

Control System Achievement at KEBB and Upgrade Design for SuperKEKB

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Earthquake in March – Thanks

- ◆ Thank you so much for your warm messages from all over the world.



- ◆ Operation will be normal soon.

KEKB Controls 1998 - 2010

◆ EPICS as Main control Software Toolkit

- ❖ Became one of de-facto standard at 1995
- ❖ Several fieldbuses were incorporated
 - ✧ VME, VXI, CAMAC, ArcNet, GPIB, etc
- ❖ Reduced software design efforts much

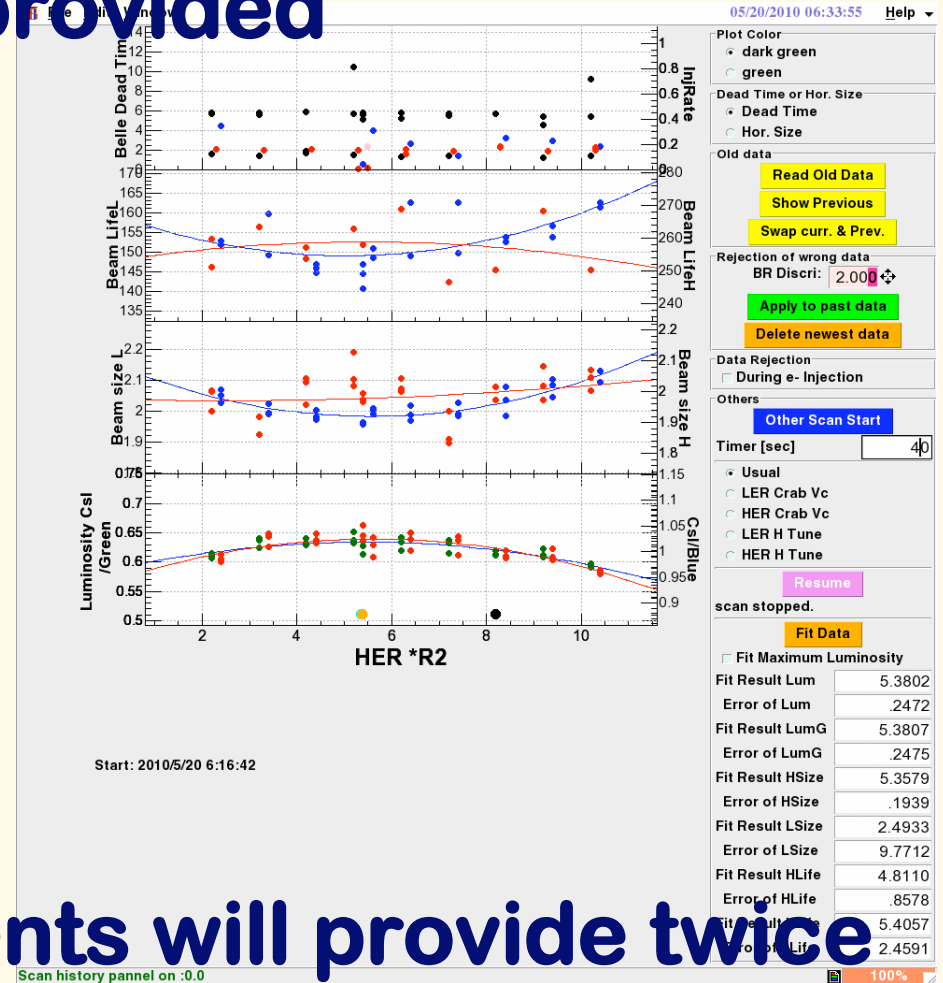
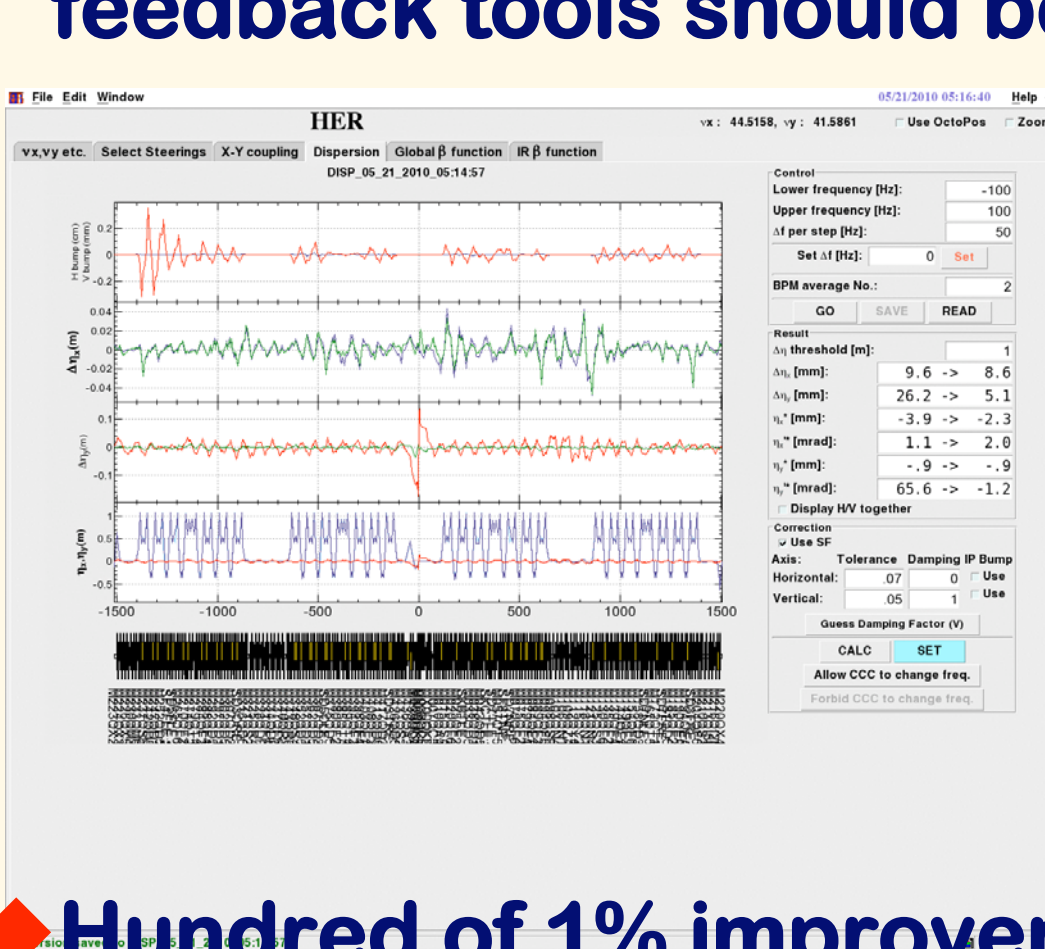
◆ Scripting Languages for Operational Software

