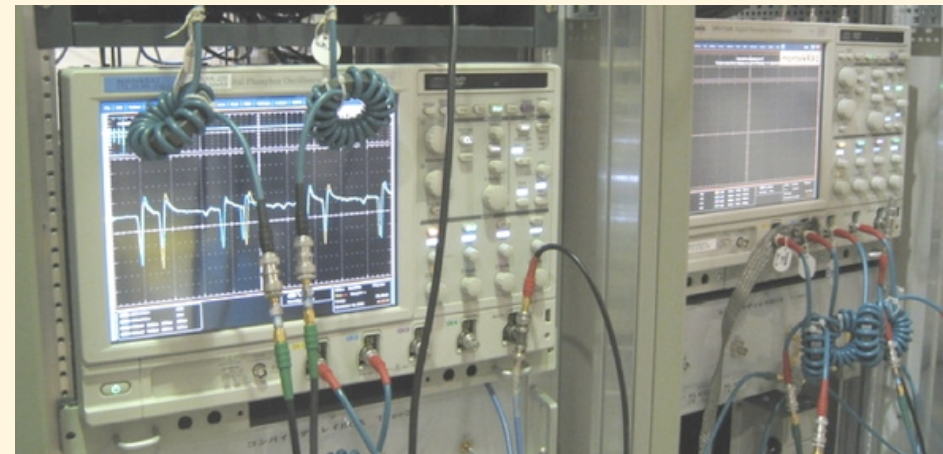
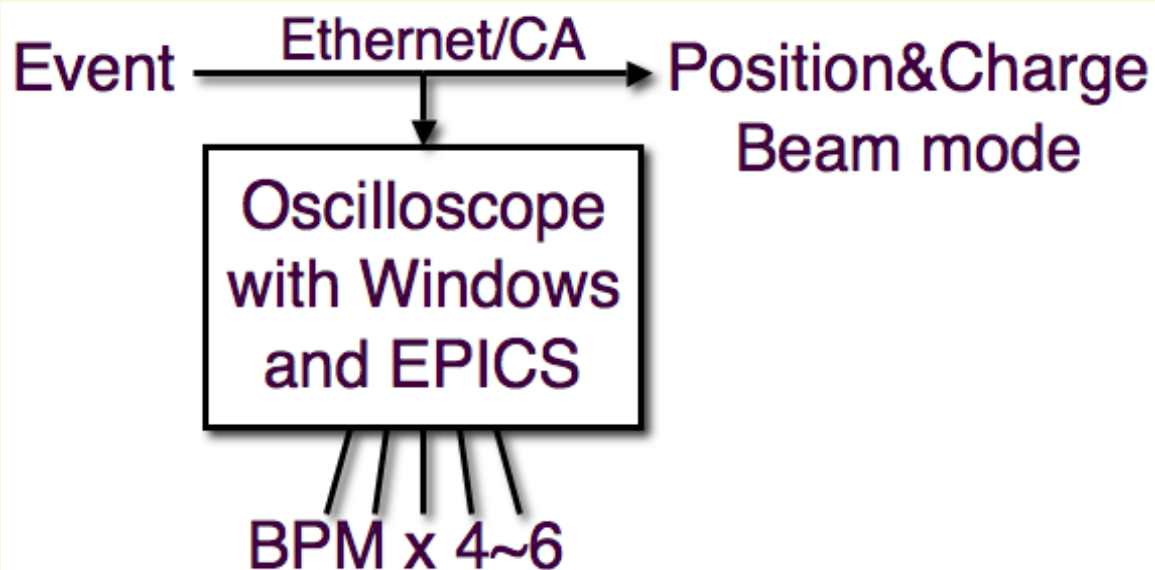
◆ Several fast control projects for SuperKEKB

- ❖ Several embedded systems with PLC EVRs for RF stations
- ❖ Bucket selection to cover both damping and main rings
 - ✧ In KEKB, separate system was used and selection signal was used as AC to EVG
- ❖ Fast feedbacks in Linac and in main ring