- ❖ SADscript/Tk, Python/Tk, Tcl/Tk used much
 - ✧ Especially, SADscript as a bridge btw. Accelerator simulation, Numeric manipulation, Graphic interface and EPICS controls
- ❖ Bright new idea in the morning meeting could make the operation much advanced in the evening
 - ✧ Great tool to optimize the operation



SADscripts/Tk

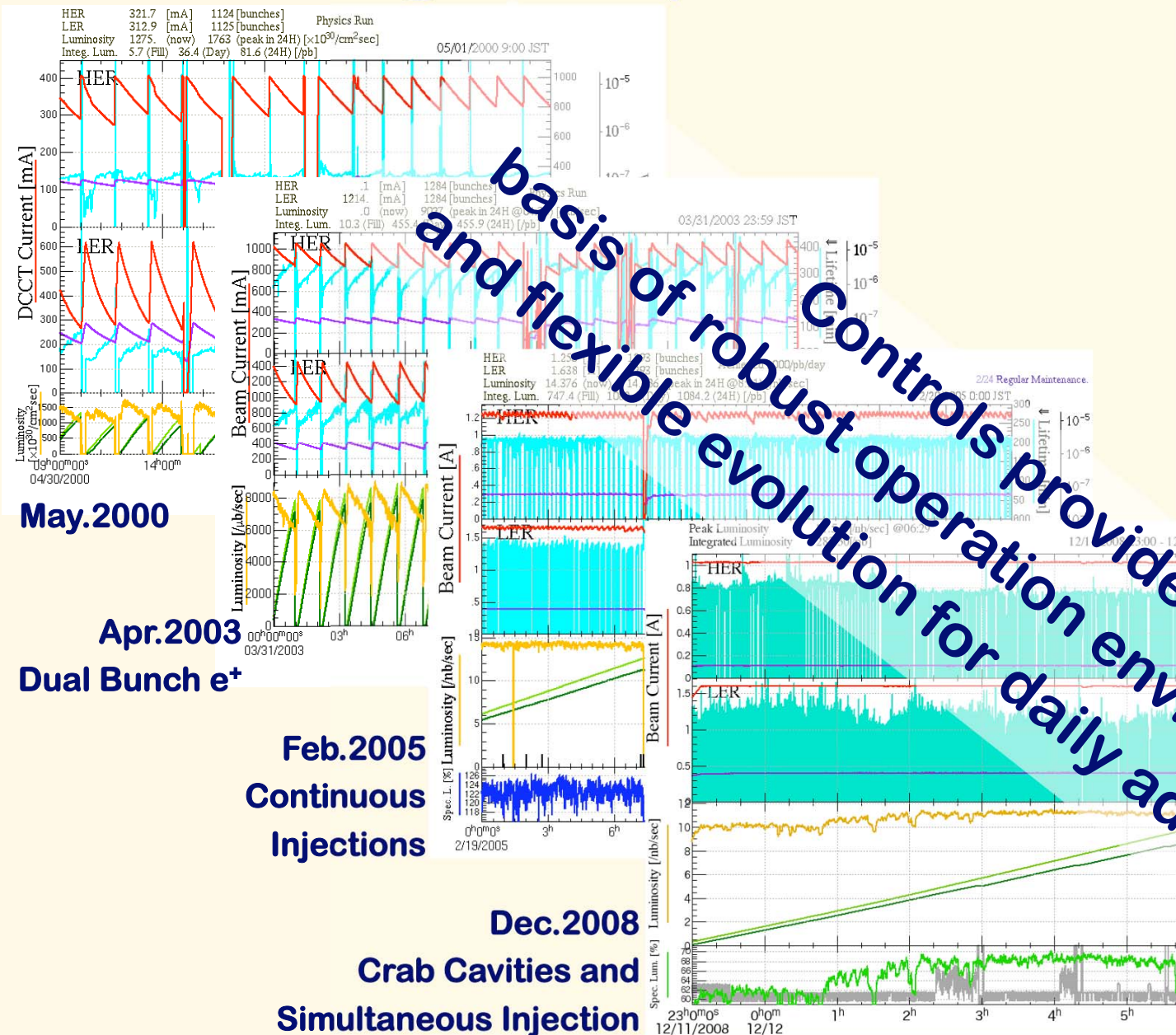
◆ Many machine diagnostic and correction/feedback tools should be provided



◆ Hundred of 1% improvements will provide twice better performance, rapidness is important



Change in Operation Modes at KEKB



May.2000

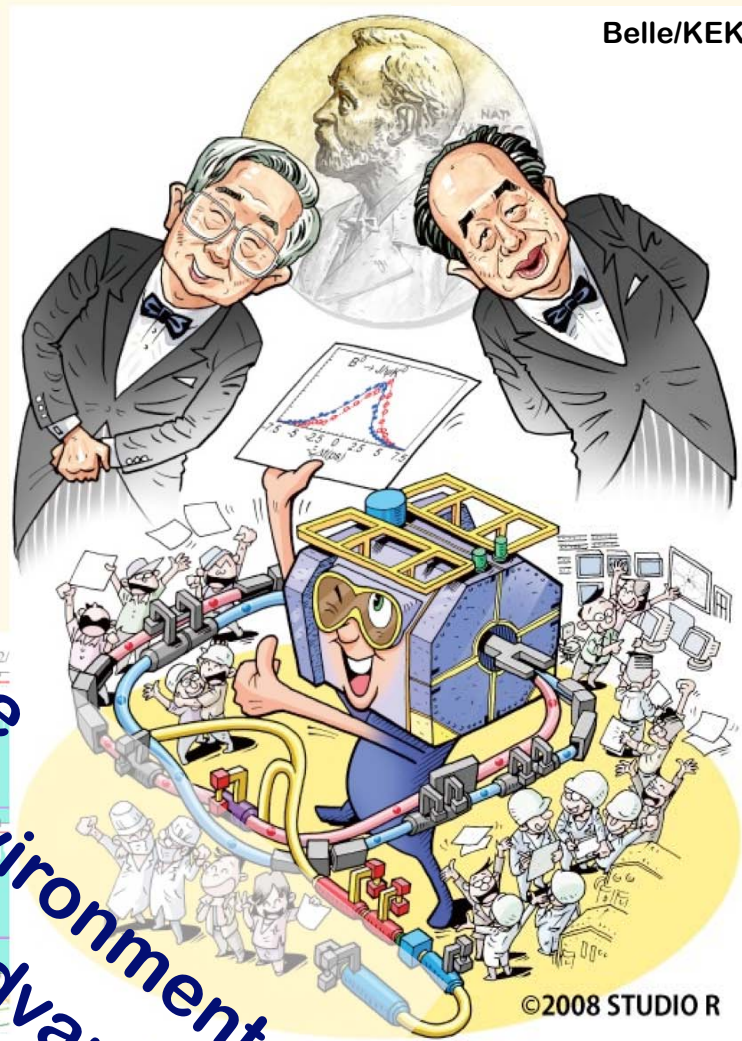
Apr.2003

Dual Bunch e^+

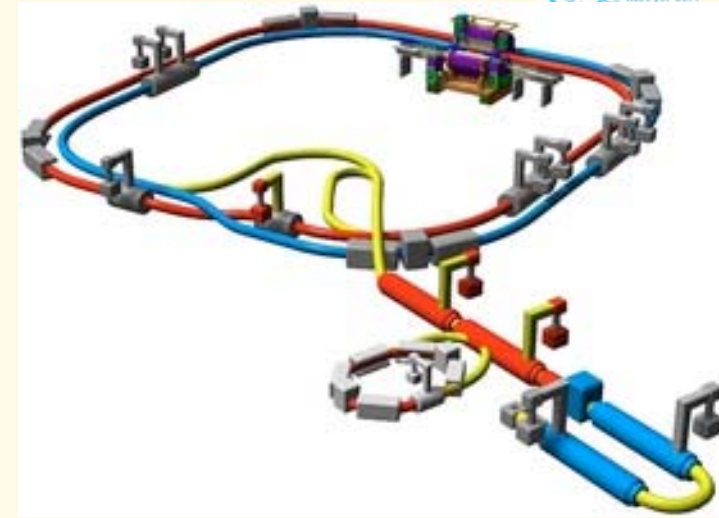
Feb.2005
Continuous
Injections

Dec.2008
Crab Cavities and
Simultaneous Injection

basis of robust operation provide
and flexible evolution for daily advances



SuperKEKB



◆ Electron-positron asymmetric collider

- ❖ Based on a decade of successful operation at KEKB
- ◆ Aims at 40-times higher luminosity
 - ❖ $8 \times 10^{35} \text{cm}^{-2}\text{s}^{-1}$ for further flavor physics studies
 - ❖ 7GeV / 2.6A electron, 4GeV / 3.6A positron
 - ❖ $\beta_y^* \sim 0.3\text{mm}$, $\varepsilon_x/\varepsilon_y \sim 4\text{nm}/9\text{pm}$, $\sigma_y \sim 50\text{nm}$, $\sigma_z \sim 6\text{mm}$
 - ❖ Ante chamber, longer bend, damping ring, rf gun, etc