◆ Several others

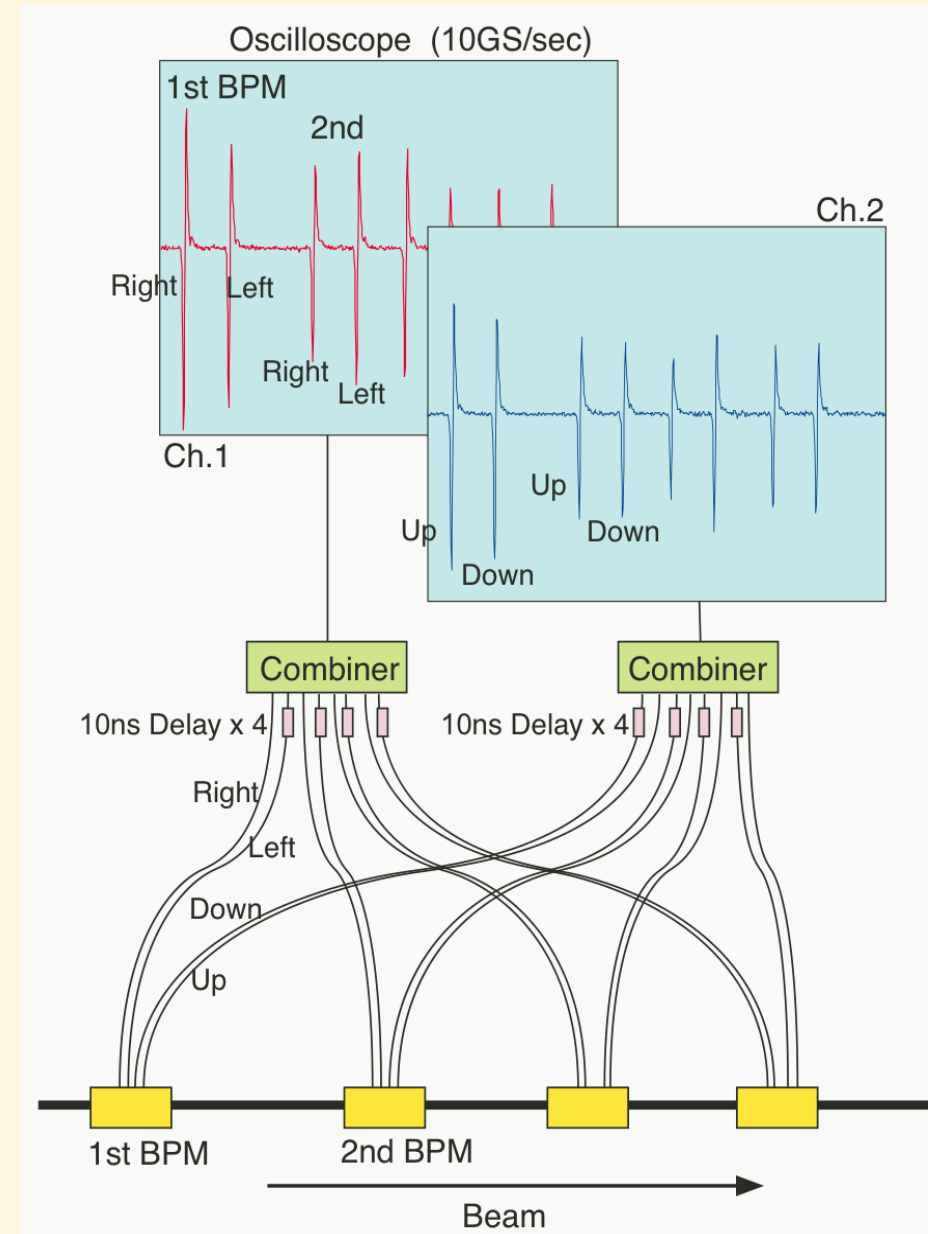
BPM

- ◆ Tektronix DPO7104 can acquire data at $>50\text{Hz}$.
 - ❖ With embedded EPICS
- ◆ Beam modes are recognized by events through CA network.
- ◆ Clients can monitor data of an interested beam mode.
- ◆ 26 oscilloscopes are installed.
- ◆ 100 BPMs are synchronized. (100 BPMs at BT as well soon)



Measurement and Data Acquisition

- ◆ Originally much efforts to develop detectors, shaping amplifiers
 - ❖ No budget for all BPMs
- ◆ Switched to direct waveform acquisition
 - ❖ Minimized active components, then minimized calibration tasks, maintenance
 - ❖ Equal-length cables
 - ❖ One oscilloscope covers about 5 BPMs, or combined 20 (or 40) waveforms
 - ❖ 5 - 10Gs/s (with additional interpolation)
 - ❖ Possible to measure dual bunches
 - ❖ Solved many issues at once!
 - ❖ Extract each signal, apply calibration factors, send to upper layer at 50Hz



Embedded IOC on Oscilloscope

◆ DPO7104, 10Gs/s, 4ch, 8bit

- ❖ Windows-XP

- ❖ Cygwin software development environment

- ❖ Microsoft Visual C++ 2008

 - ✧ <http://www-linac.kek.jp/cont/epics/win32/>

- ❖ EPICS 3.14.8.2

- ❖ Fast data-acquisition at ~150Hz was tricky, but was possible

- ❖ Event triggers the data acquisition

- ❖ Beam positions and charges are calculated based on ~30 coefficients, and tagged with beam modes

- ❖ 50Hz processing is stable at Linac

- ❖ Very efficient for us