SuperKEKB Controls

◆ Inherit Good part of KEKB Controls

- ❖ EPICS

- ❖ Scripting languages

- ❖ With simple rejuvenation of software/hardware

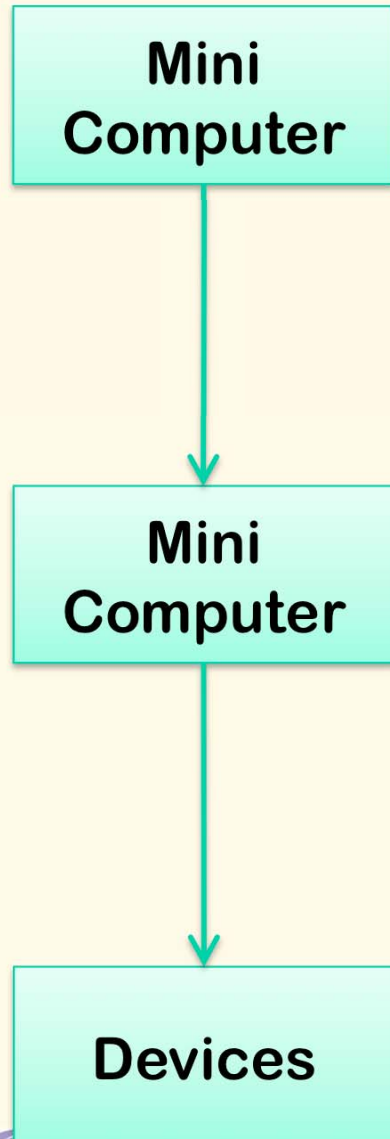
◆ Two Additional Concepts

1st: CA Everywhere

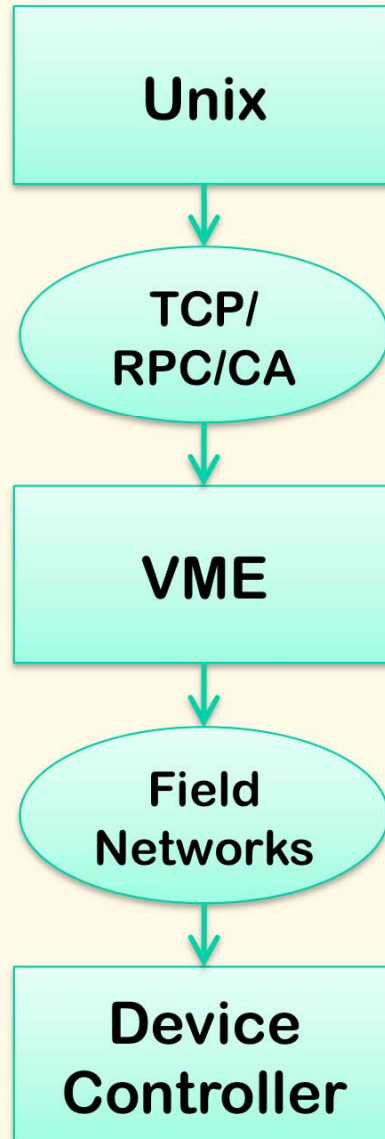
- ◆ **EPICS Channel Access (CA) Everywhere**
 - ❖ **Embed EPICS control software (IOC) everywhere possible**
 - ❖ **Reduce efforts on protocol design, testing, etc**

Transition of Architecture

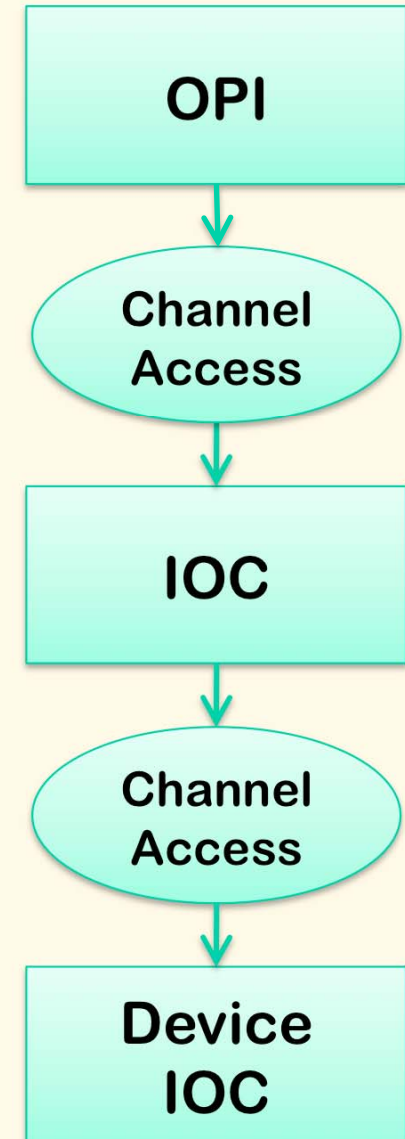
1990~



1993~



2005~



Overview of controls at KEK

◆ VME + Unix (1990~)

- ❖ Standard model (later EPICS) configuration
 - ✧ With several fieldbuses



◆ Every controller on IP network (1993~)

- ❖ 2-layer physical, 3-layer in logical (Linac, J-PARC)



◆ Every controller with EPICS IOC (2005~)

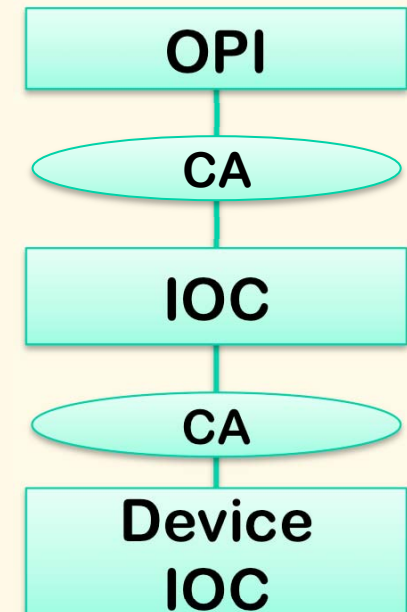
- ❖ Channel Access everywhere (CA Everywhere)
 - ✧ Good for rapid development and smooth maintenance
 - ✧ May need some consideration on network management

Embedded EPICS IOCs at (Super)KEKB

◆ Not only information server, but also the same software framework on every controller

✧ Rapid development and smooth maintenance

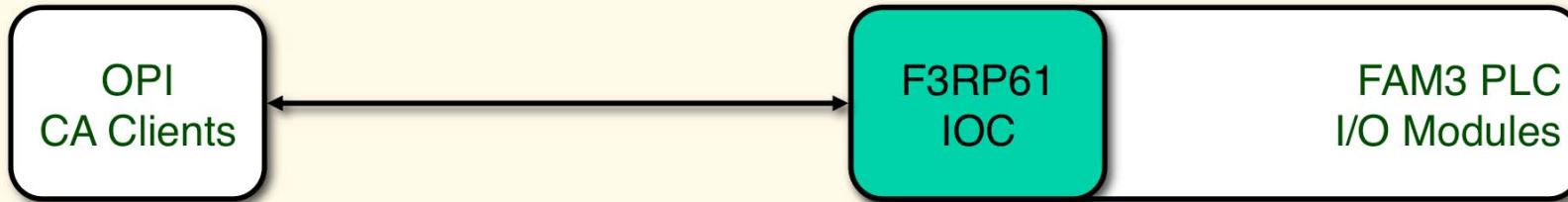
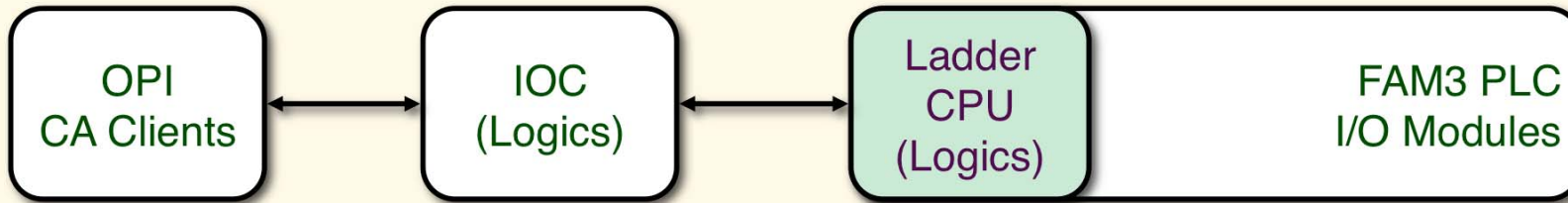
- ✧ μ TCA LLRF module: Linux/FPGA (Odagiri...) THDAULT05
- ✧ Yokogawa PLC: Linux CPU (Odagiri...)
- ✧ Oscillo. 50Hz measurement: Windows (Satoh...)
- ✧ MPS management :Linux/FPGA (Akiyama...)
- ✧ Timing TDC: Linux/Arm (Kusano...)
- ✧ Power modulator: Linux/FPGA (Kusano...)
- ✧ Libera BPM at 50Hz: Linux/FPGA (Satoh...)
- ✧ NI cRIO : CAS/FPGA (Odagiri...)
- ✧ Many more...



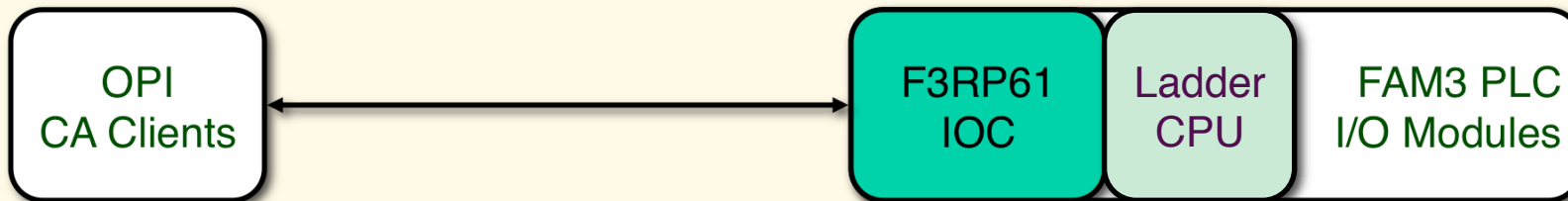
Simpler PLC Usage under EPICS

Conventional PLC usage

with asynchronous access



If necessary, we can combine



Logics are confined in PLC, and management is easier

2nd: Dual-layer Controls

- ◆ **Another layer in addition to EPICS/CA**
 - ❖ **Event system helps EPICS with another channel**
 - ❖ **Additional functionality, synchronization and speed**

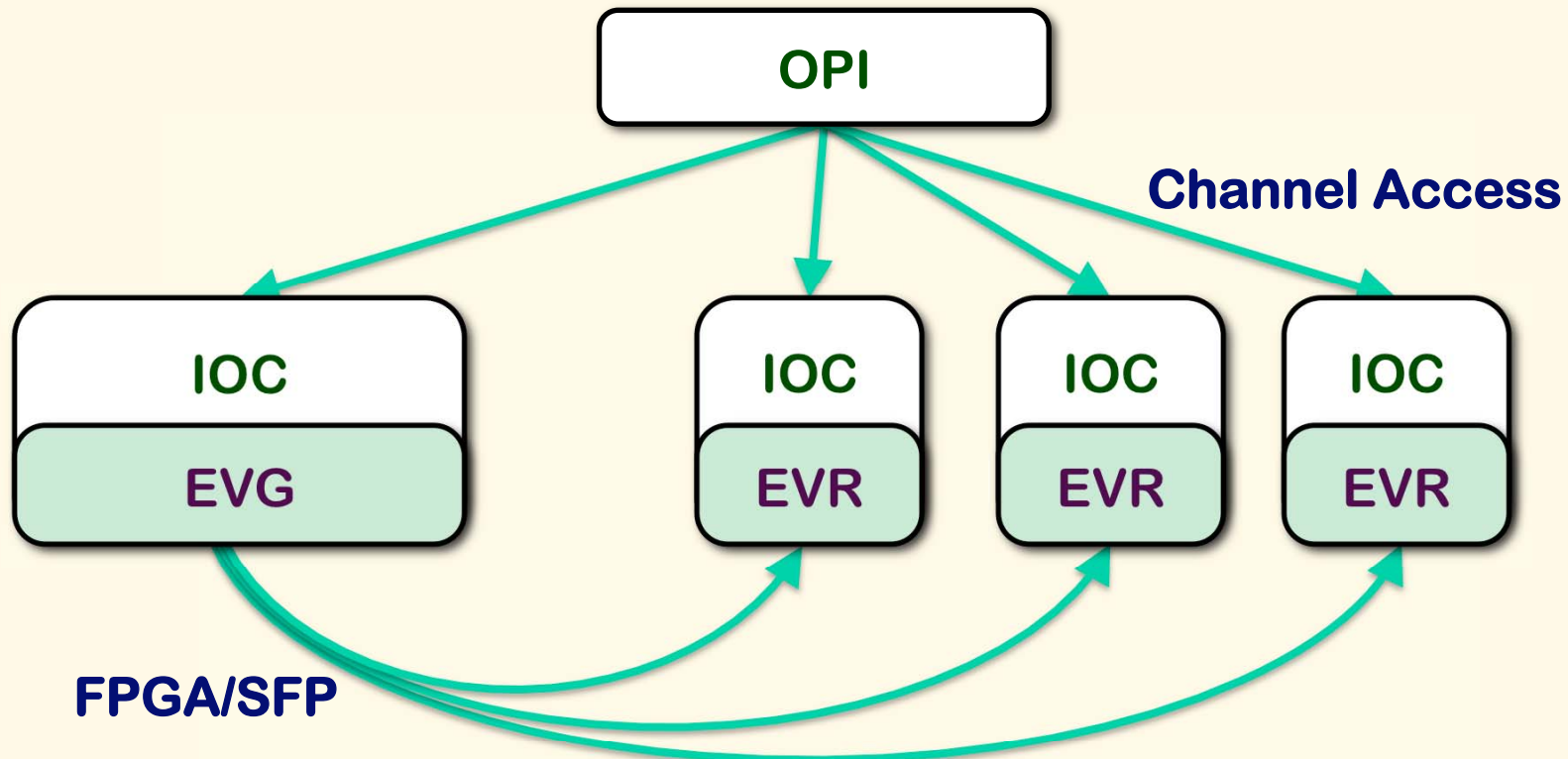
Dual-layer Controls

◆ IOC controls via Conventional EPICS CA

✧ Above 1ms, ordered controls

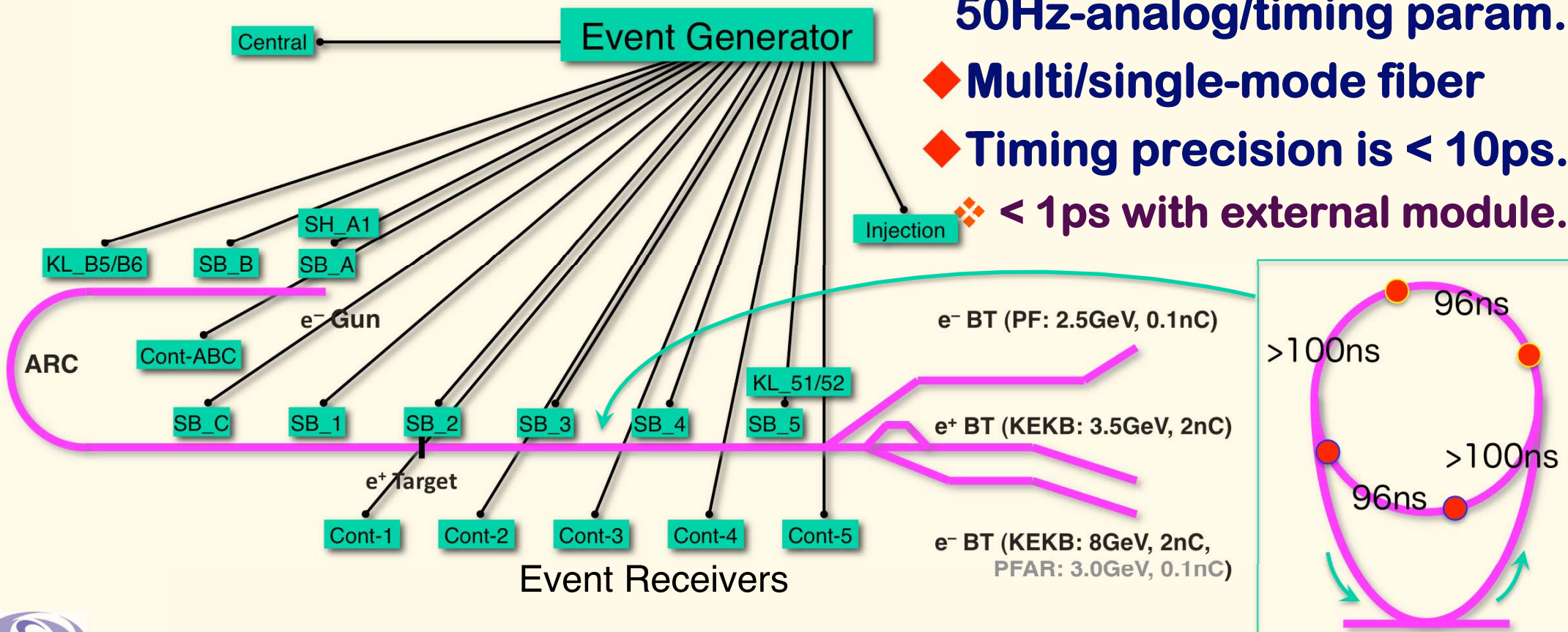
◆ Fast FPGA controls via SFP/Fiber

✧ 10ps ~ 100ms, 114MHz synchronous controls



Fast Global Synchronous Controls

- ◆ MRF's series-230 Event Generator / Receivers
- ◆ VME64x and VxWorks v5.5.1
- ◆ EPICS R3.14.9 with DevSup v2.4.1
- ◆ 17 event receivers up to now
- ◆ 114.24MHz event rate, 50Hz fiducials
- ◆ More than **hundred** 50Hz-analog/timing param.
- ◆ Multi/single-mode fiber
- ◆ Timing precision is $< 10\text{ps}$.
- ◆ $< 1\text{ps}$ with external module.



Event Manipulation

Human Operator

Injection Programs

Flexible with script
and reliable/fast
with FPGA.

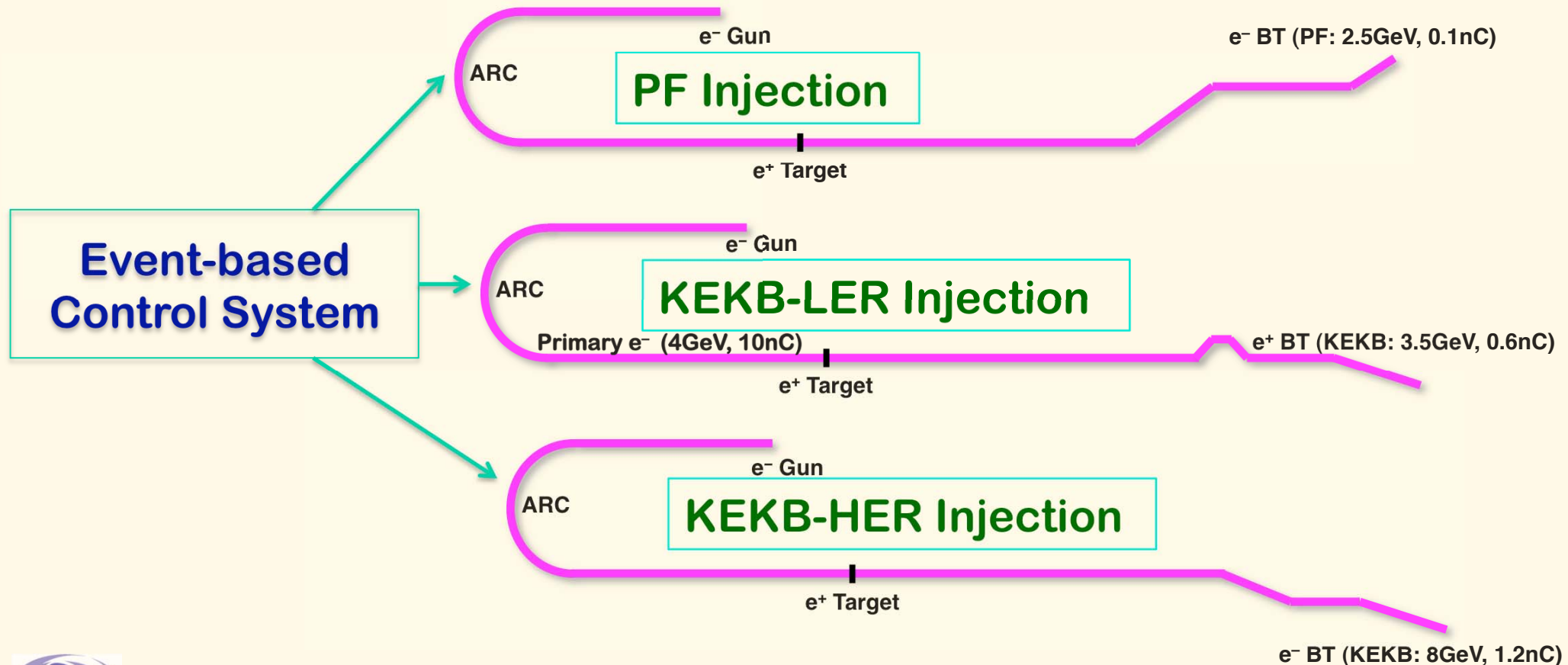
Arbitrate and Generate Beam Mode Pattern (in PythonTk)
considering priorities of the ring accelerators
equalizing pulsed power supply interval
in arrays of length 2 (40ms) to 500 (10s)
each element corresponds to a 20-ms time slot and a beam mode

Generate Events for the Next 20-ms Time Slot (in Event Generator)
reading two consecutive elements from the beam mode pattern
generate several events for the next pulse
generate preparation events for the next after next

Generate Signals based on Received Events (in Event Receiver)
generate pulsed signals as prepared in the previous time slot
program the signals (analog value, delays, etc) for the next
start to generate analog signals for the next

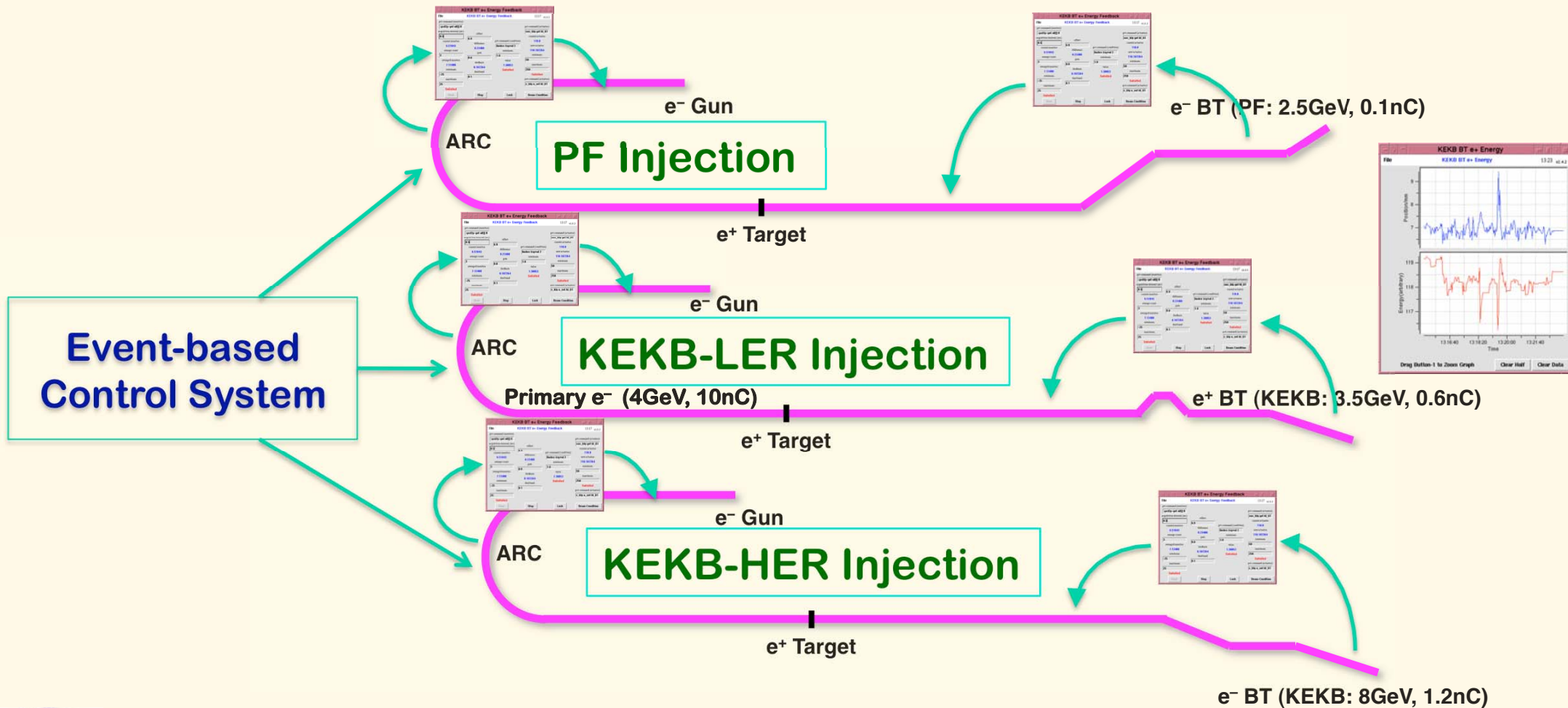
One Machine, Multiple Virtual Accelerators (VAs)

- ◆ **Control/Monitor are carried dependent on a VA**
 - ❖ **Mostly independent between VAs**
- ◆ **Independent parameter set for each VA, one of the VAs is controlled at a time**
 - ❖ **VAs for Injections (HER (e^-), LER (e^+), PF, PF-AR) and Linac-only in SuperKEKB project**



Multiple Closed Loop Controls Overlapped

- ◆ Closed loops can be installed on each VA independently
- ❖ Tested at KEKB



Towards SuperKEKB

- ◆ **Upgrade of controllers for each type of device**
 - ❖ **Discussions with device groups, for aging controllers**
- ◆ **Base software components, OS, EPICS, CSS, (Scripting) Languages**
 - ❖ **Especially EPICS Collaboration-based software**
- ◆ **Operational software**
 - ❖ **Archiver, Archive viewer, Alarm, e-Log, etc**
- ◆ **Information sharing to offices**
 - ❖ **More Web based application software**
- ◆ **Seminar and training**
- ◆ **IP Networking, Wireless LAN, Console Desk, etc**



Accelerator Controls

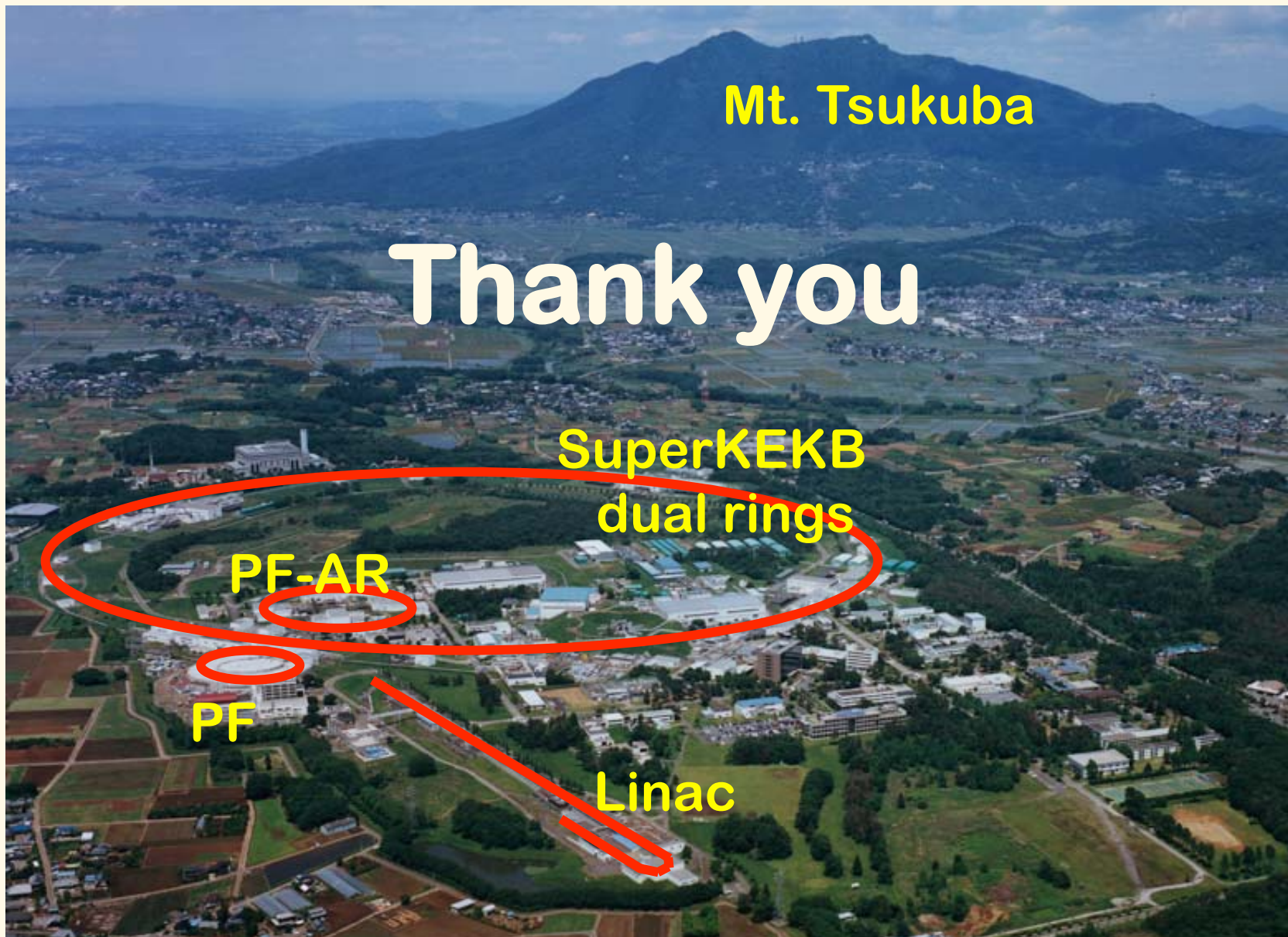
- ◆ It's a fan to interact with all the components of the accelerator through control hardware and software
- ◆ It's a fan to interact with all the staff members of the project in order to design and improve controls
- ◆ We can contribute to the machine performance and the results even without realizing it



Conclusion

- ◆ **Control efforts have contacts with all activities in the particle accelerator. We are at the privileged position to enjoy it.**
- ◆ **Based on existent KEKB controls, “CA Everywhere” and “Dual-layer Controls” should be enforced.**
- ◆ **With some Phronesis (Greek: practical wisdom, ability to understand the universal truth), we believe we can achieve the target.**





Mt. Tsukuba

Thank you

SuperKEKB
dual rings

PF-AR

PF

Linac

Thank you